

# Causal Graph Rewriting

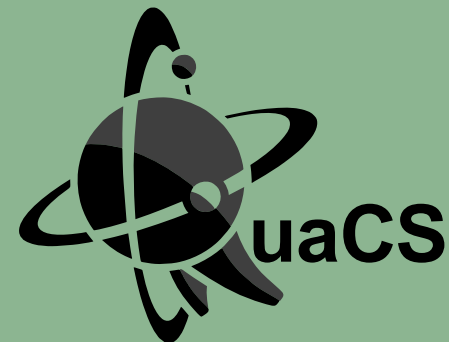
Pablo Arrighi, Marin Costes, Luidnel Maignan, Gilles Dowek

école \_\_\_\_\_  
normale \_\_\_\_\_  
supérieure \_\_\_\_\_  
paris-saclay \_\_\_\_\_

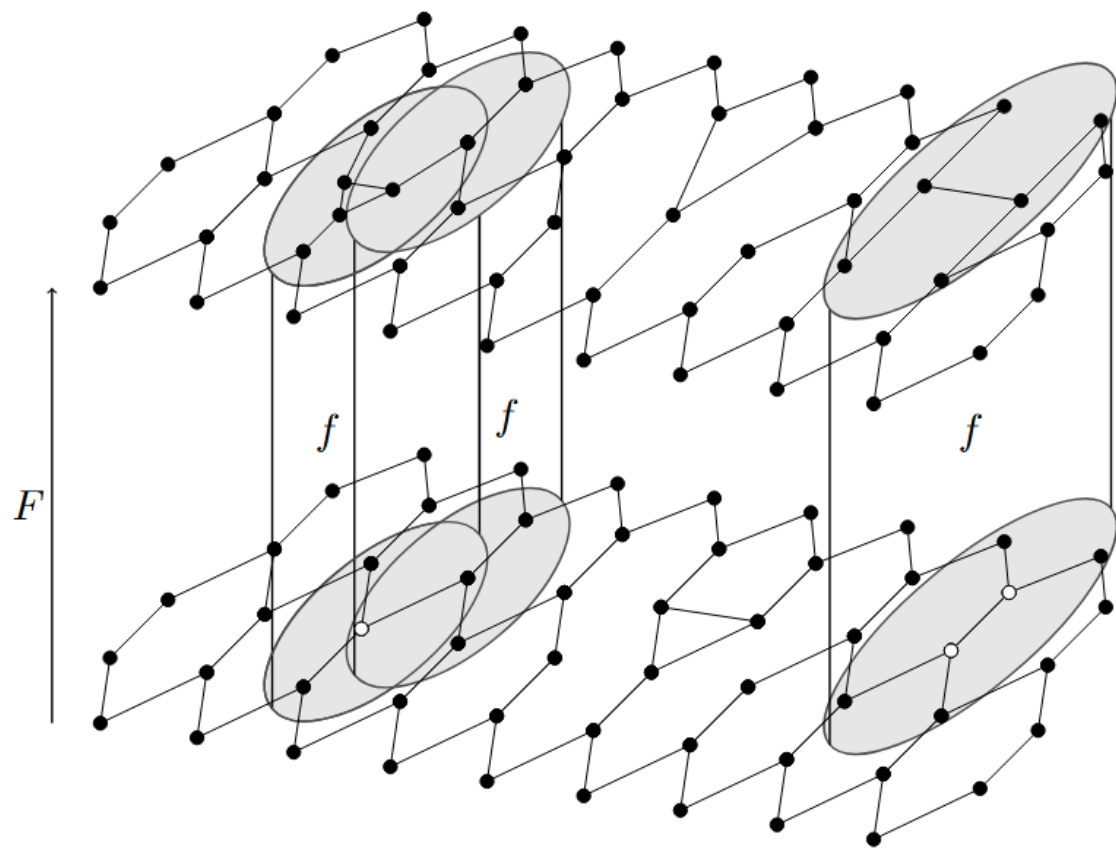
université  
PARIS-SACLAY



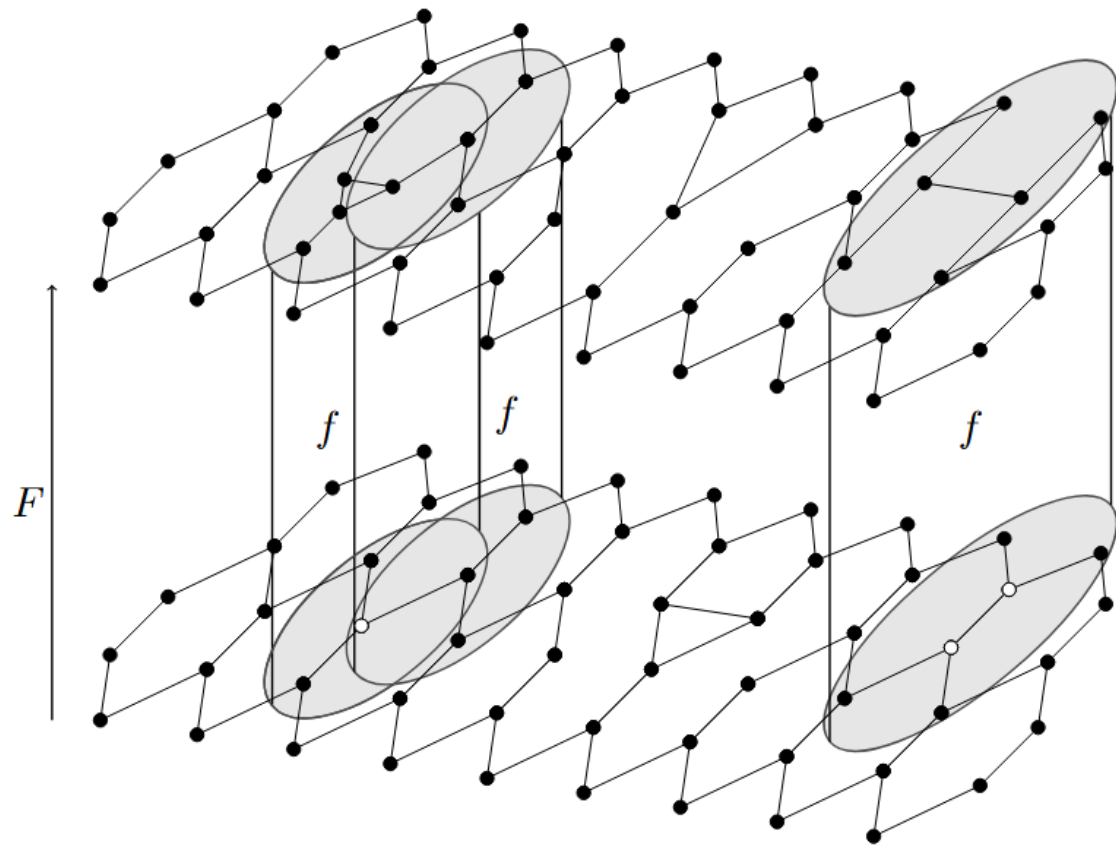
Laboratoire  
Méthodes  
Formelles



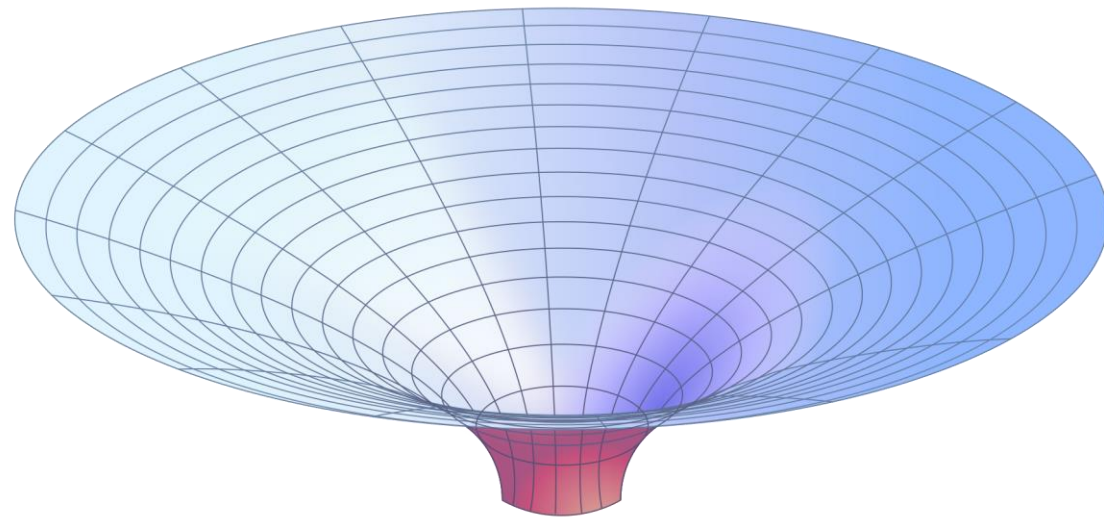
# Introduction



# Introduction



**$\neq$**

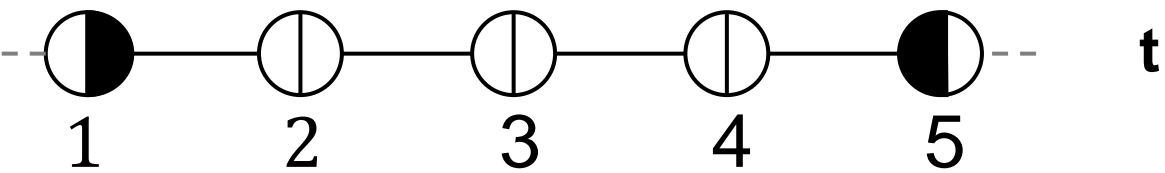


# Dynamical systems and rewriting

**Dynamical system  
(Synchronous)**

# Dynamical systems and rewriting

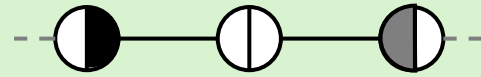
## Dynamical system (Synchronous)



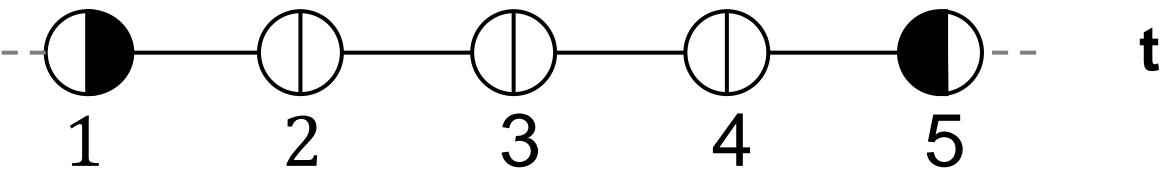
# Dynamical systems and rewriting

**Dynamical system  
(Synchronous)**

**Local rule**



$x$



# Dynamical systems and rewriting

**Dynamical system  
(Synchronous)**

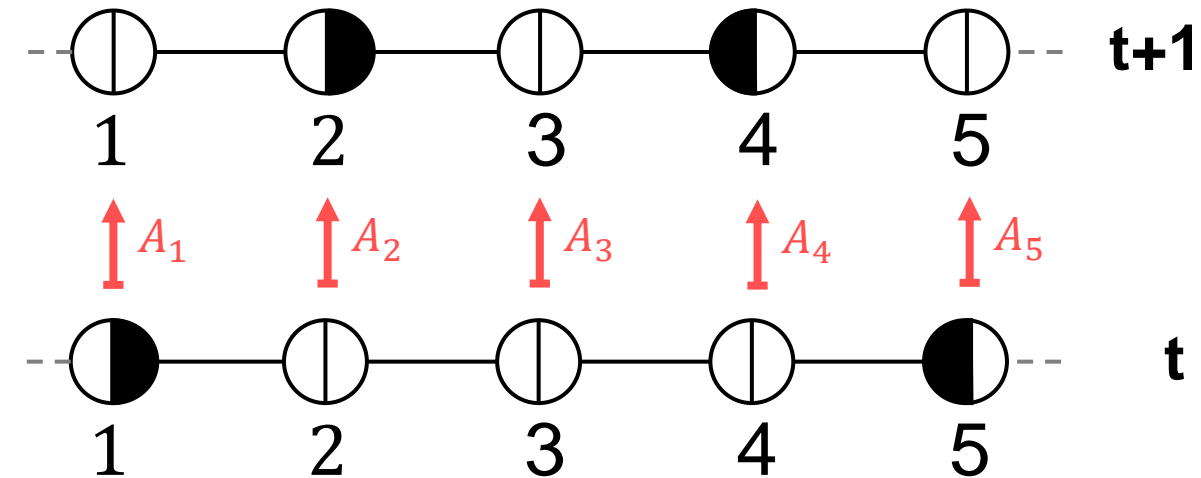
**Local rule**



$\uparrow A_x$



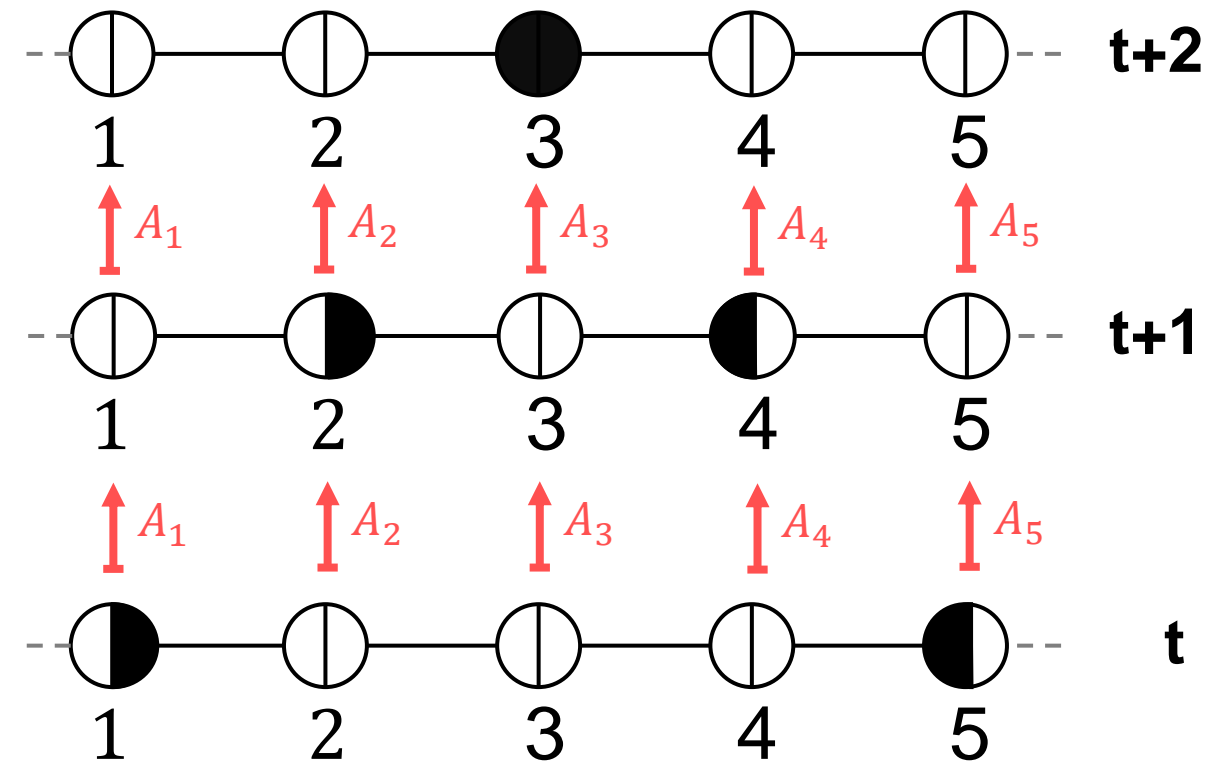
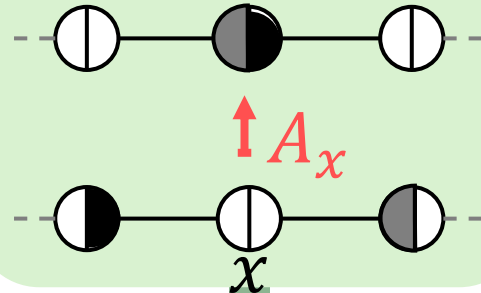
$x$



# Dynamical systems and rewriting

**Dynamical system  
(Synchronous)**

**Local rule**

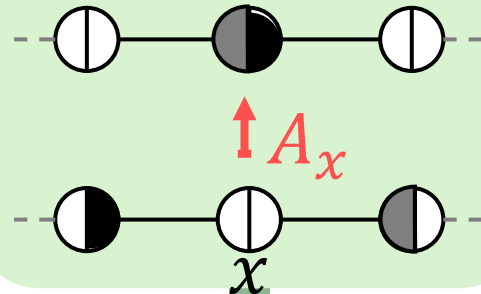




# Dynamical systems and rewriting

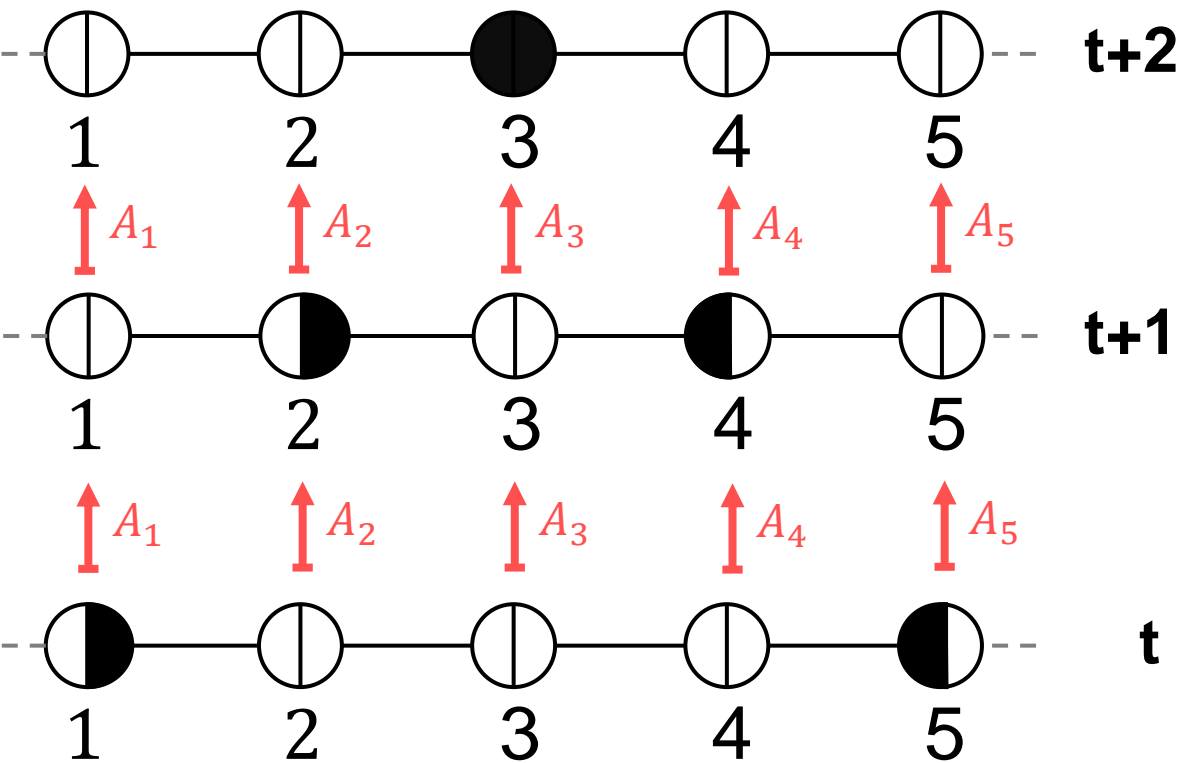
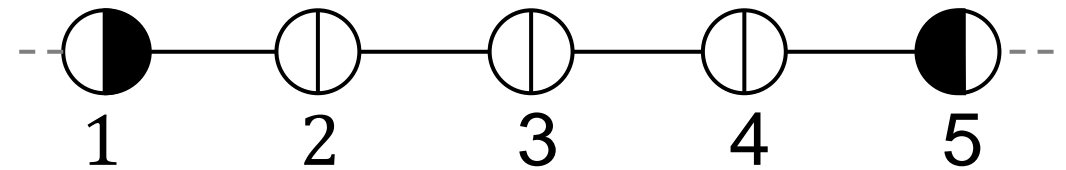
**Dynamical system  
(Synchronous)**

**Local rule**



**Naive asynchronous  
counterpart**

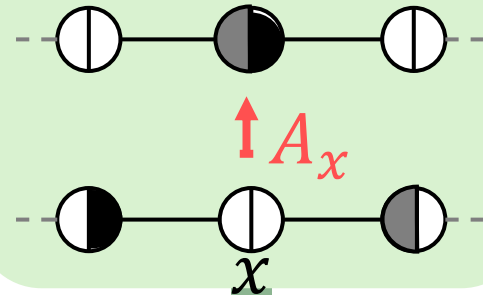
$G$



# Dynamical systems and rewriting

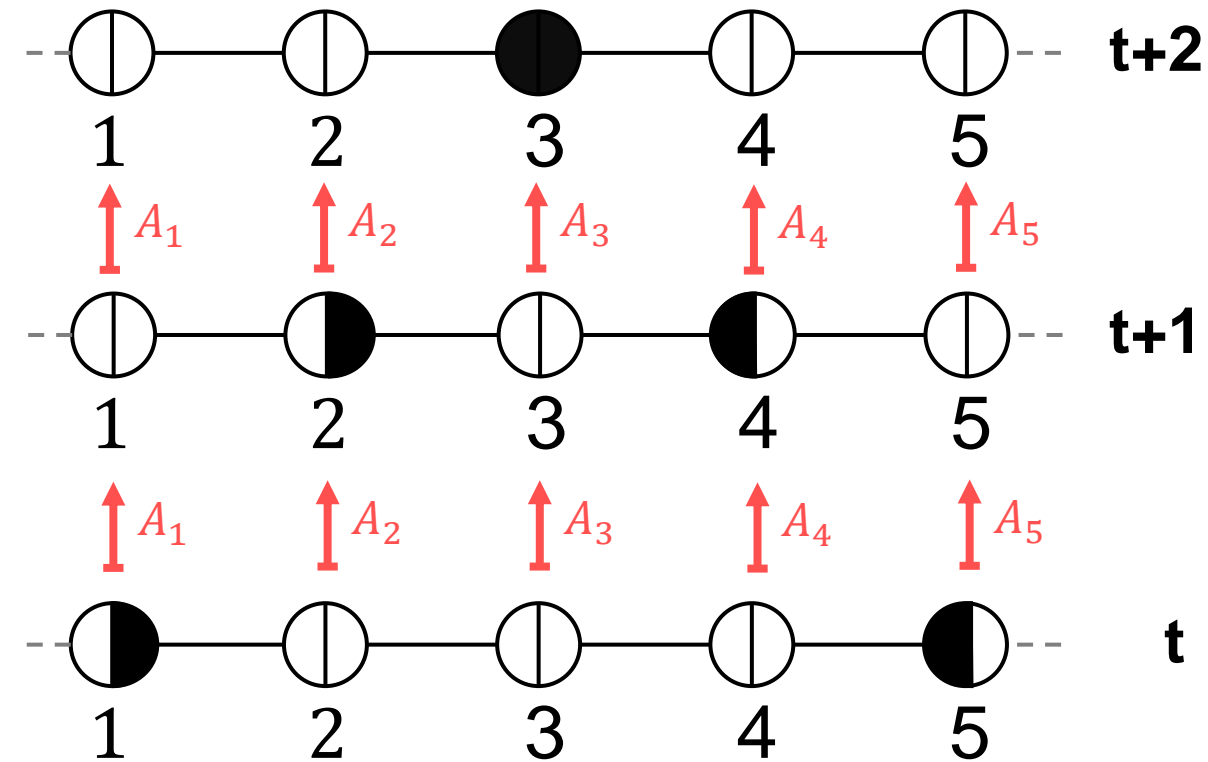
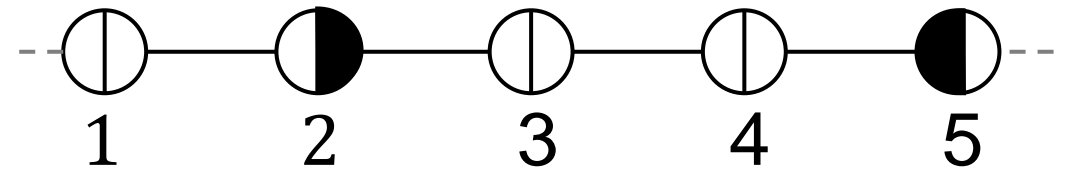
**Dynamical system  
(Synchronous)**

**Local rule**



**Naive asynchronous  
counterpart**

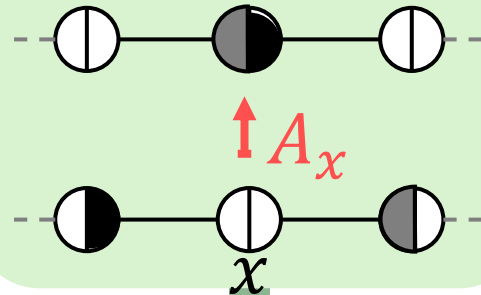
$A_2 G$



# Dynamical systems and rewriting

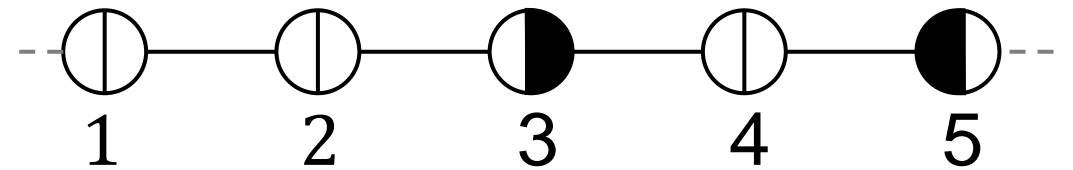
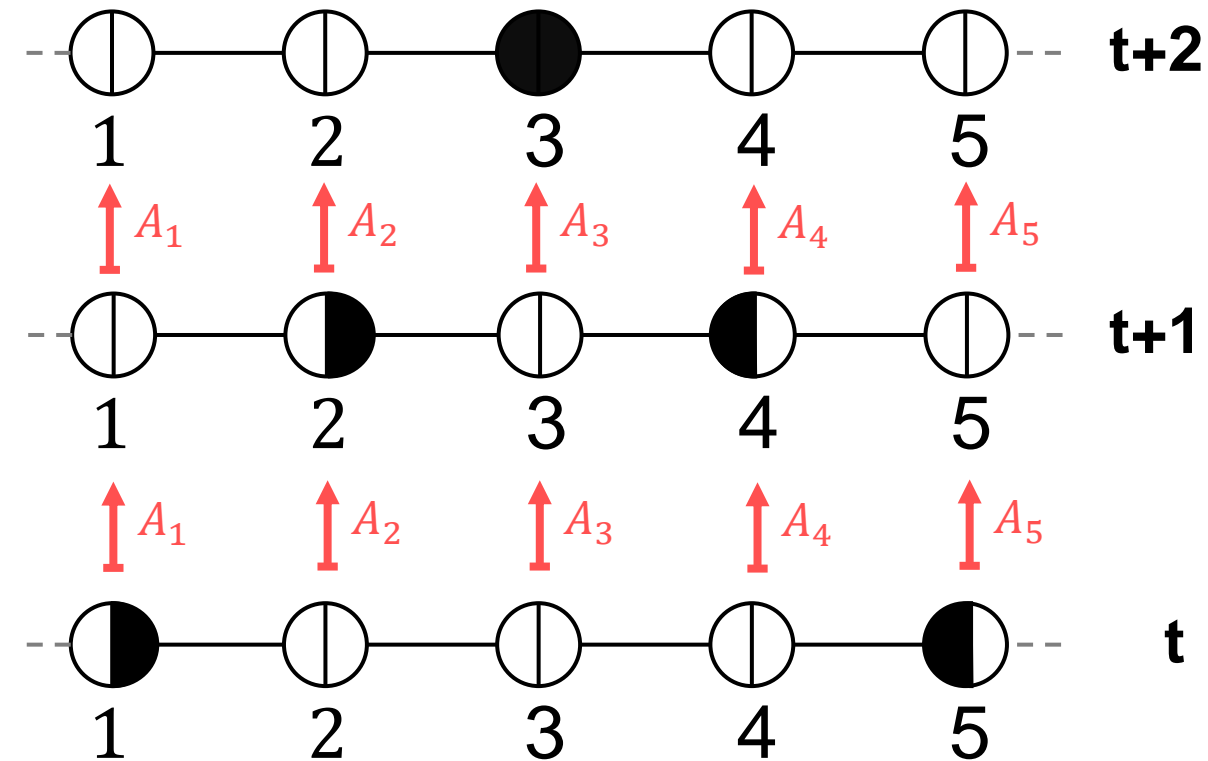
**Dynamical system  
(Synchronous)**

**Local rule**



**Naive asynchronous  
counterpart**

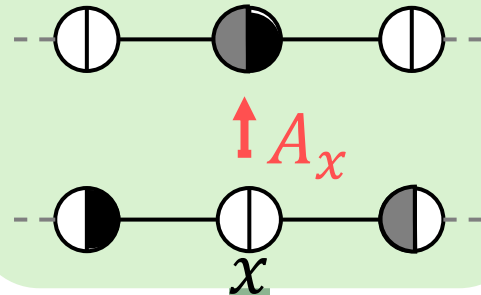
$A_3 A_2 G$



# Dynamical systems and rewriting

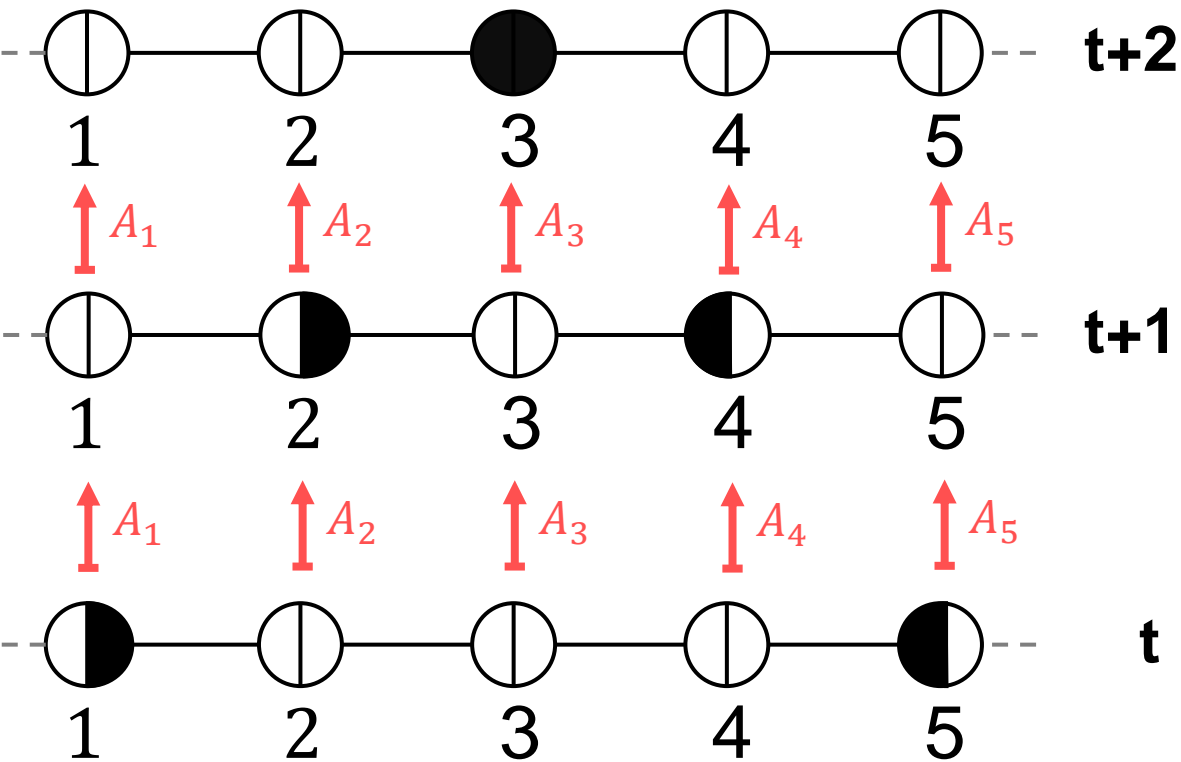
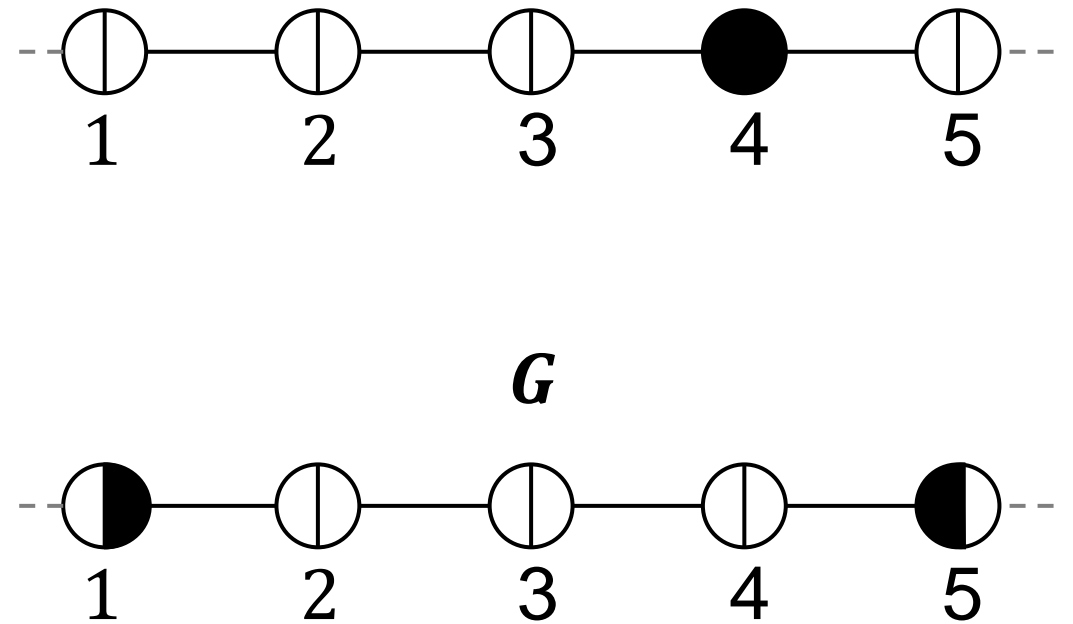
**Dynamical system  
(Synchronous)**

**Local rule**



**Naive asynchronous  
counterpart**

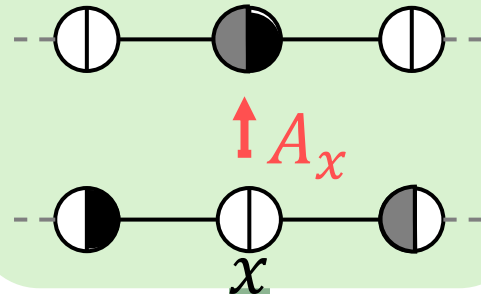
$A_4 A_3 A_2 G$



# Dynamical systems and rewriting

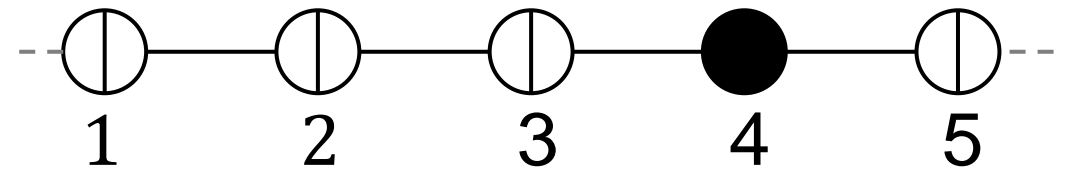
**Dynamical system  
(Synchronous)**

**Local rule**

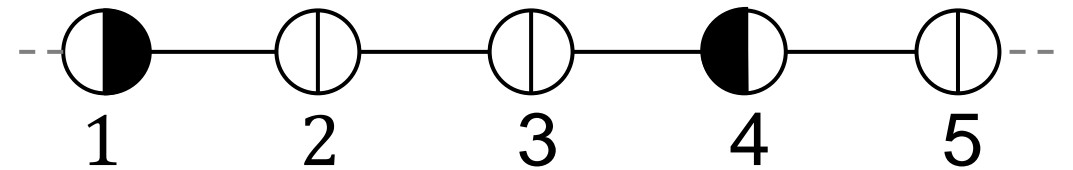


**Naive asynchronous  
counterpart**

$A_4 A_3 A_2 G$



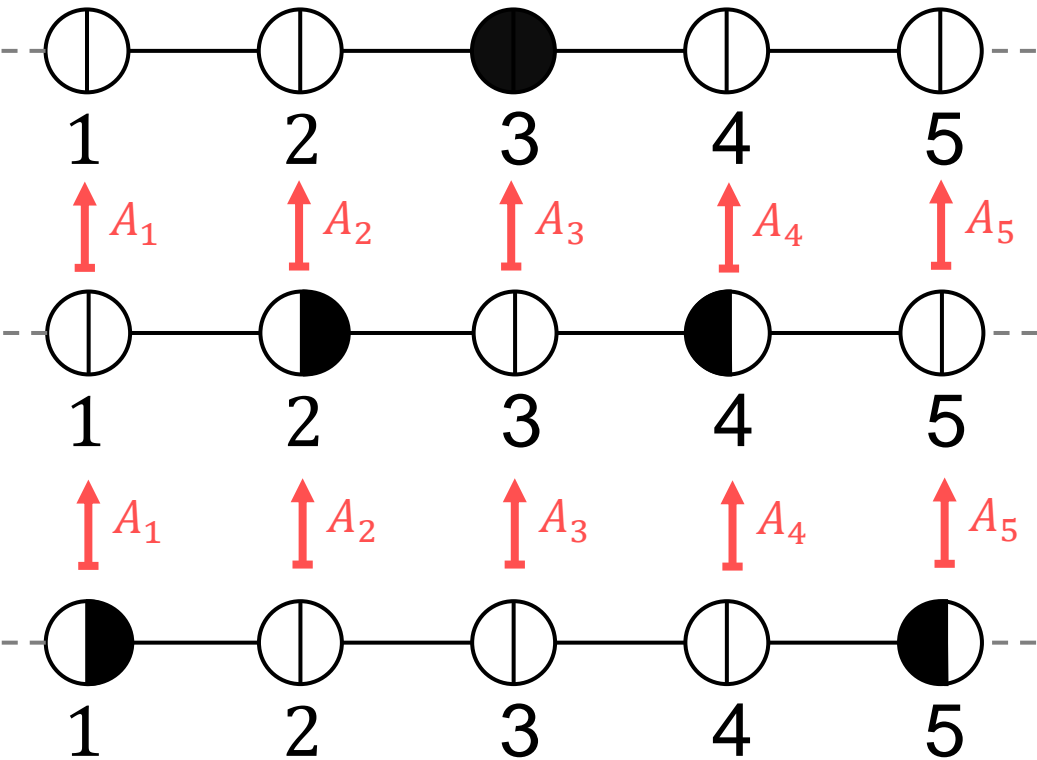
$A_4 G$



**t+2**

**t+1**

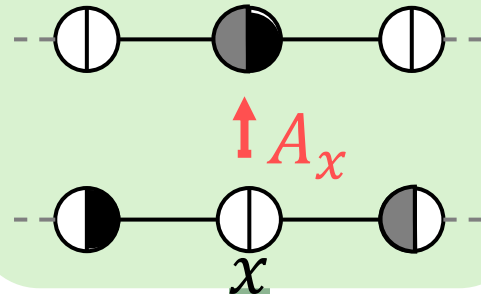
**t**



# Dynamical systems and rewriting

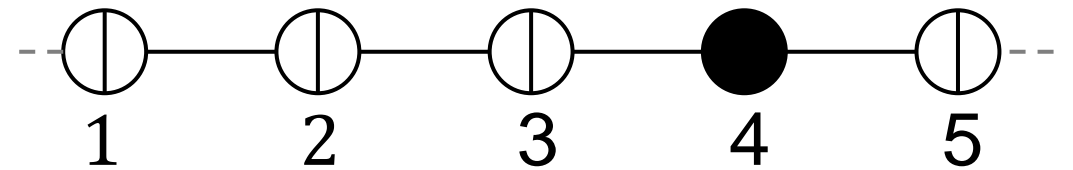
**Dynamical system  
(Synchronous)**

**Local rule**

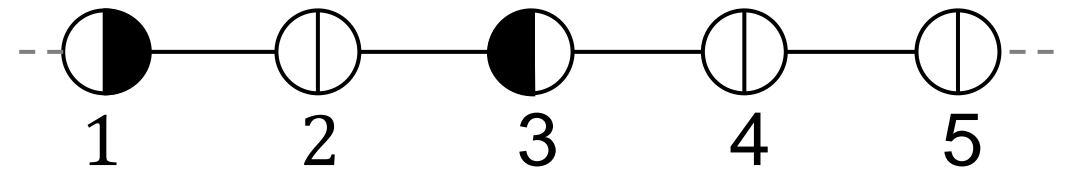


**Naive asynchronous  
counterpart**

$A_4 A_3 A_2 G$



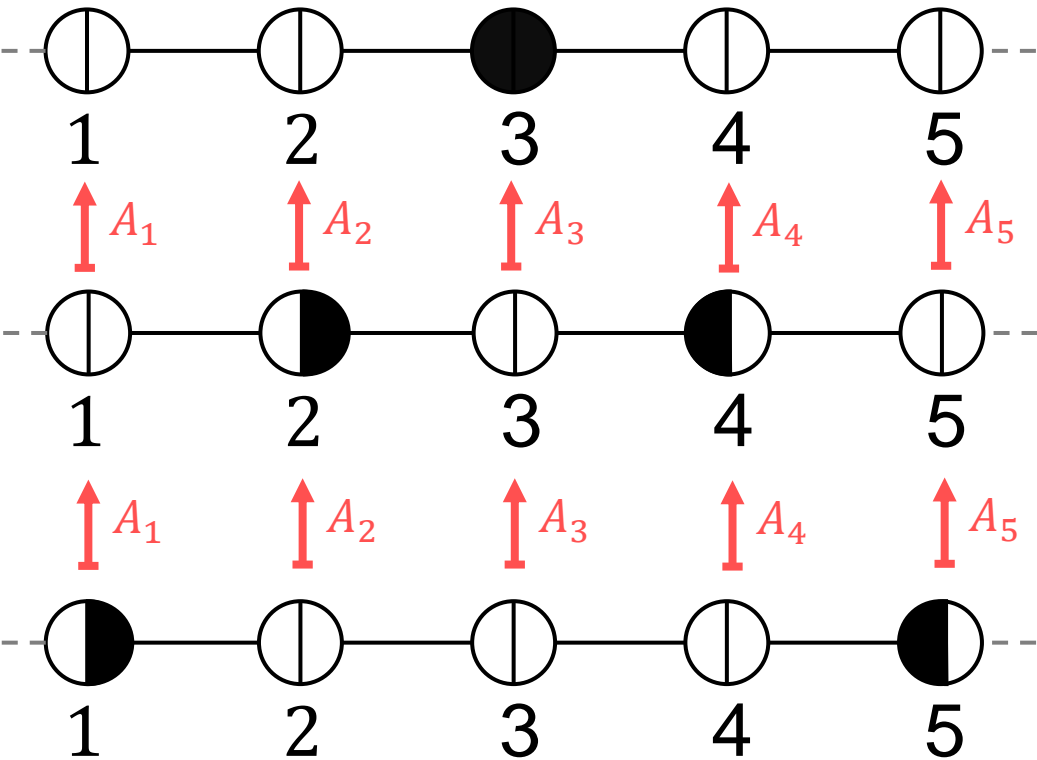
$A_3 A_4 G$



**t+2**

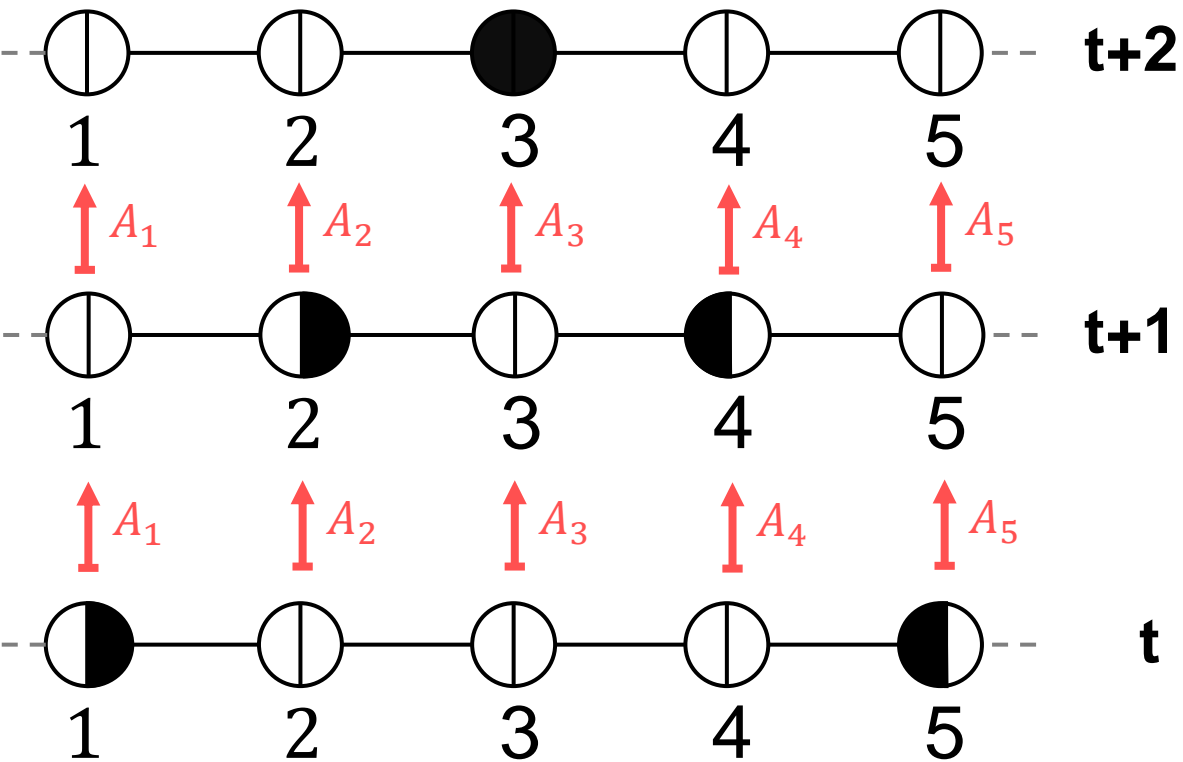
**t+1**

**t**

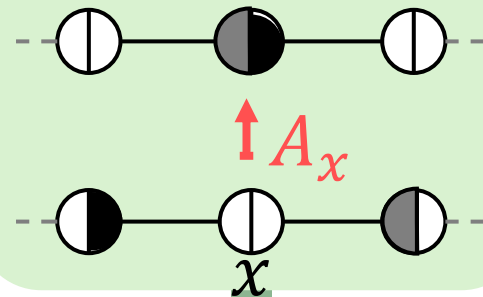


# Dynamical systems and rewriting

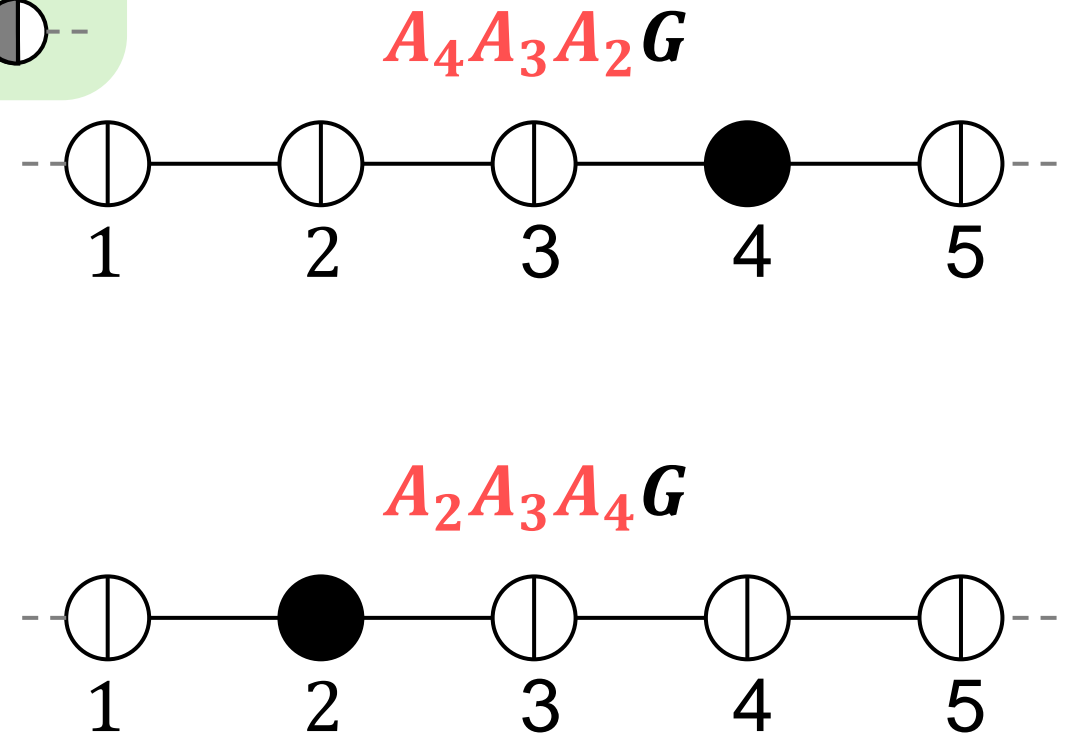
**Dynamical system  
(Synchronous)**



**Local rule**

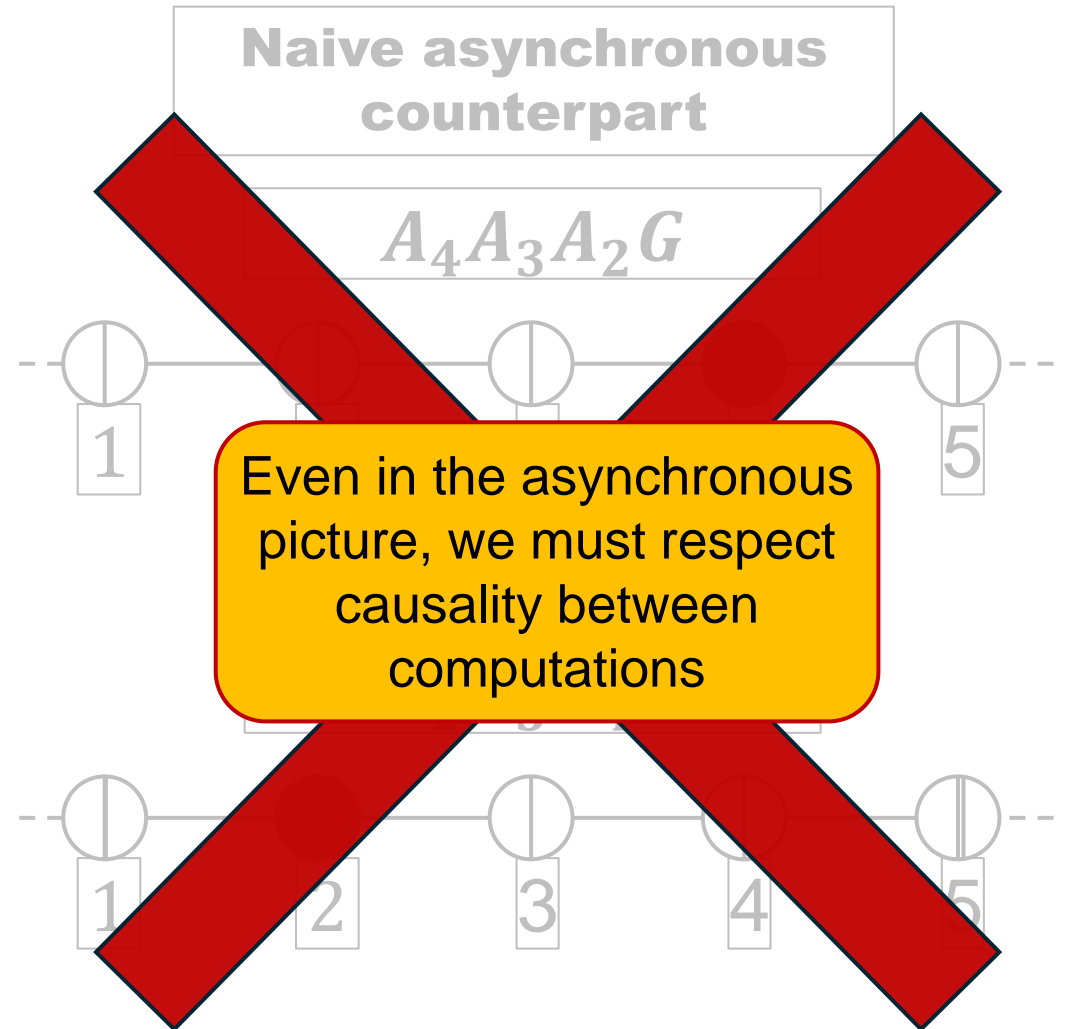
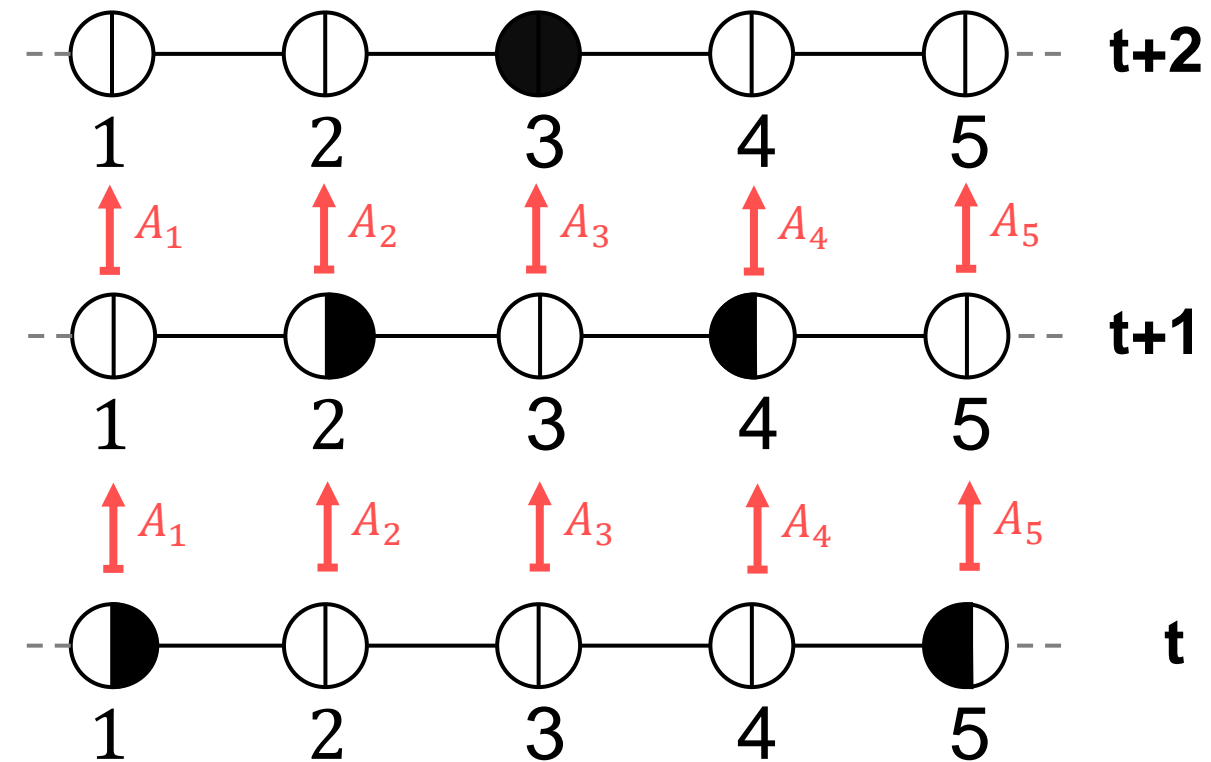


**Naive asynchronous  
counterpart**



# Dynamical systems and rewriting

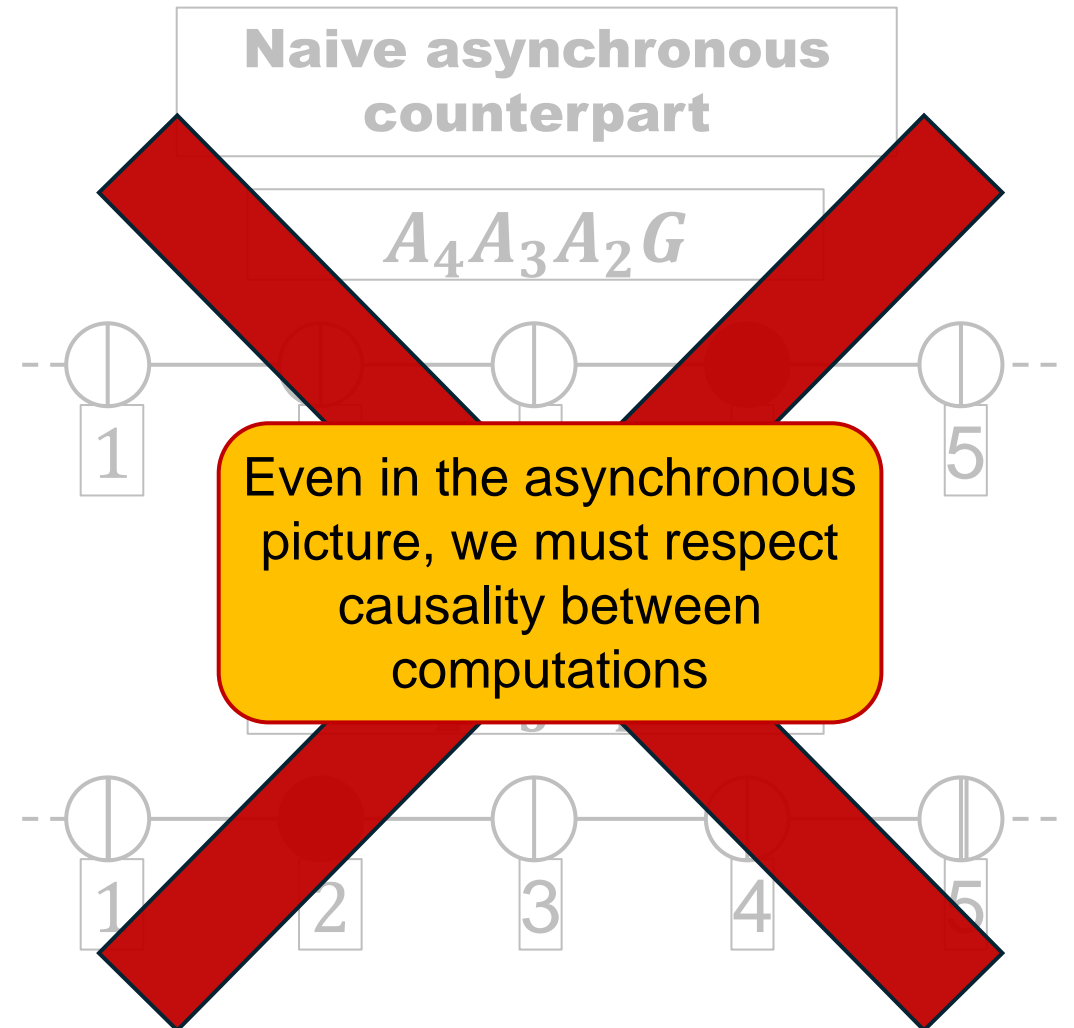
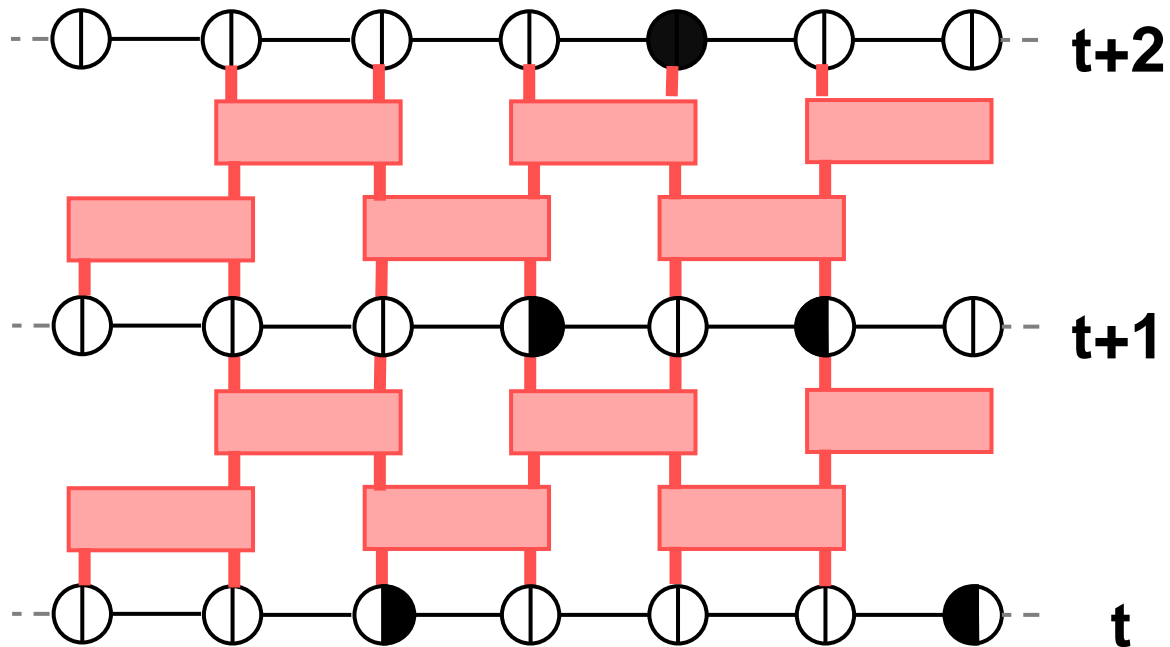
## Dynamical system (Synchronous)





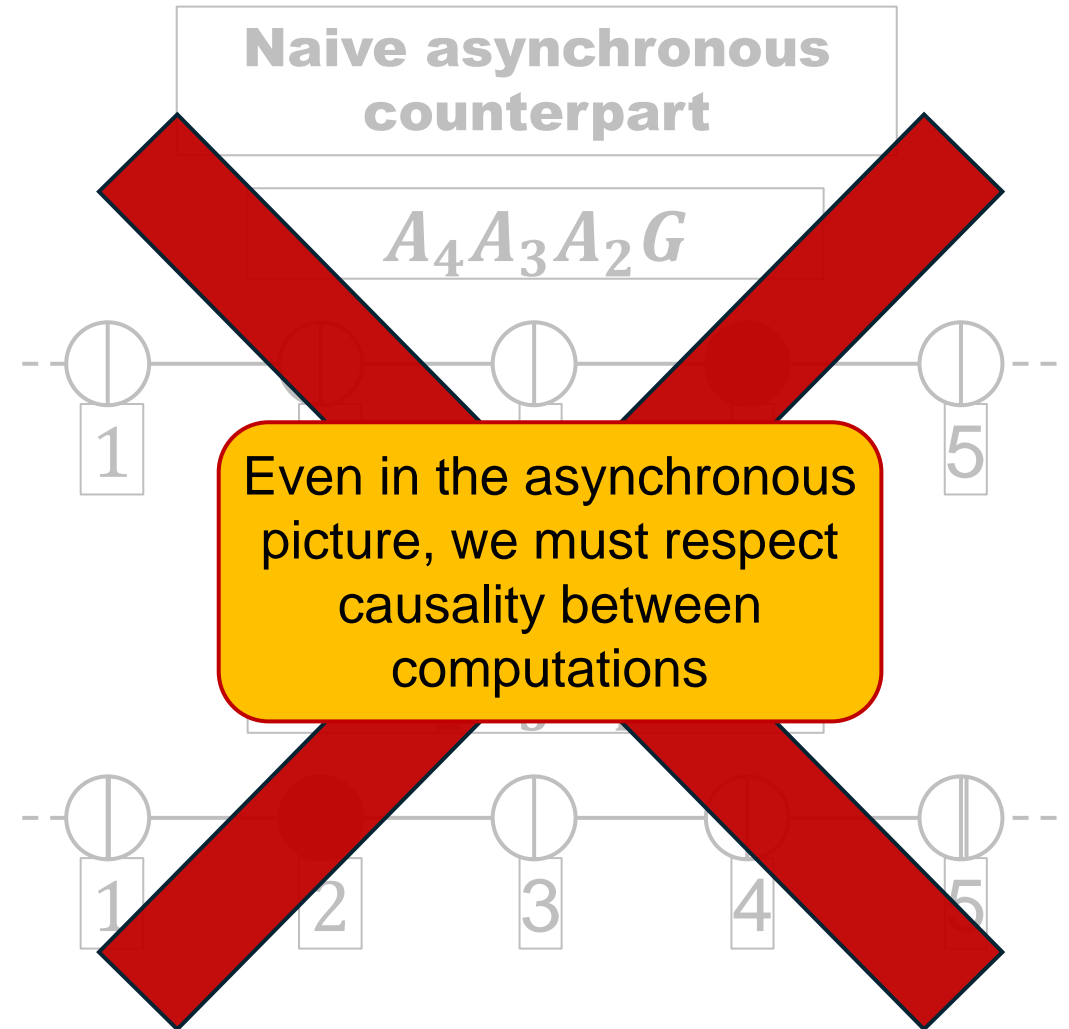
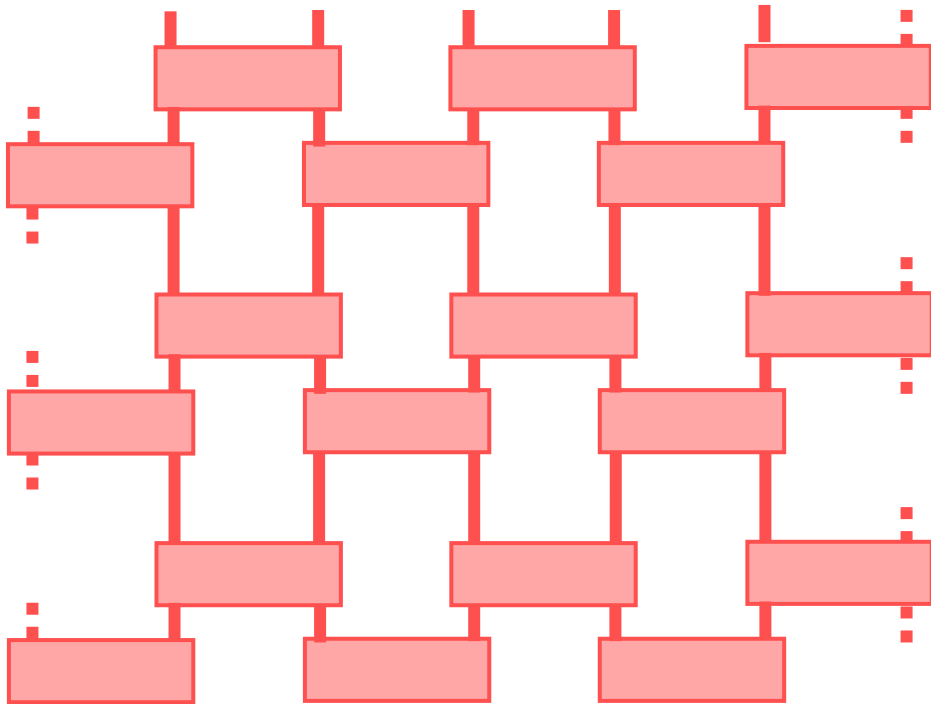
# Dynamical systems and rewriting

## Causal structure



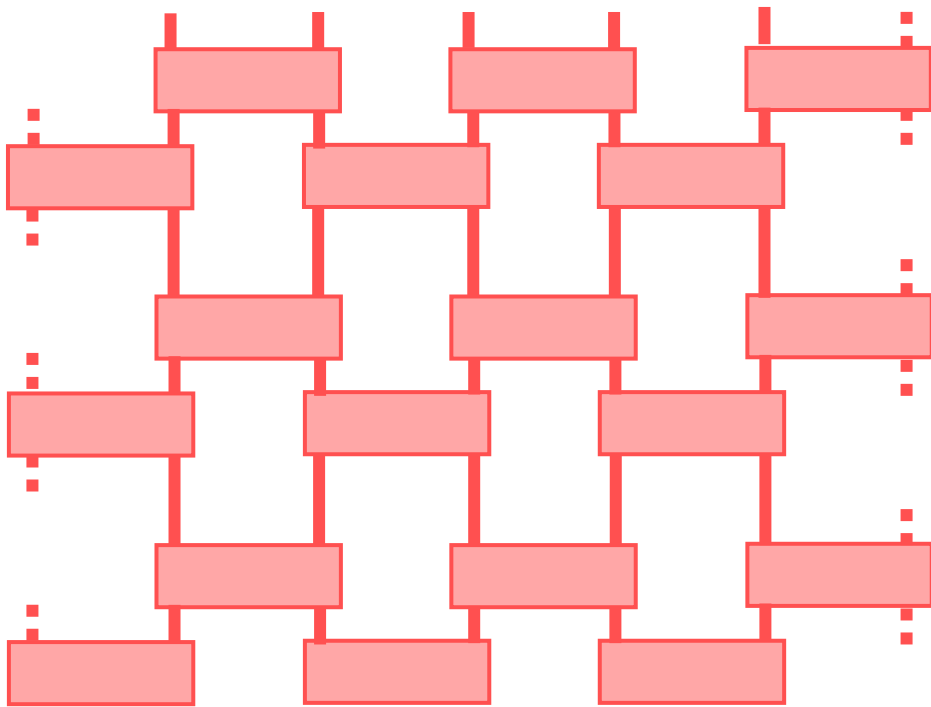
# Dynamical systems and rewriting

## Causal structure

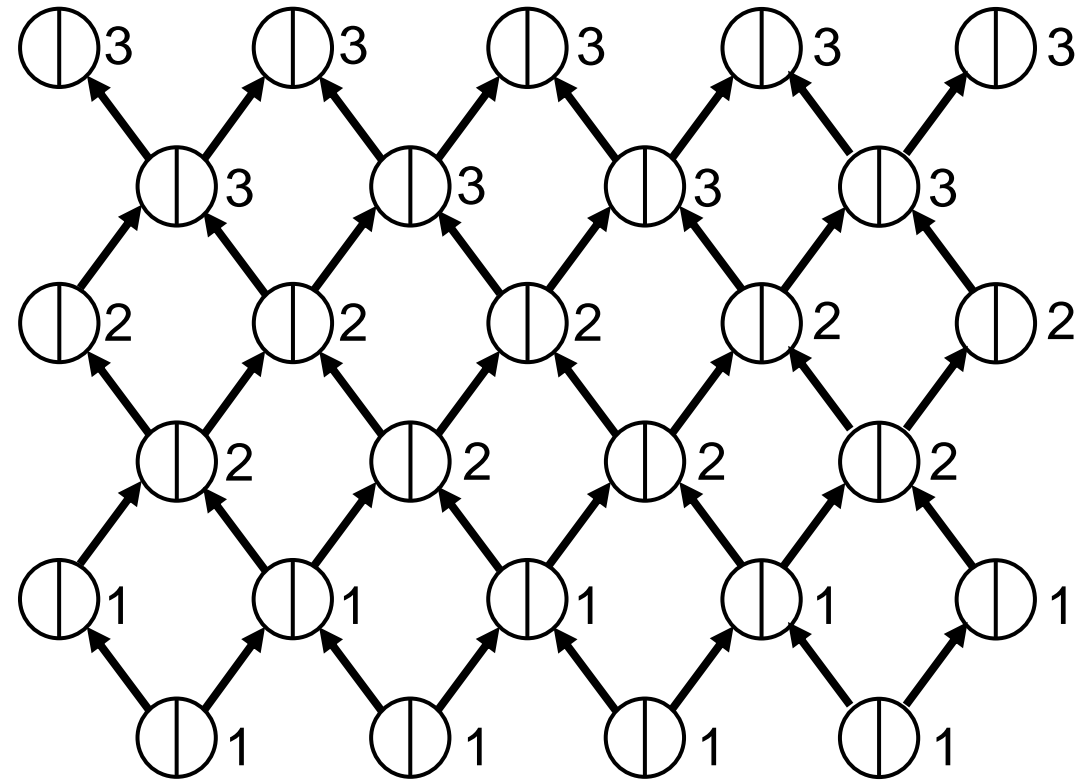


# Dynamical systems and rewriting

## Causal structure

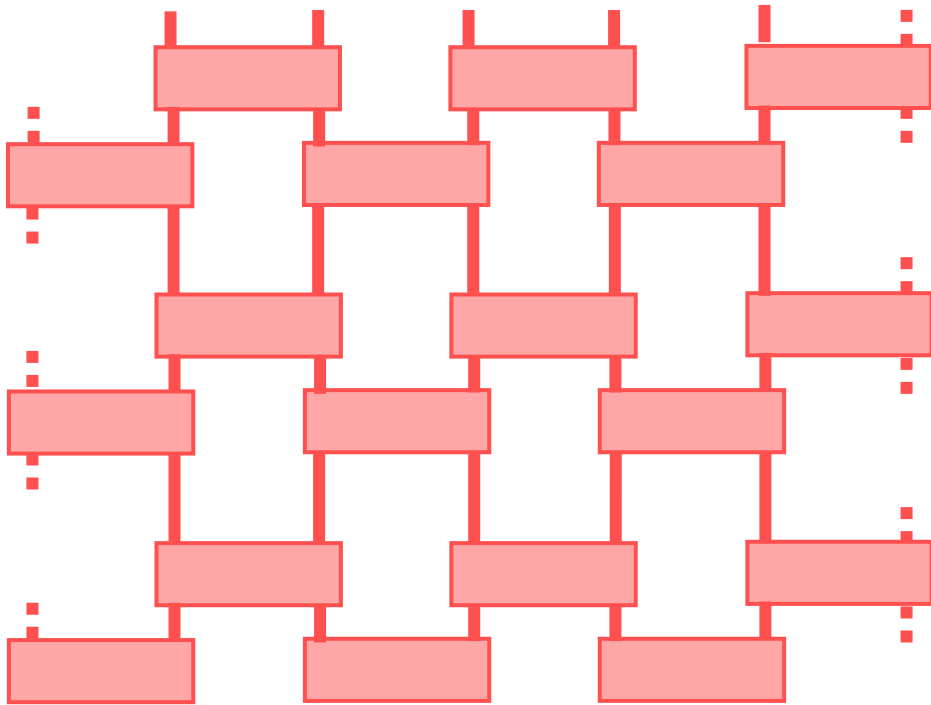


## Causal graph rewriting

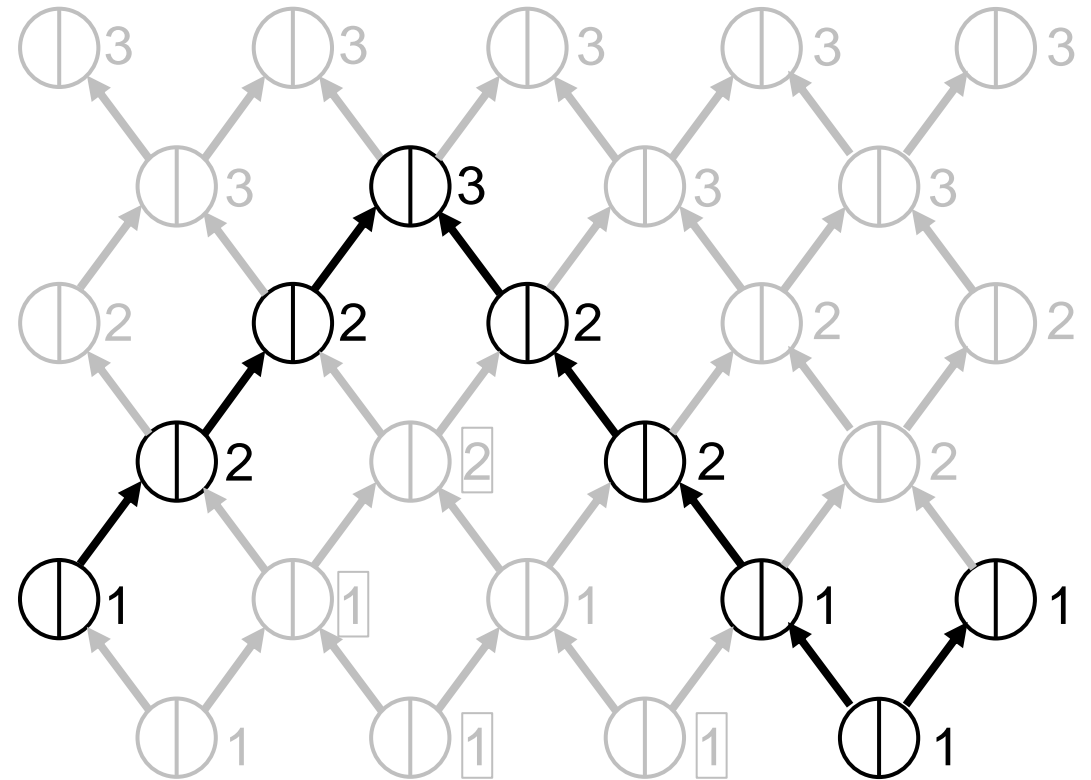


# Dynamical systems and rewriting

## Causal structure

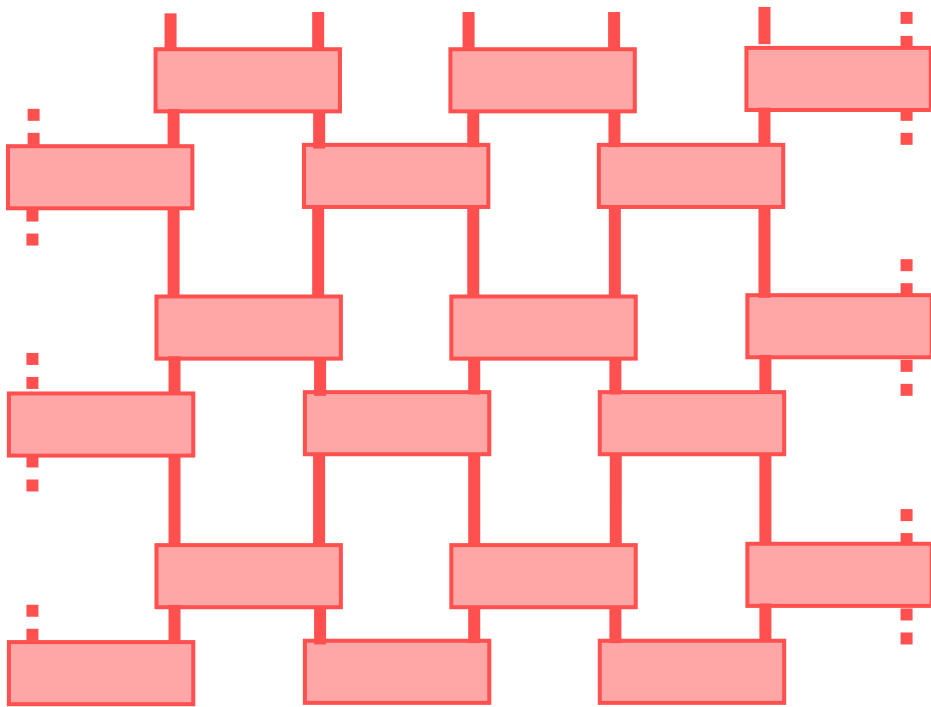


## Causal graph rewriting

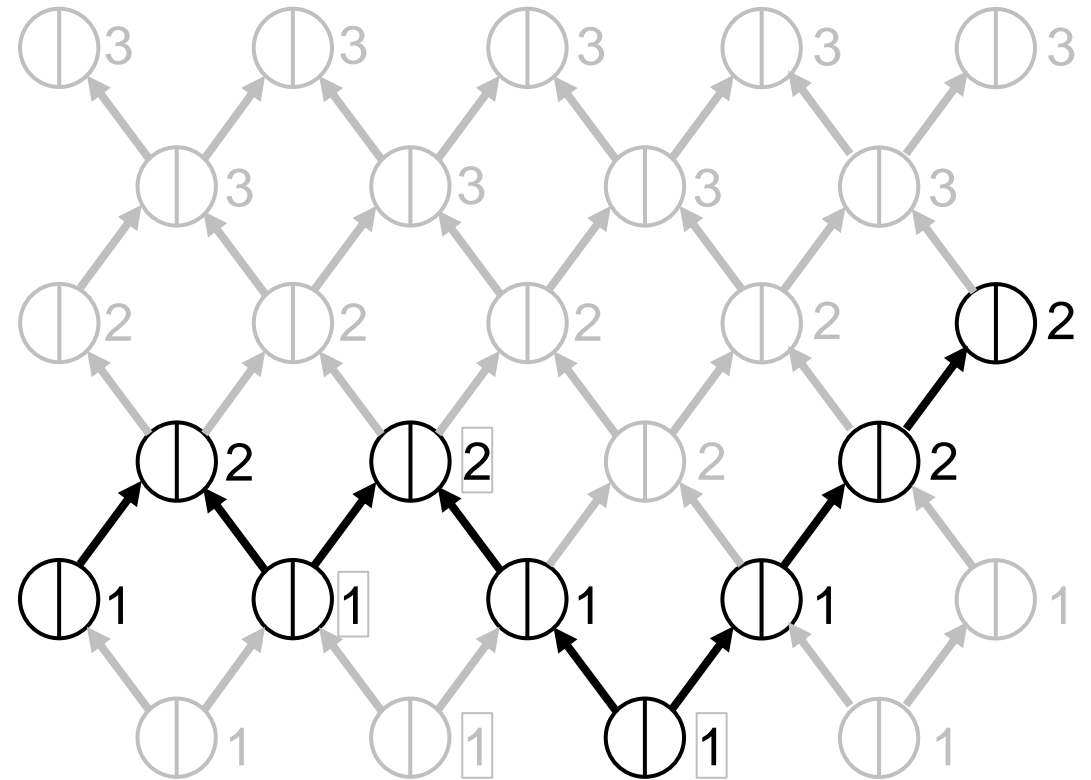


# Dynamical systems and rewriting

## Causal structure

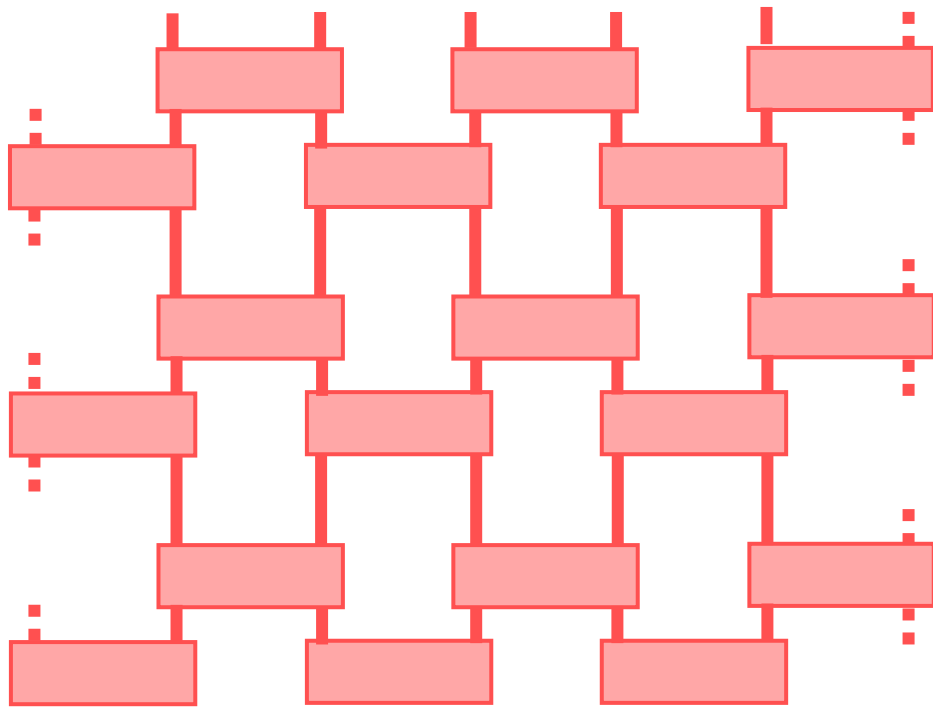


## Causal graph rewriting

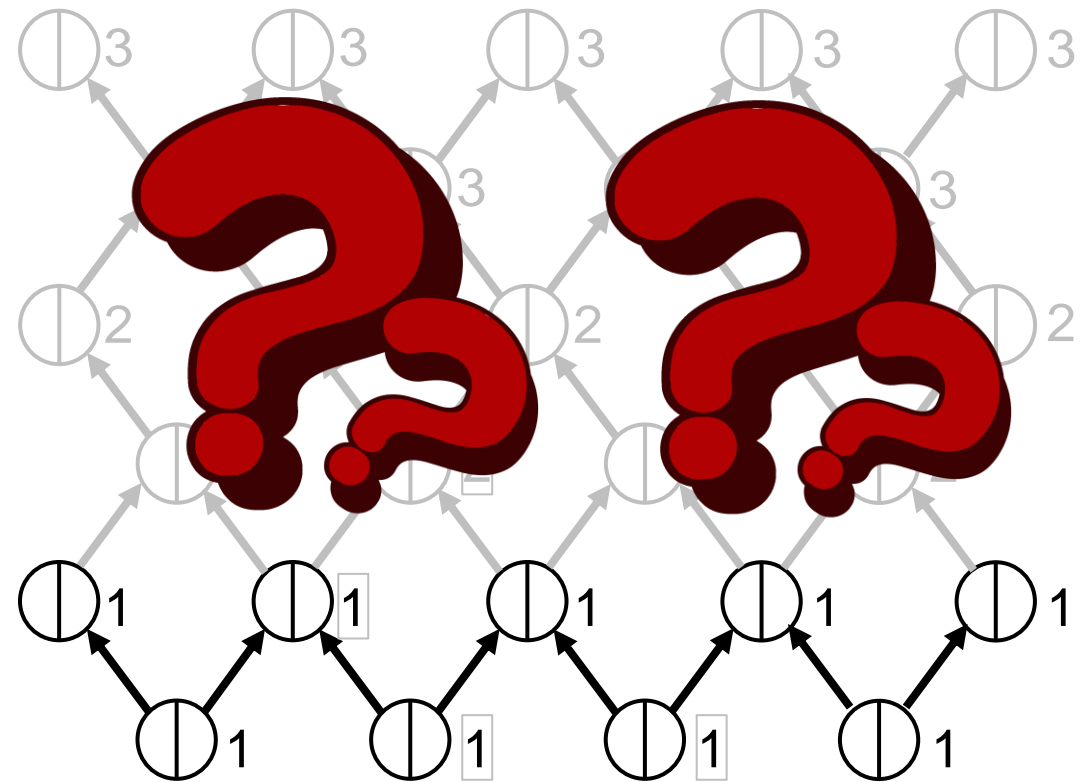


# Dynamical systems and rewriting

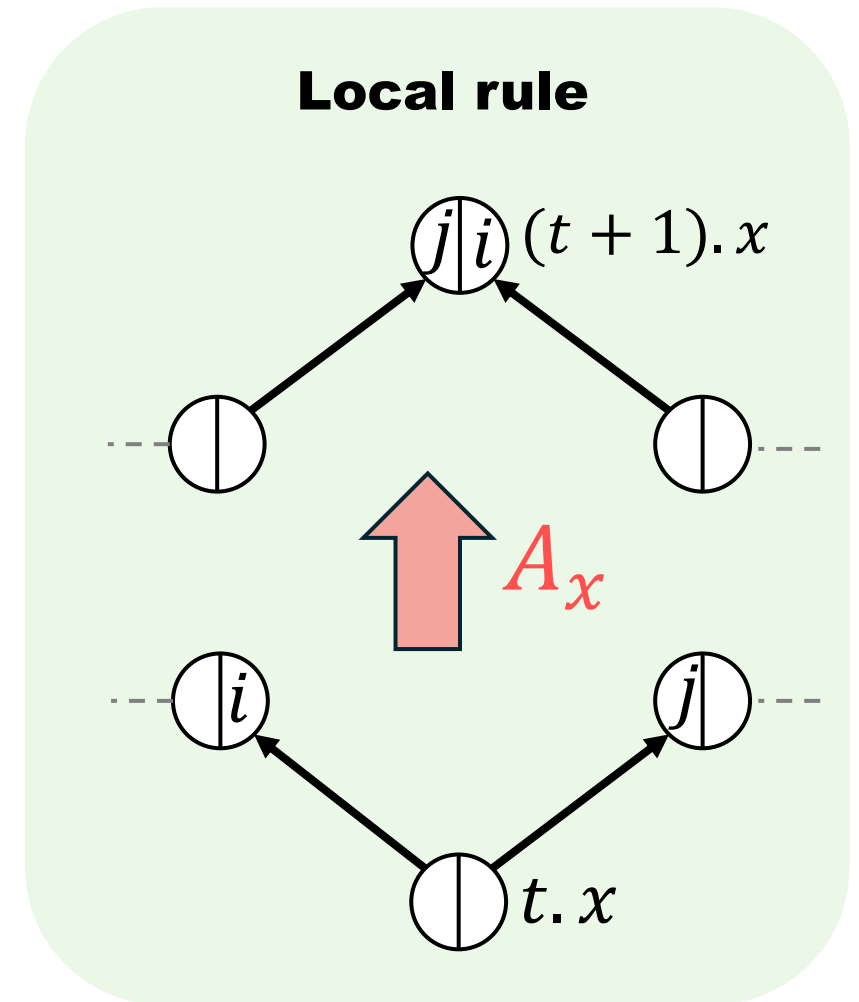
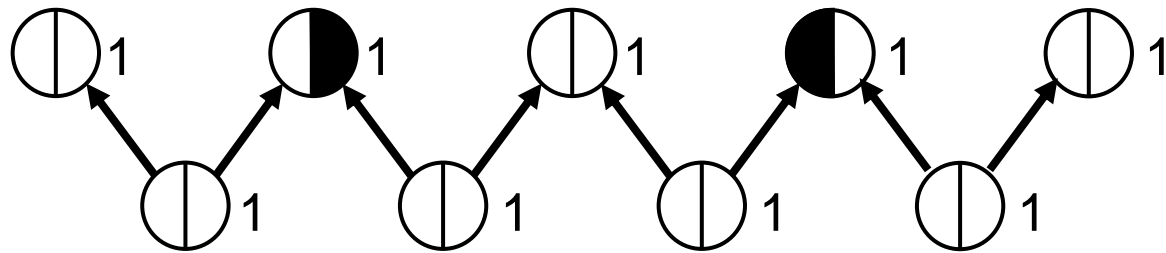
## Causal structure



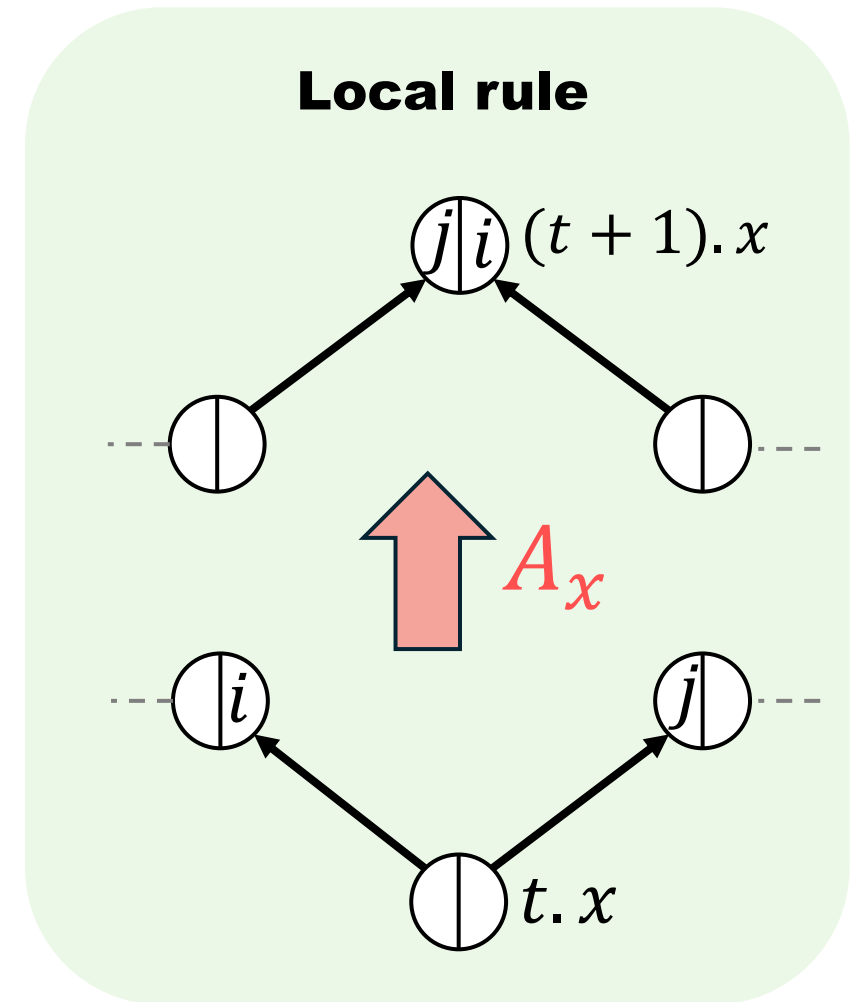
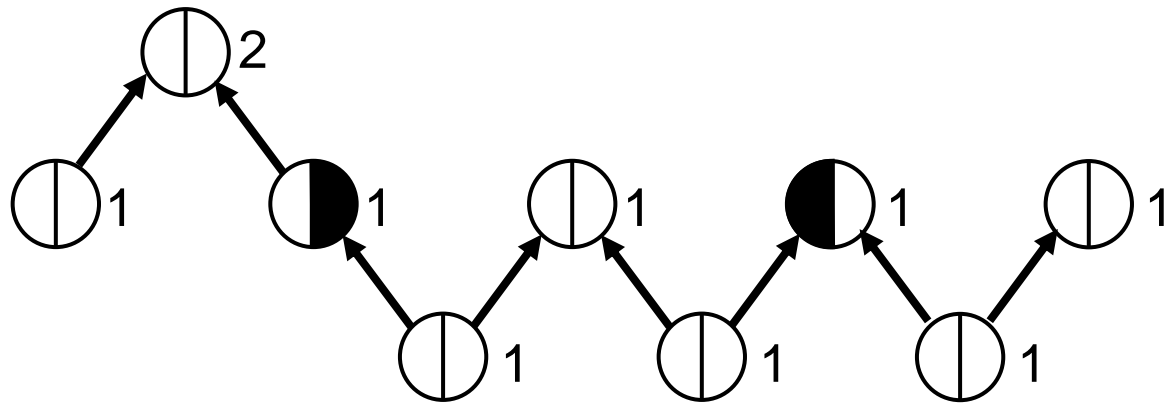
## Causal graph rewriting



# Particle system example

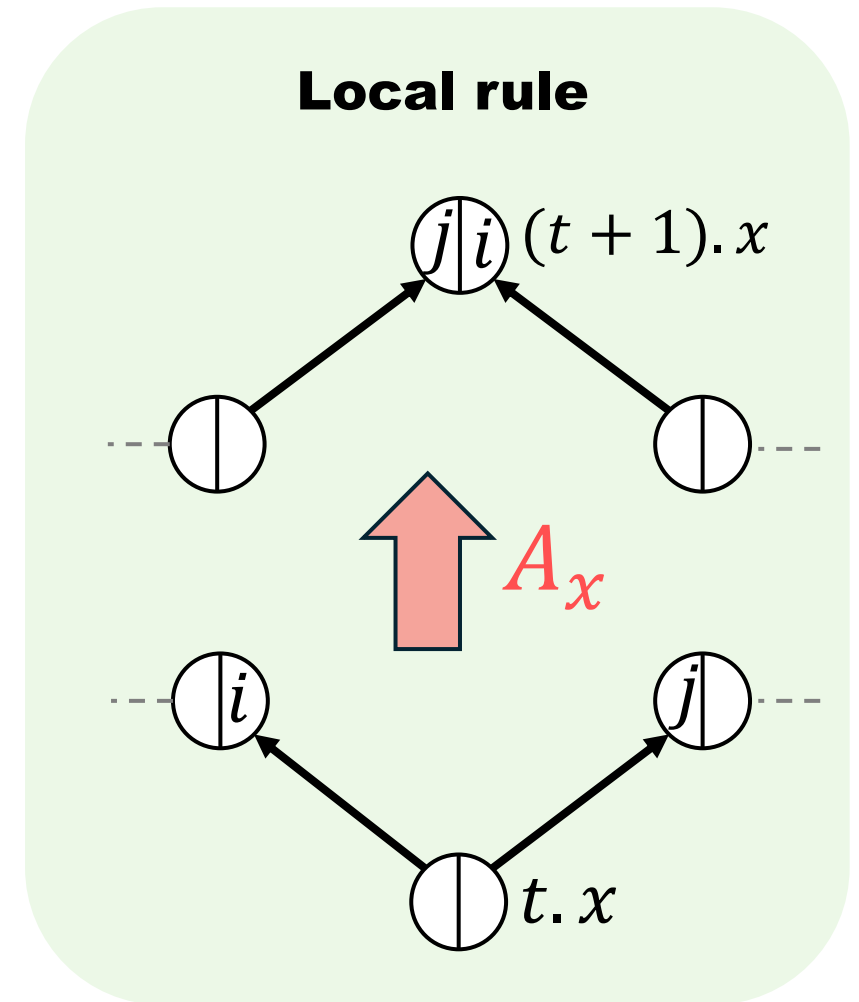
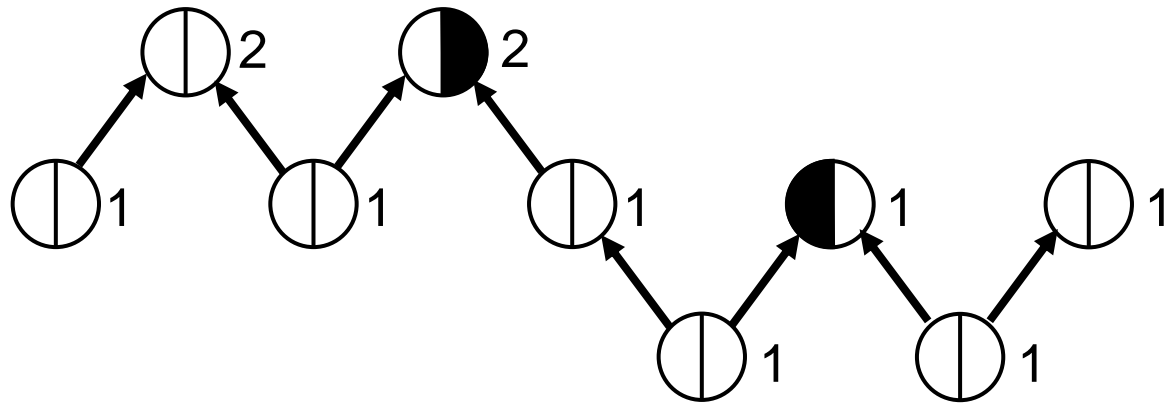


# Particle system example

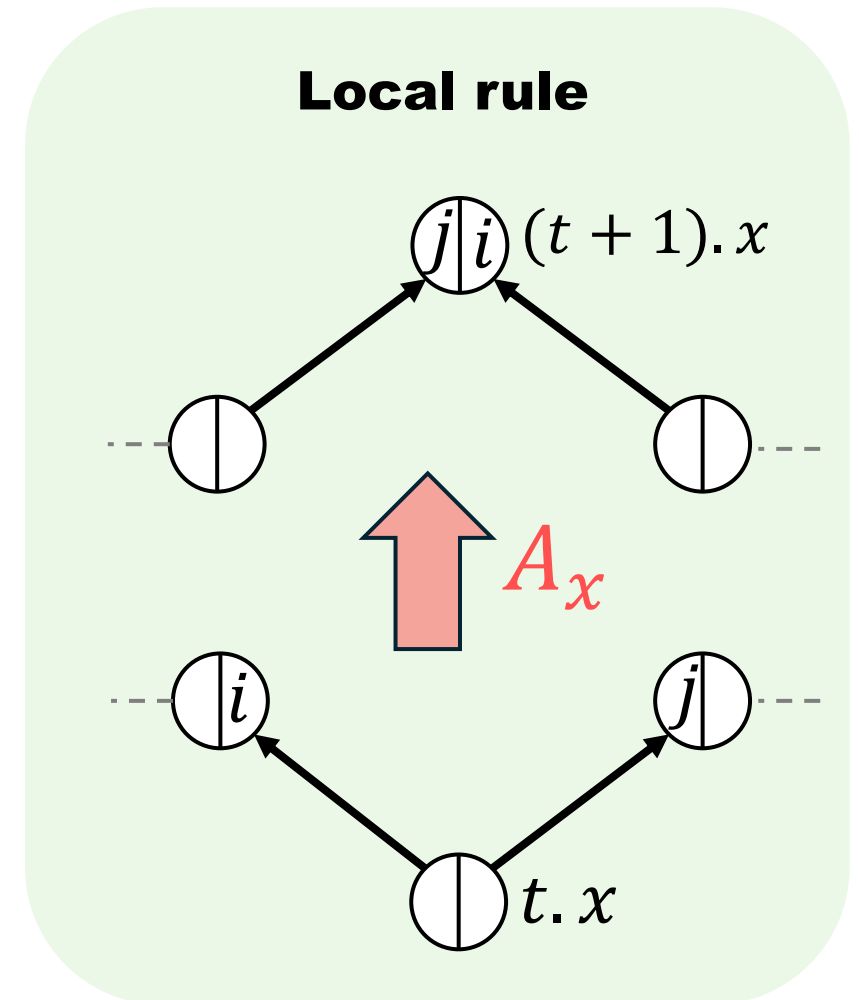
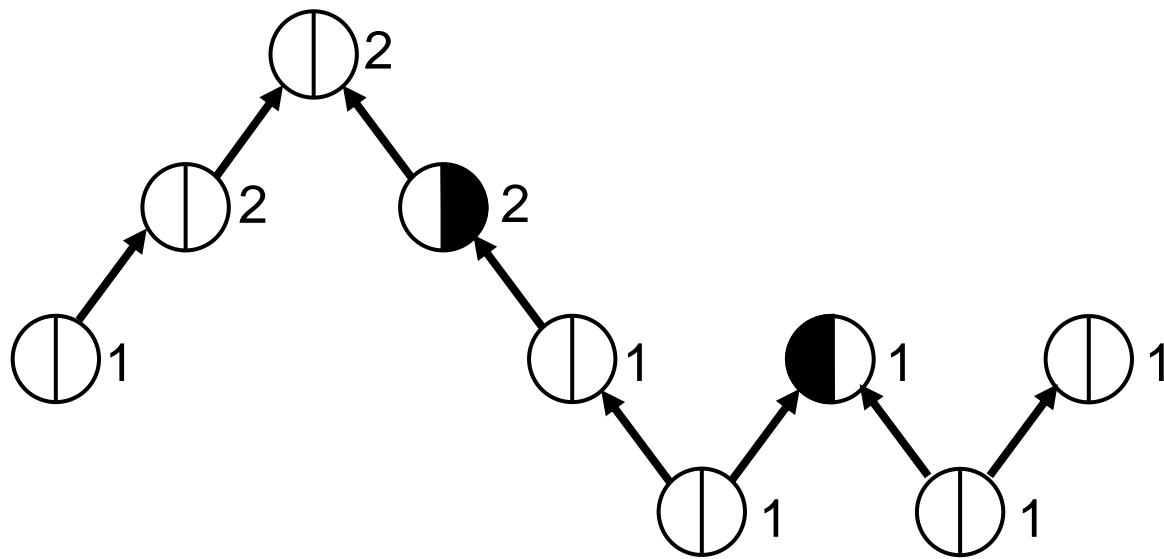




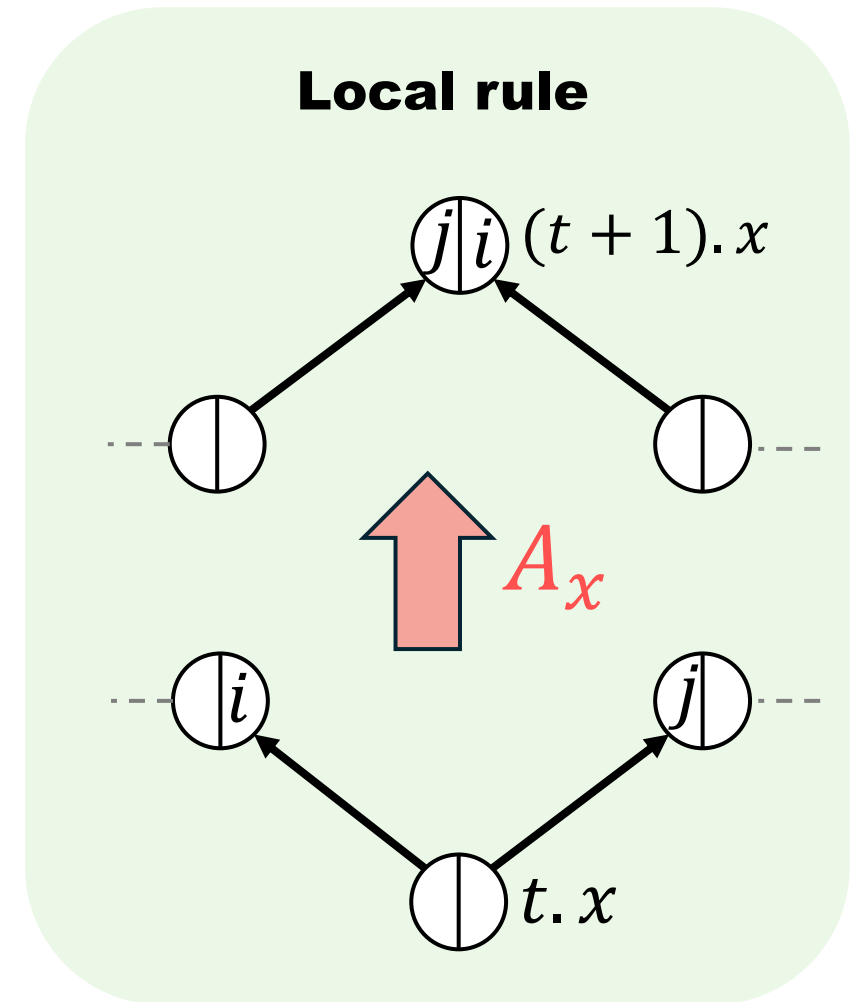
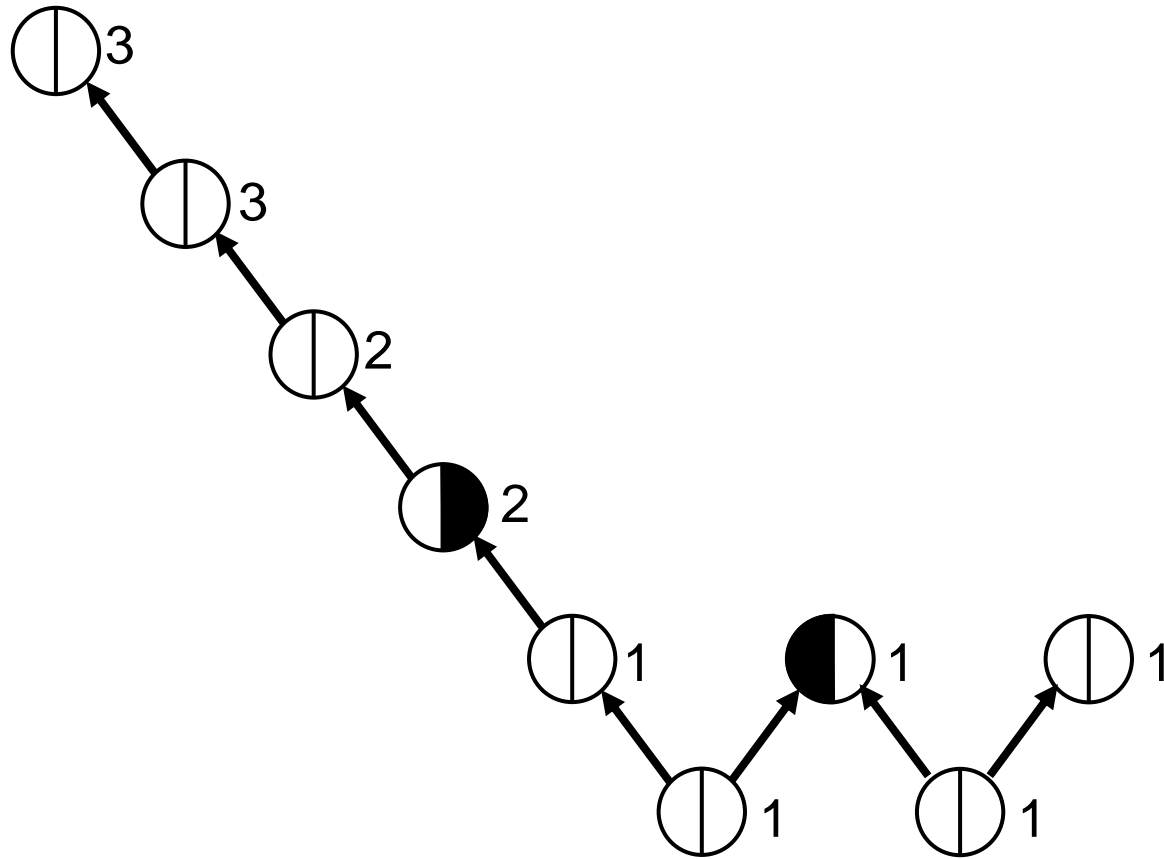
# Particle system example



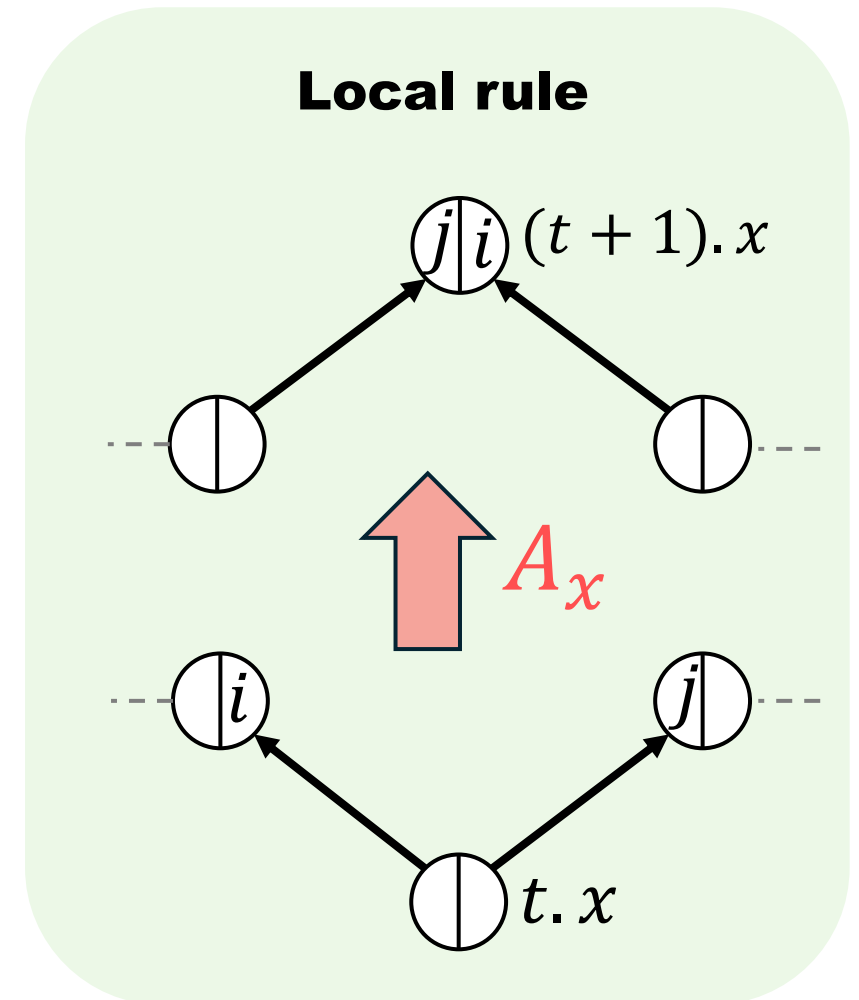
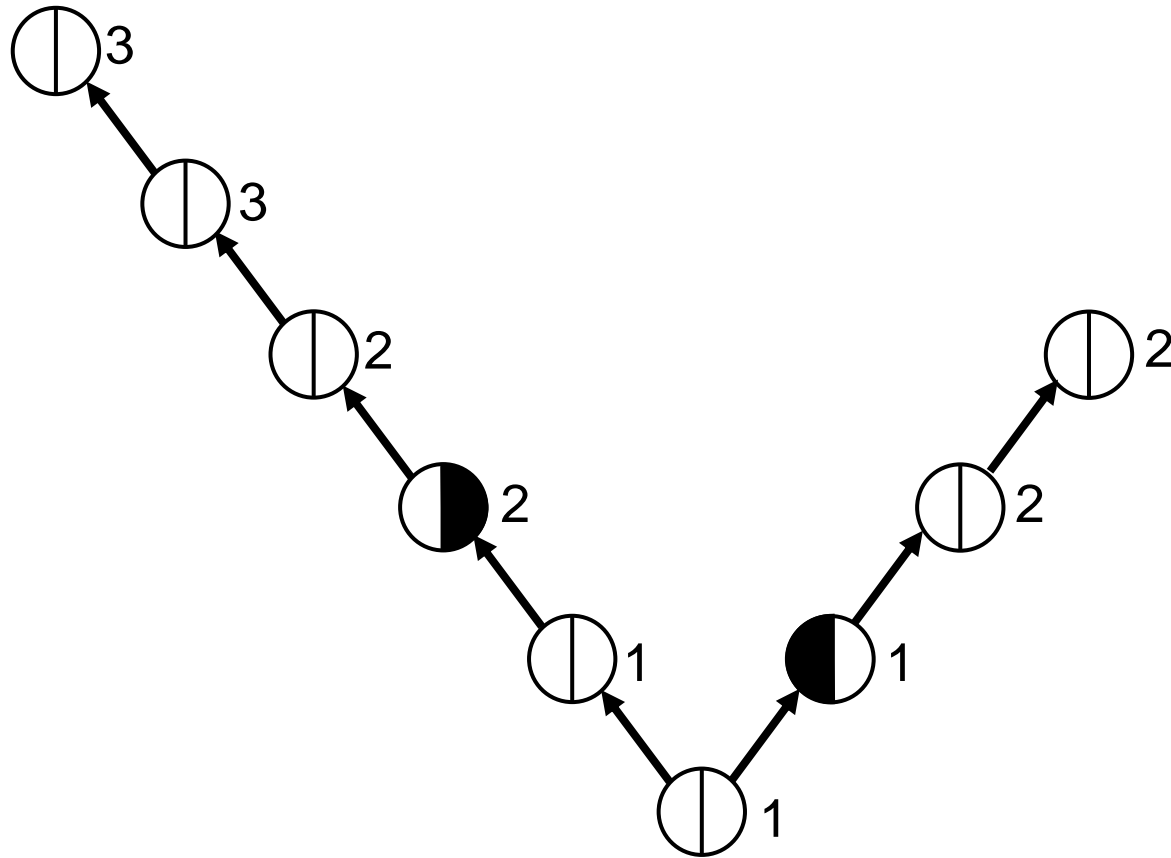
# Particle system example



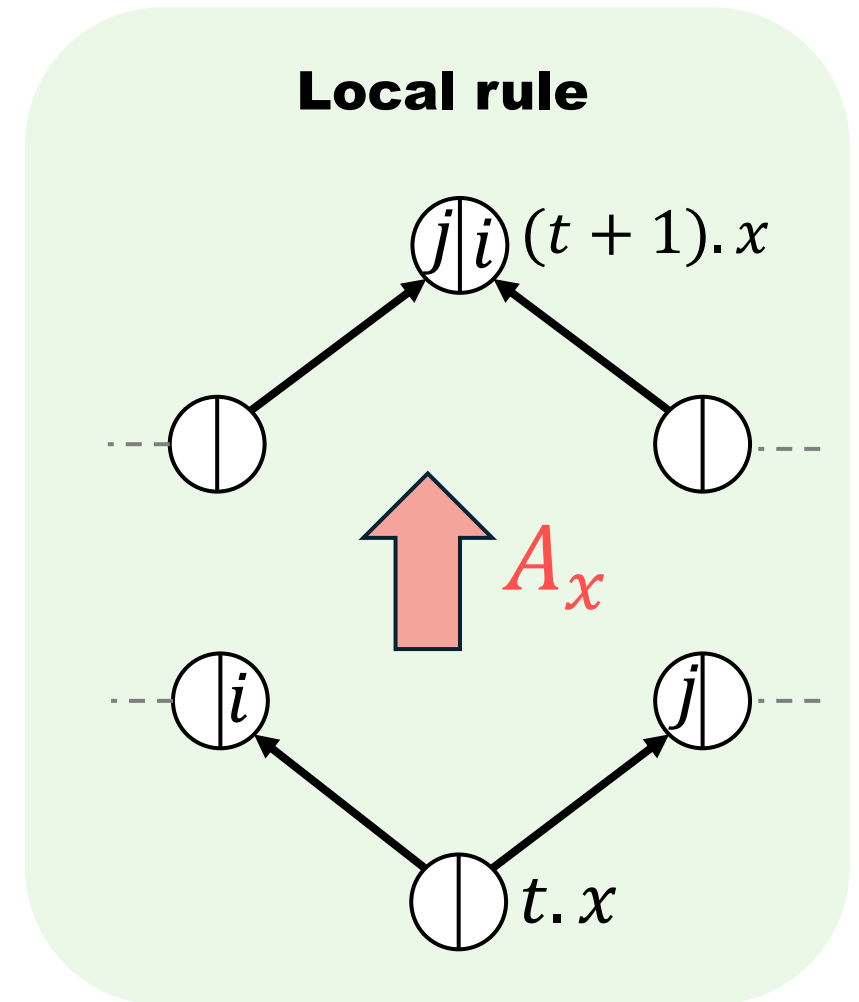
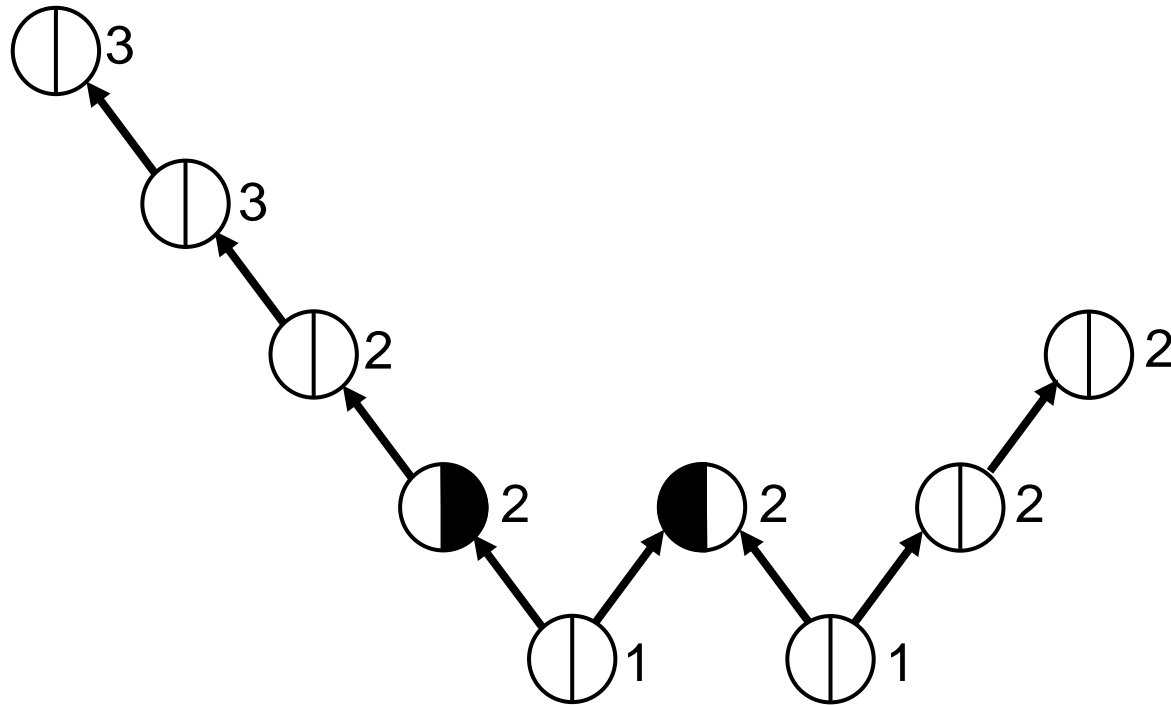
# Particle system example



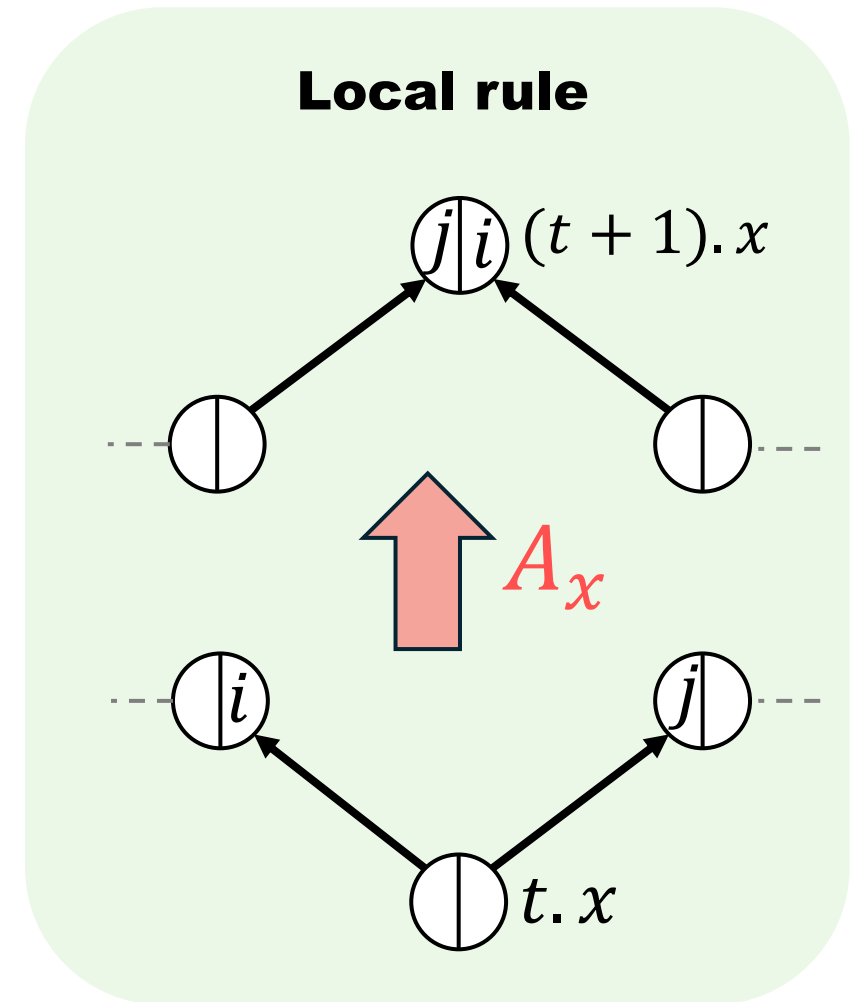
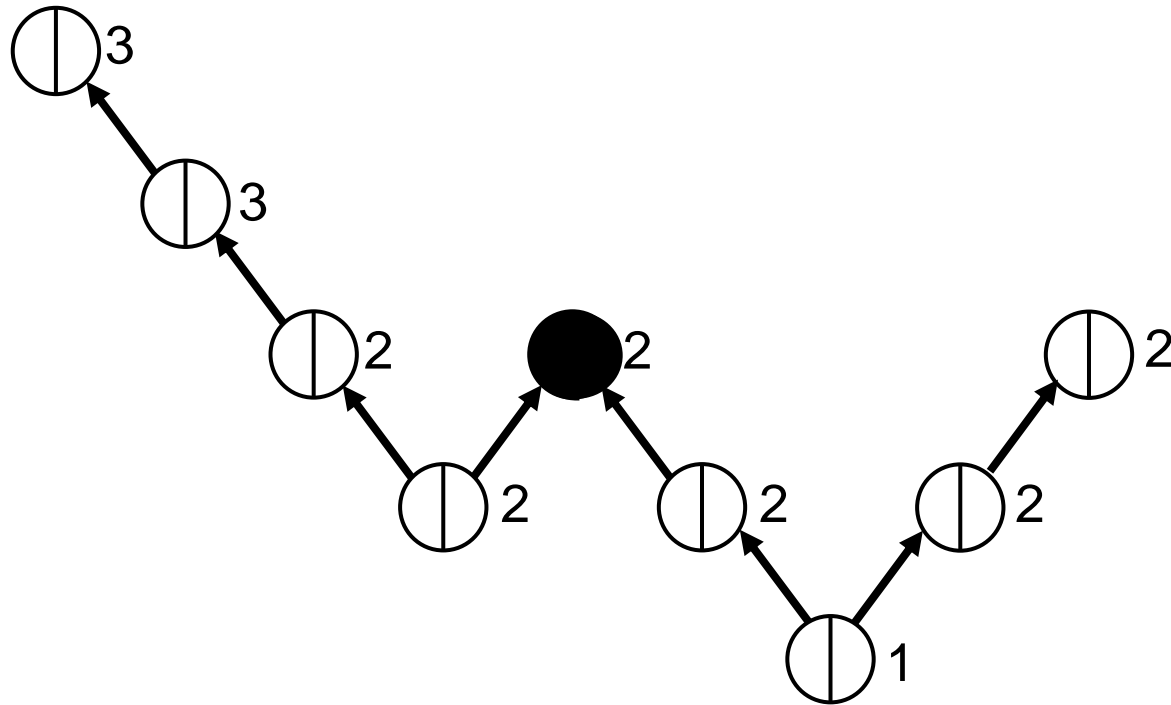
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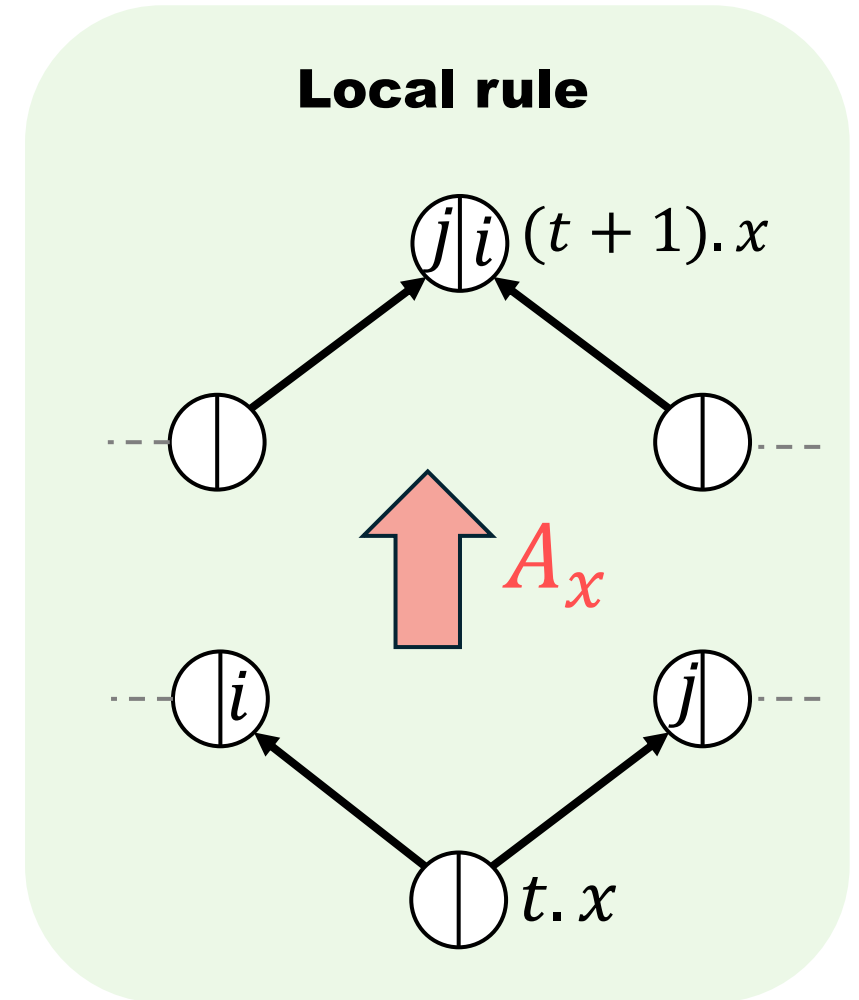
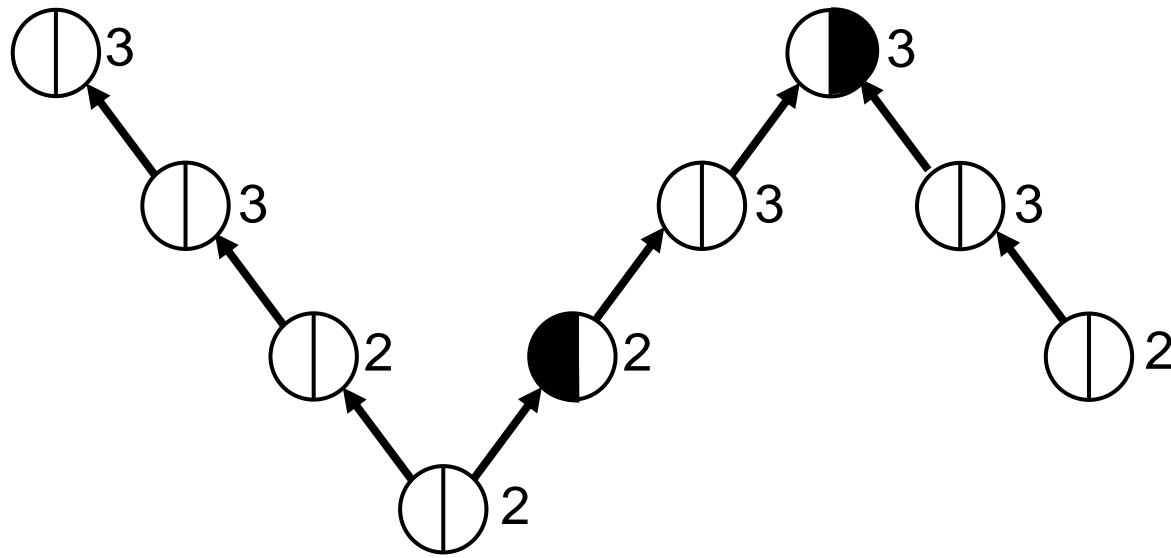
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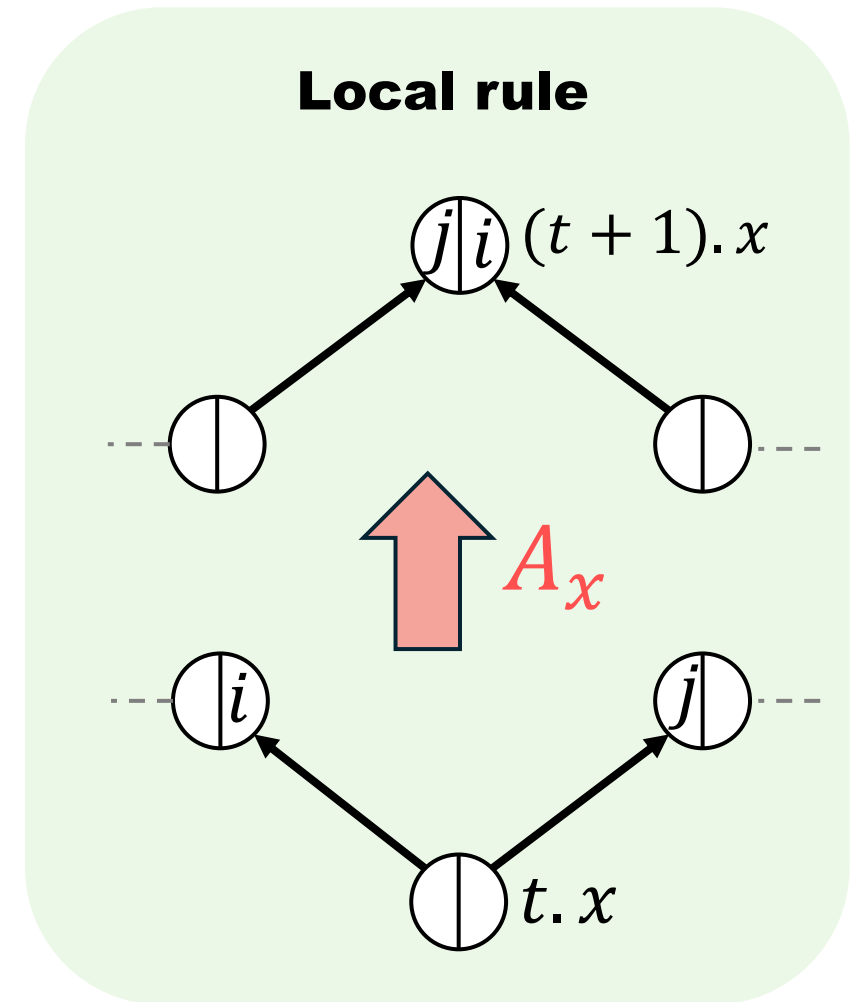
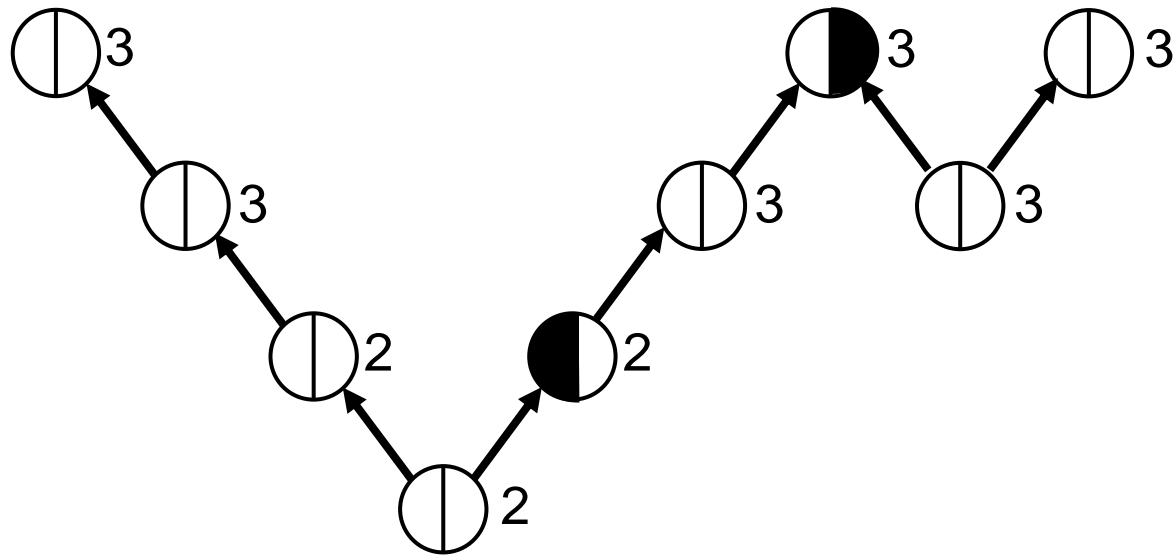
# Particle system example



# Particle system example

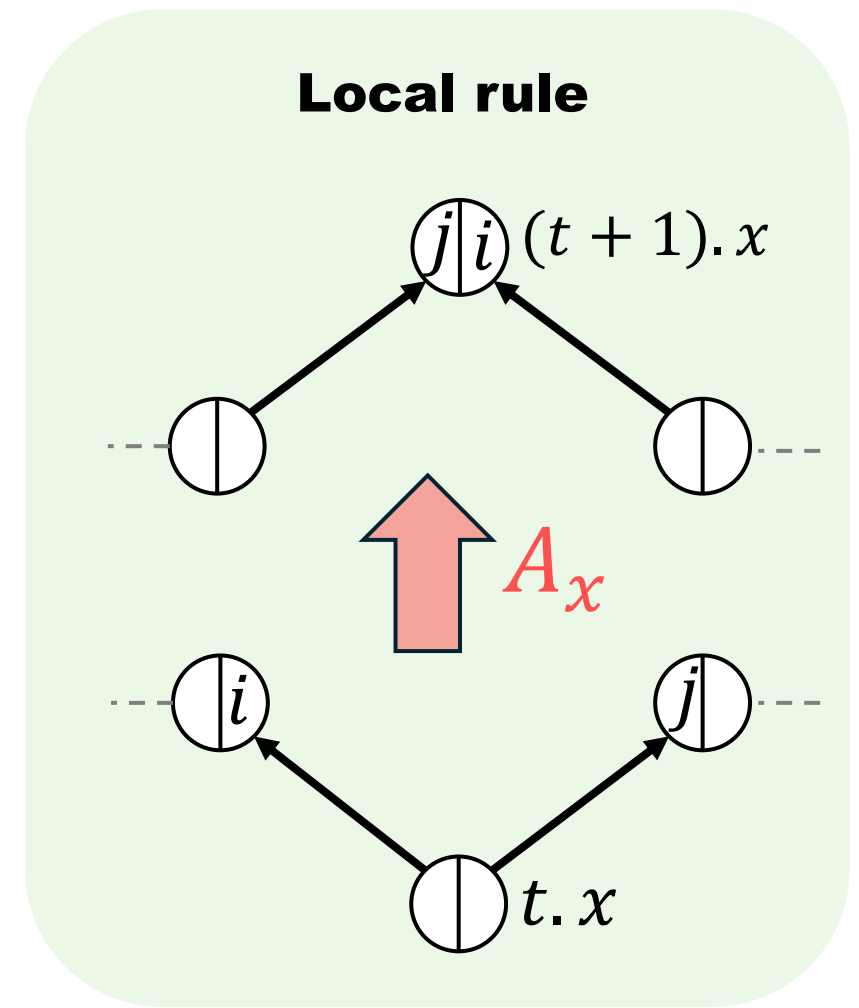
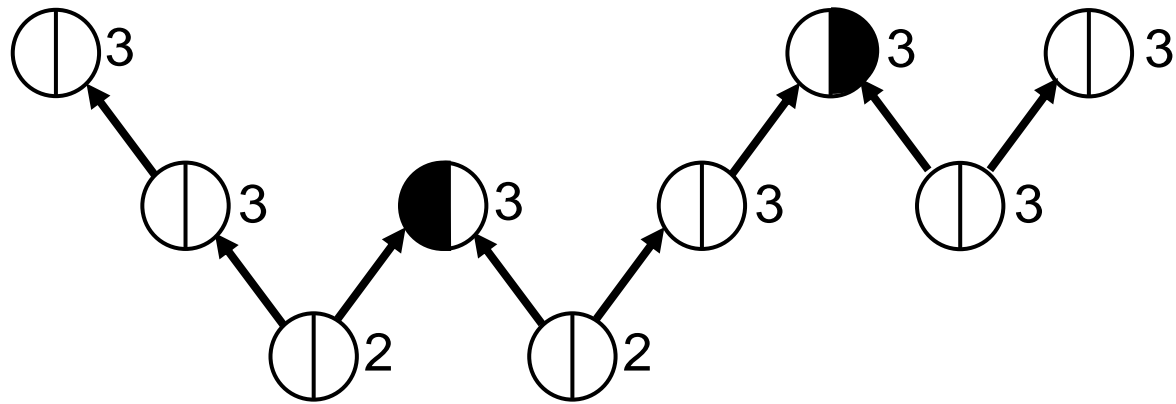


# Particle system example

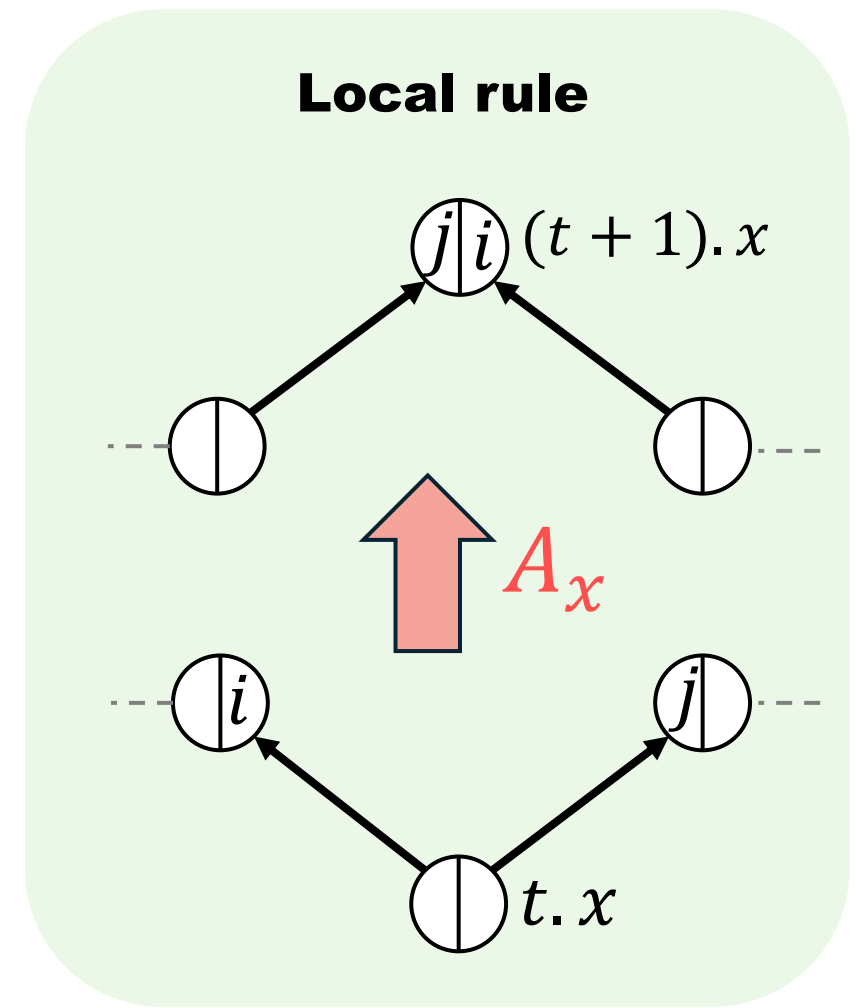
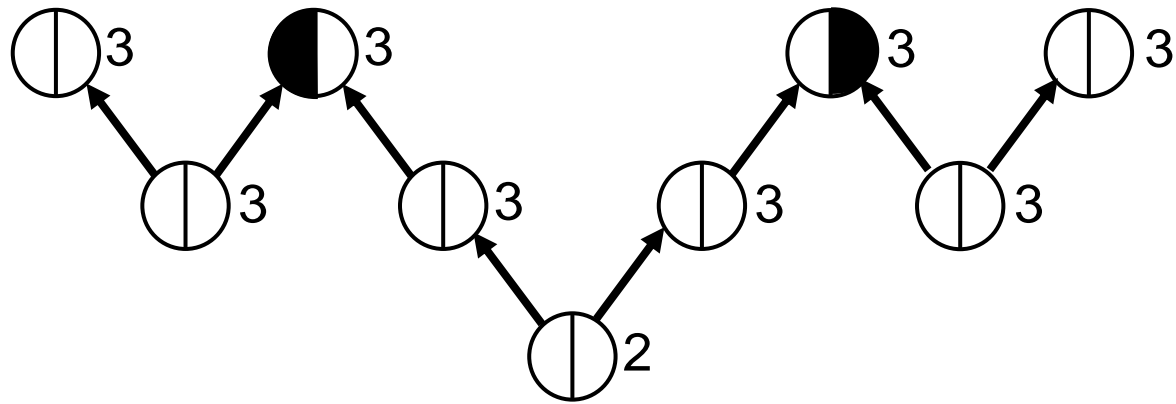




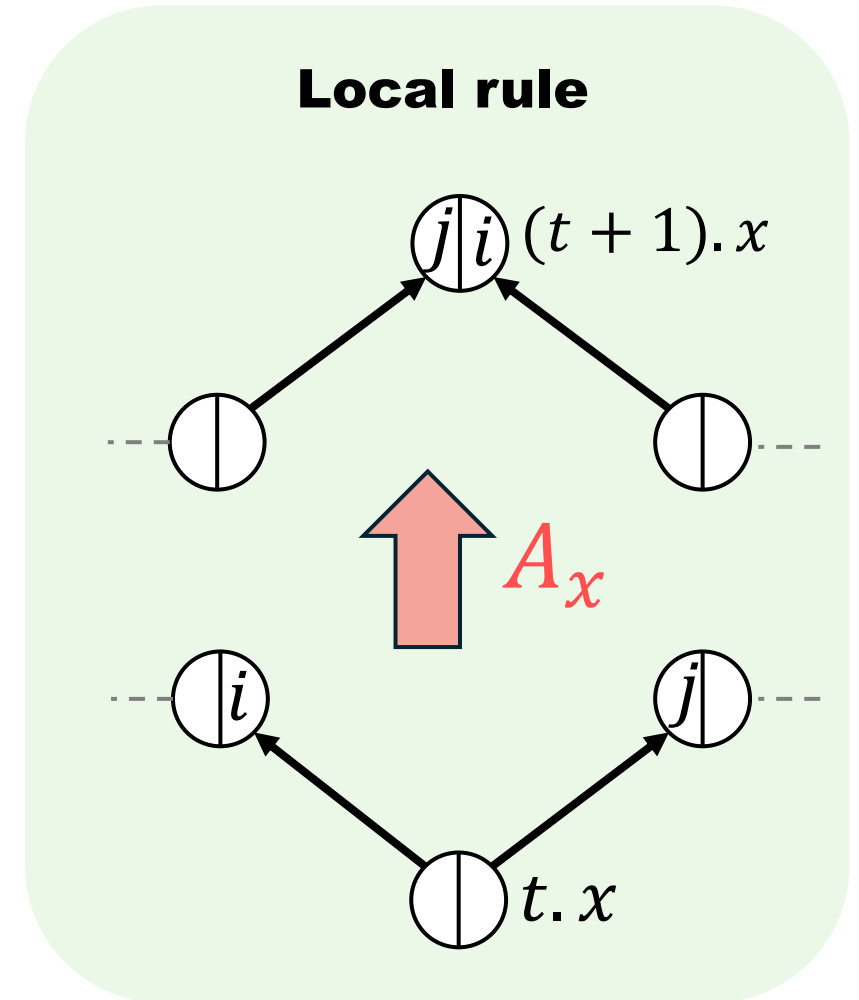
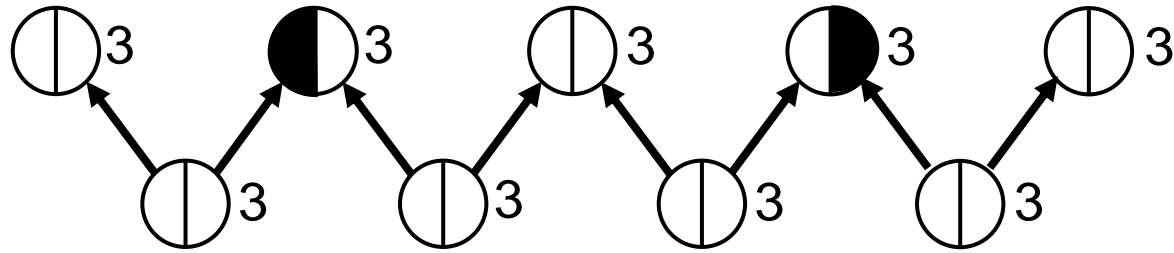
# Particle system example



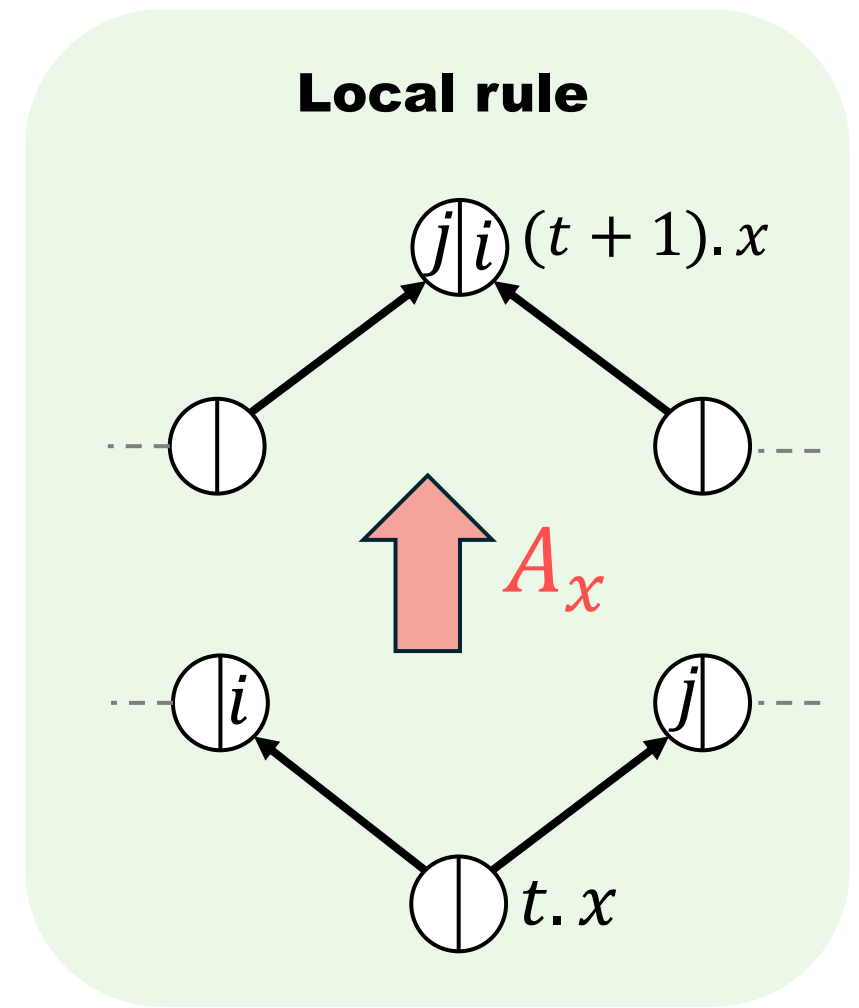
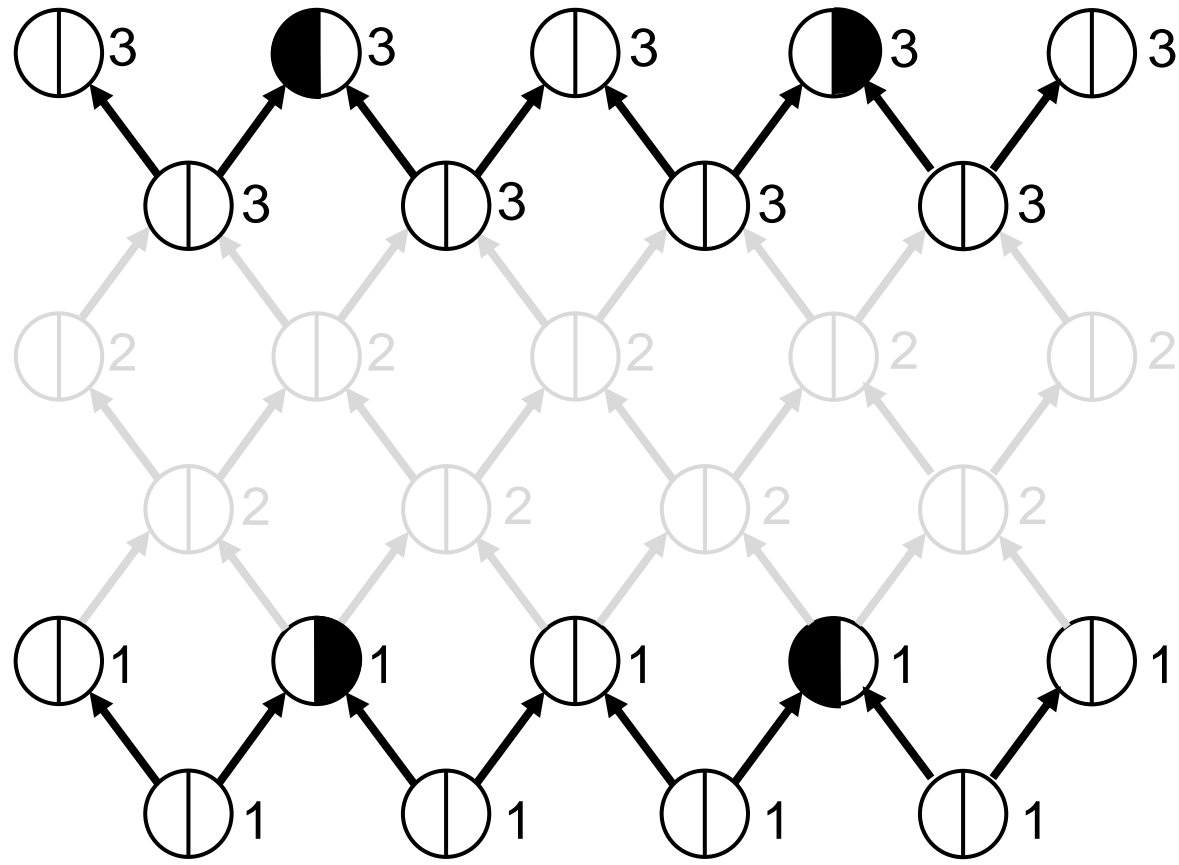
# Particle system example



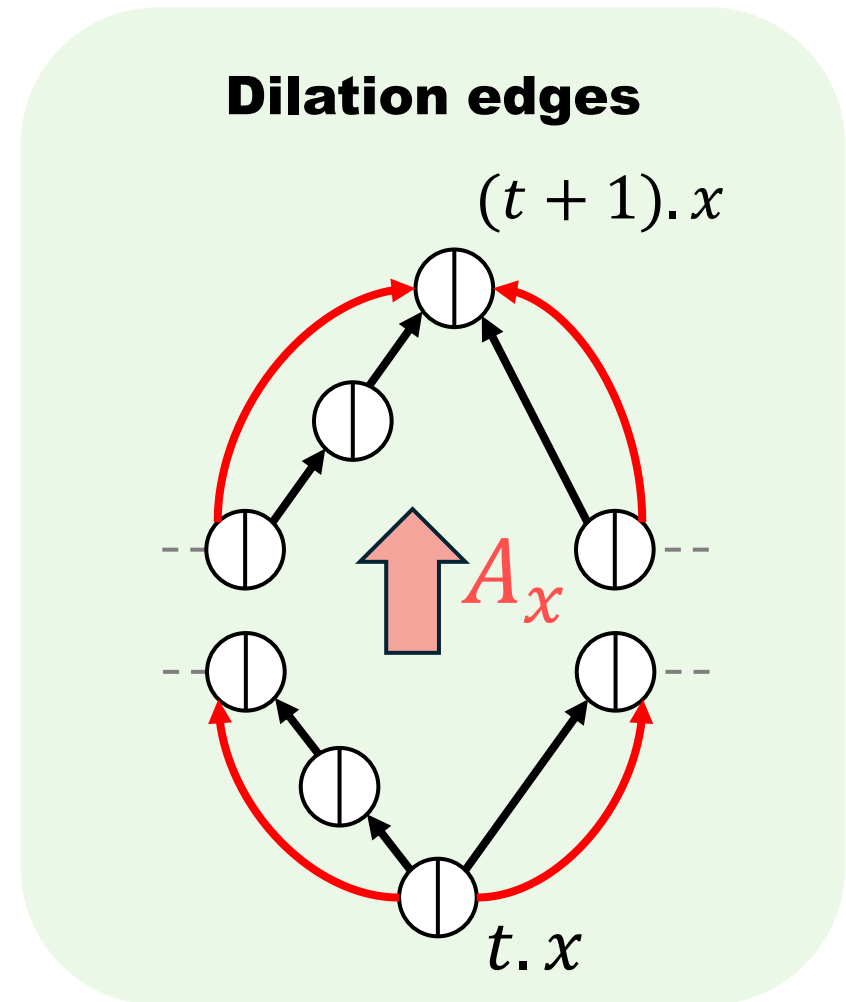
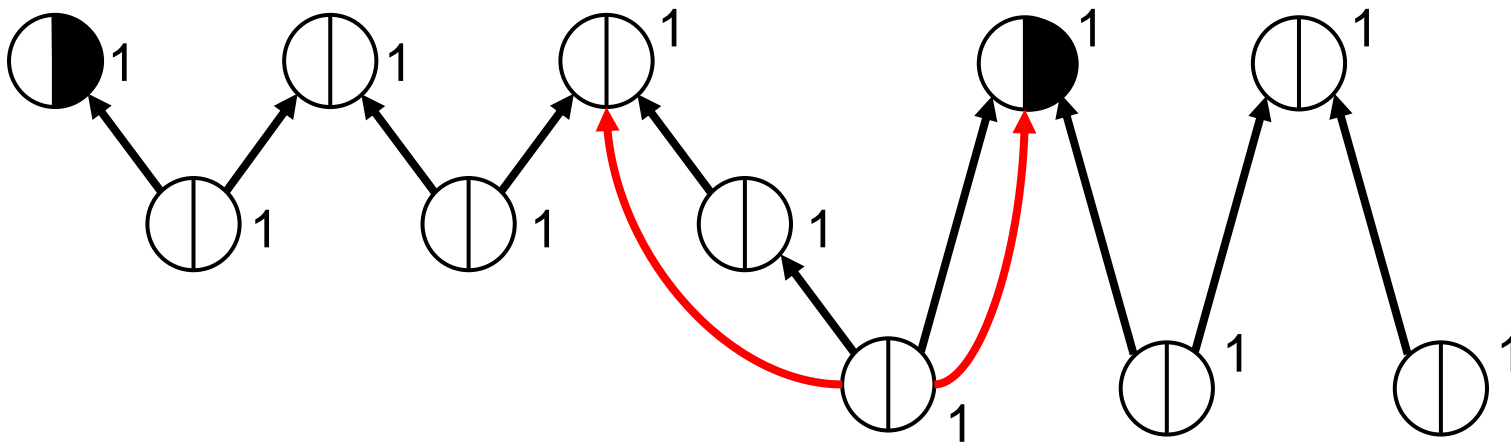
# Particle system example



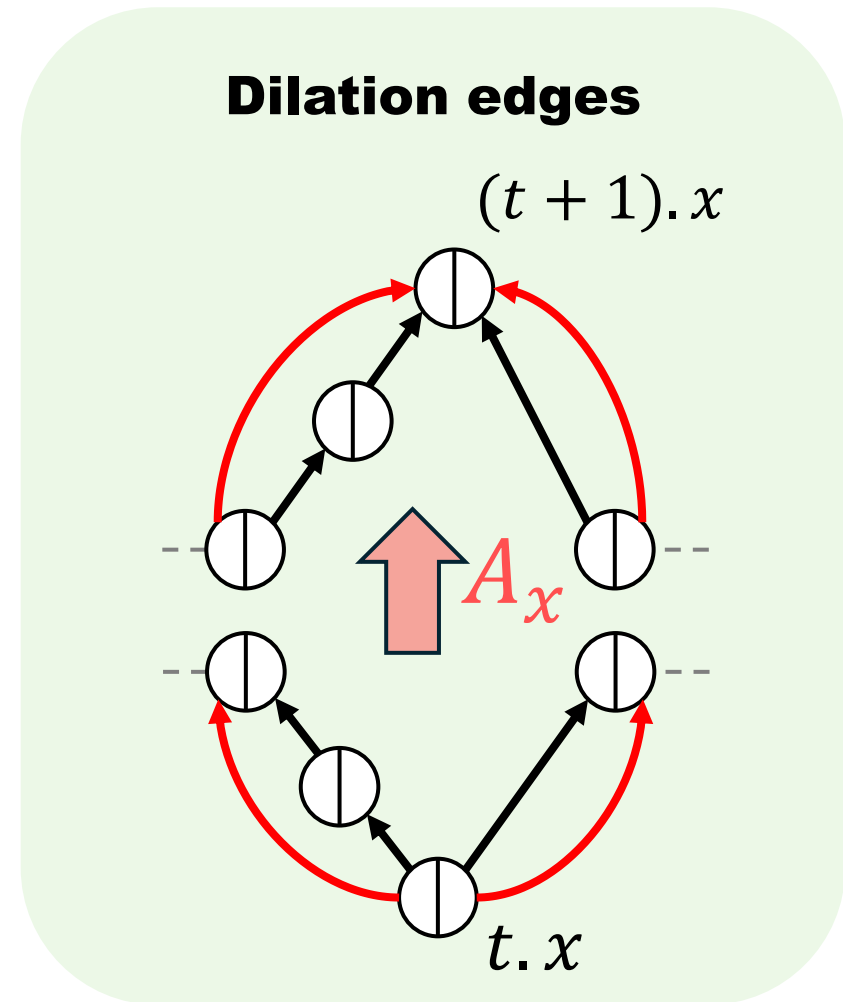
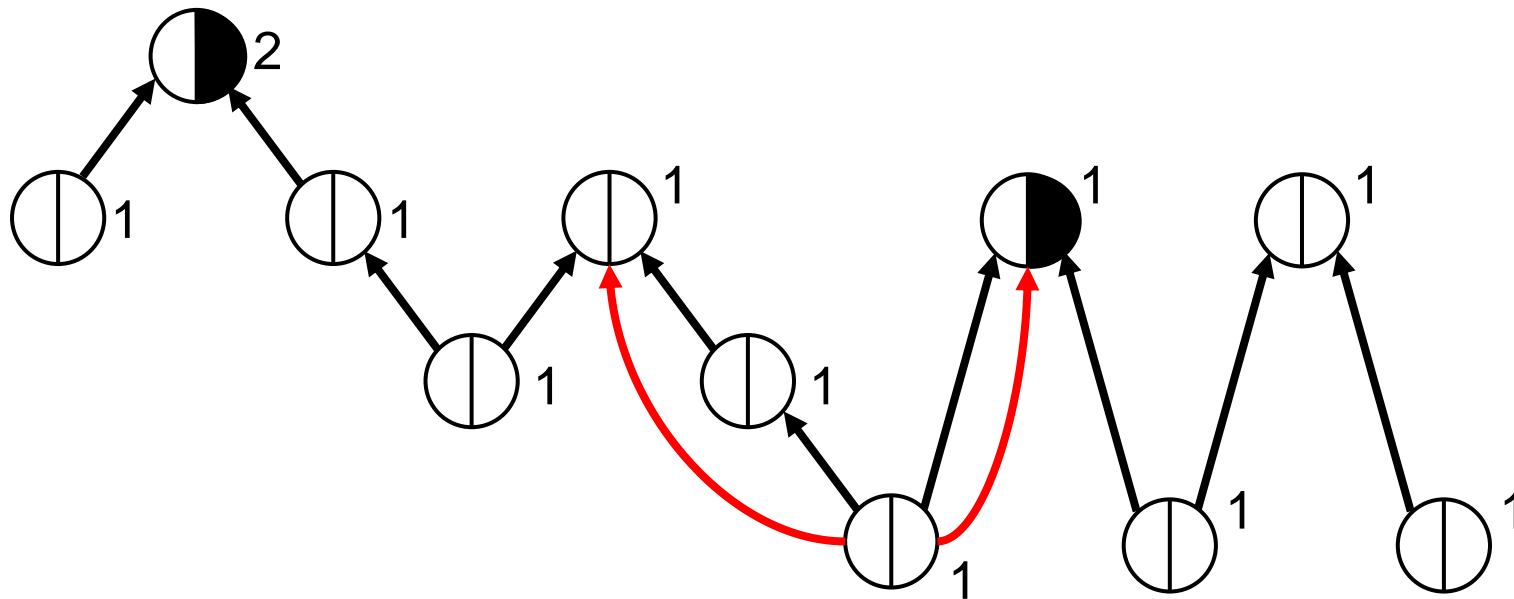
# Particle system example



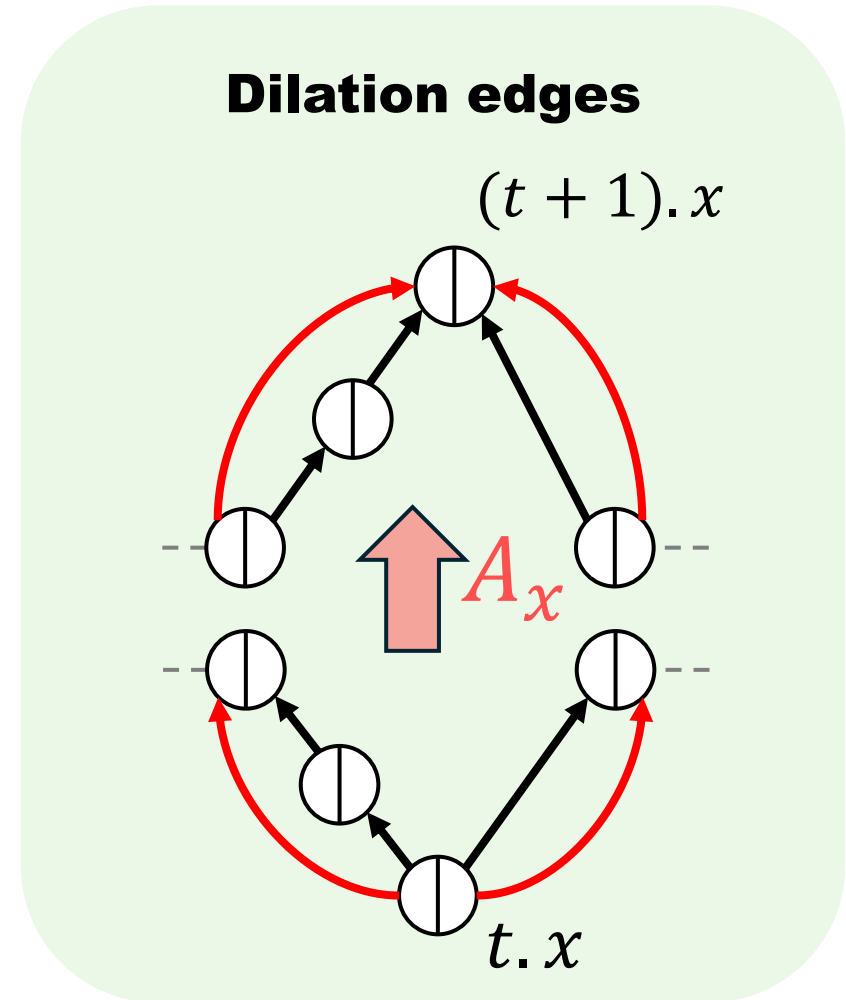
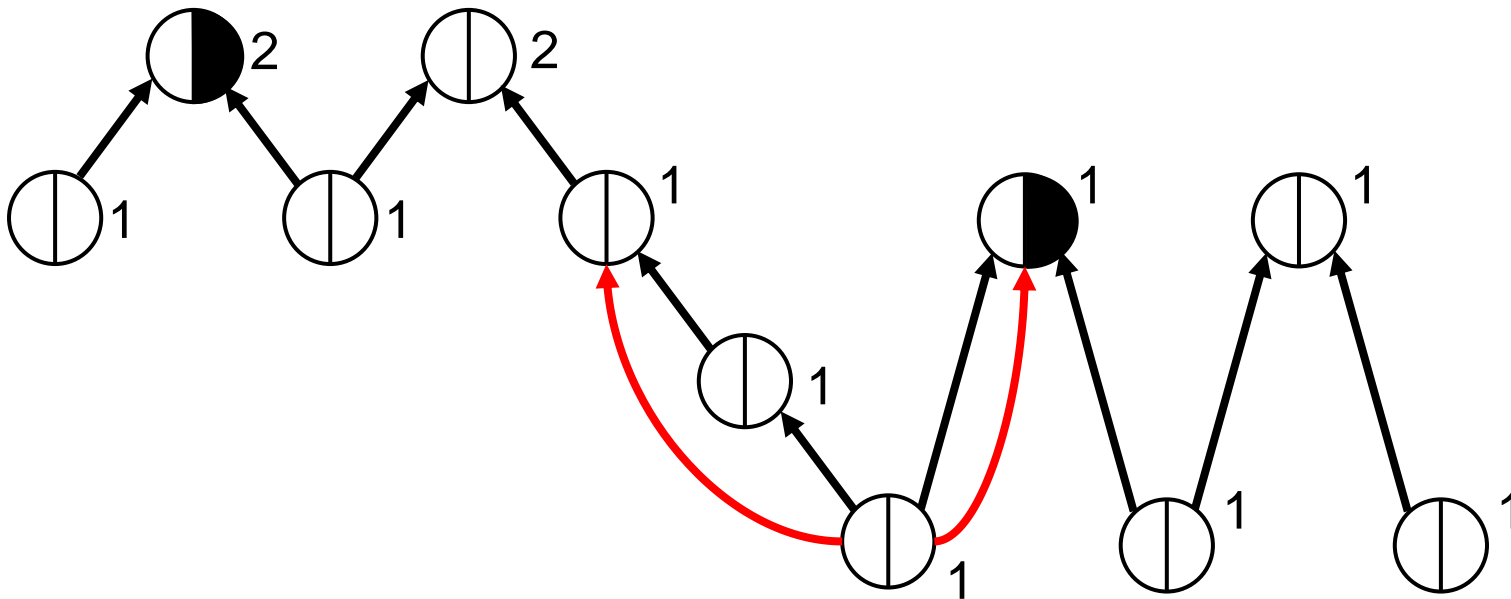
# Time dilation example



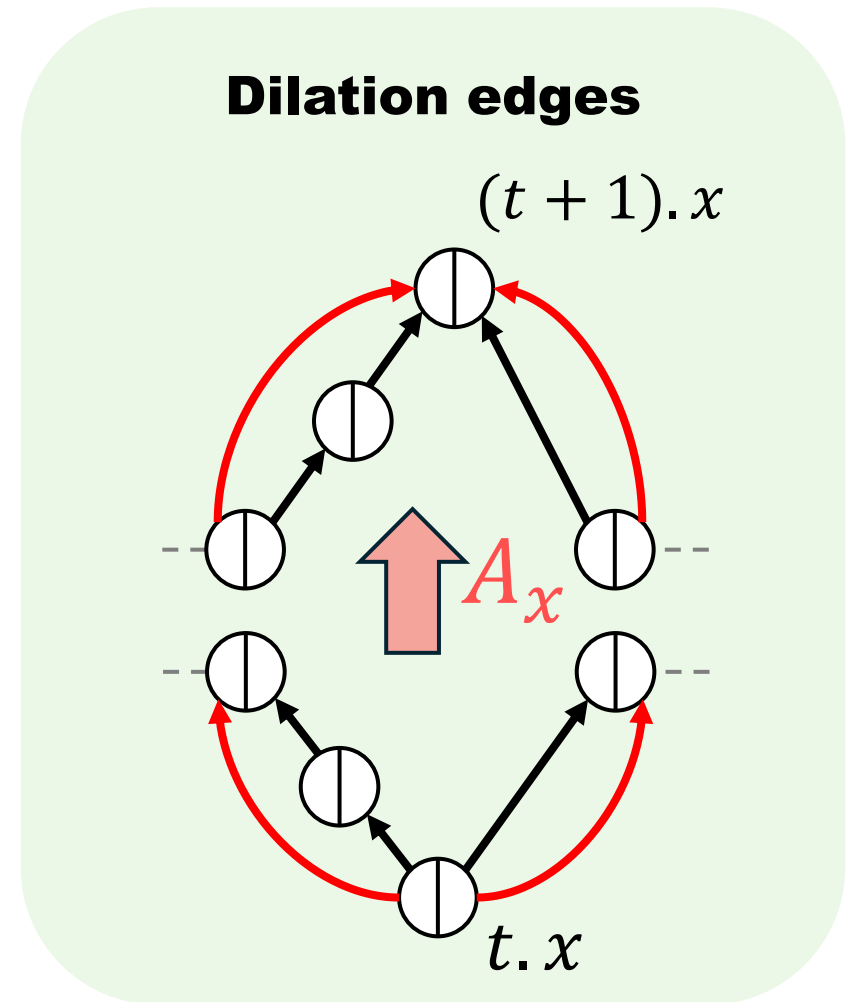
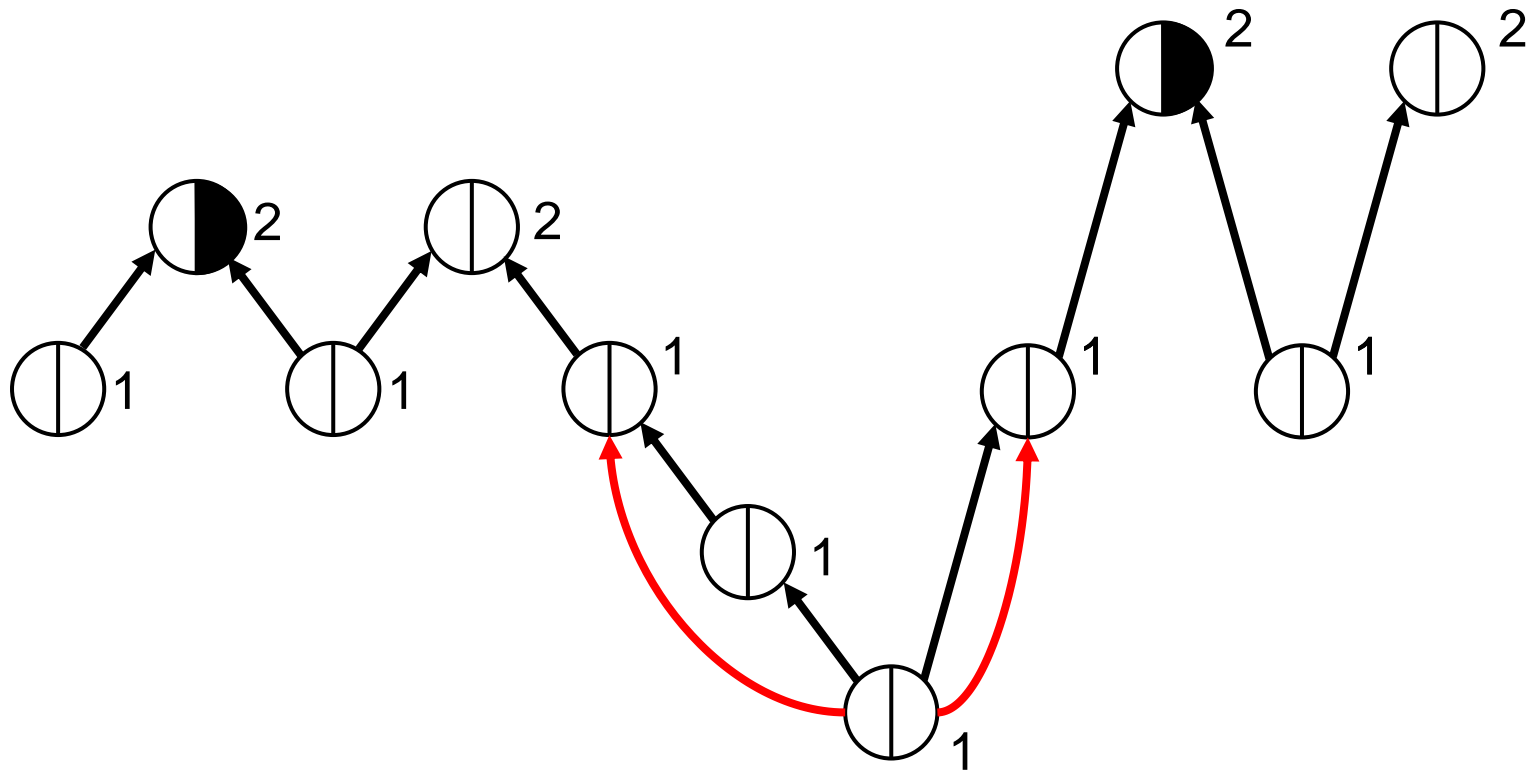
# Time dilation example



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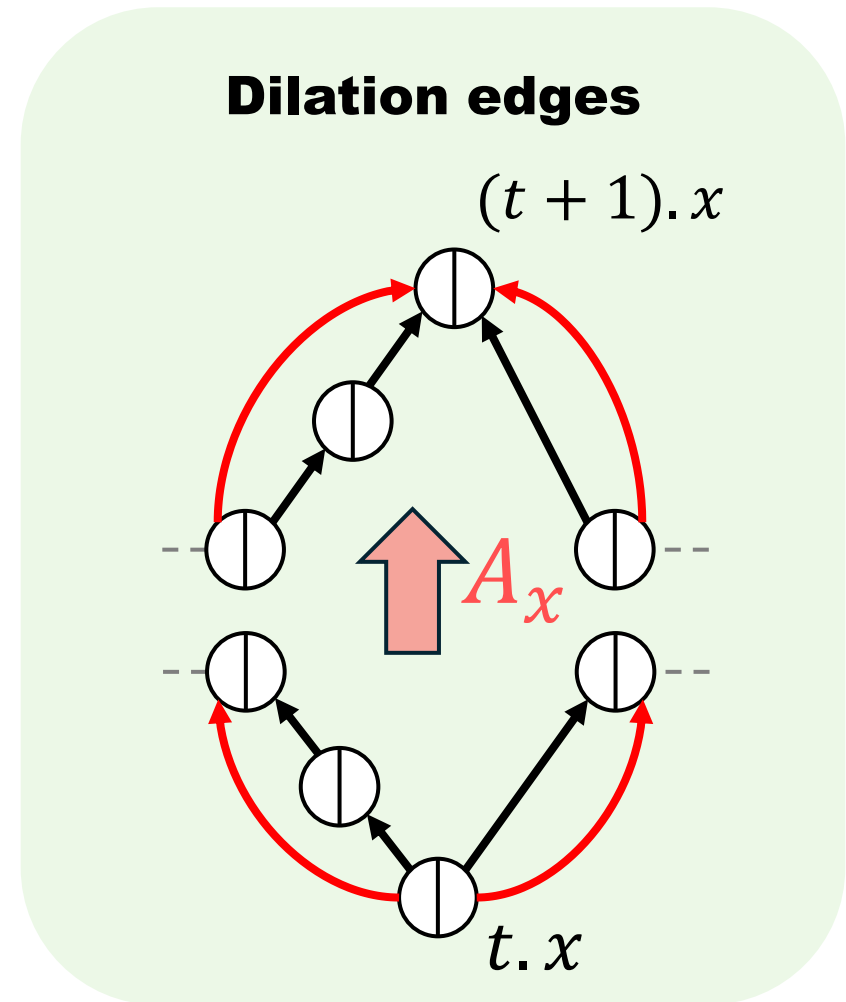
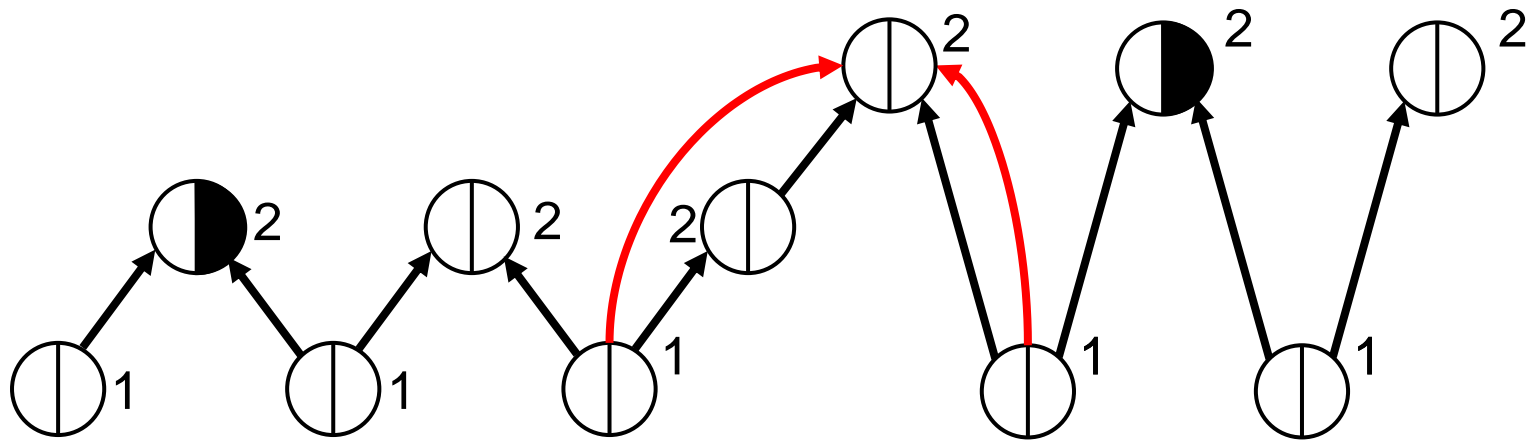


# Time dilation example

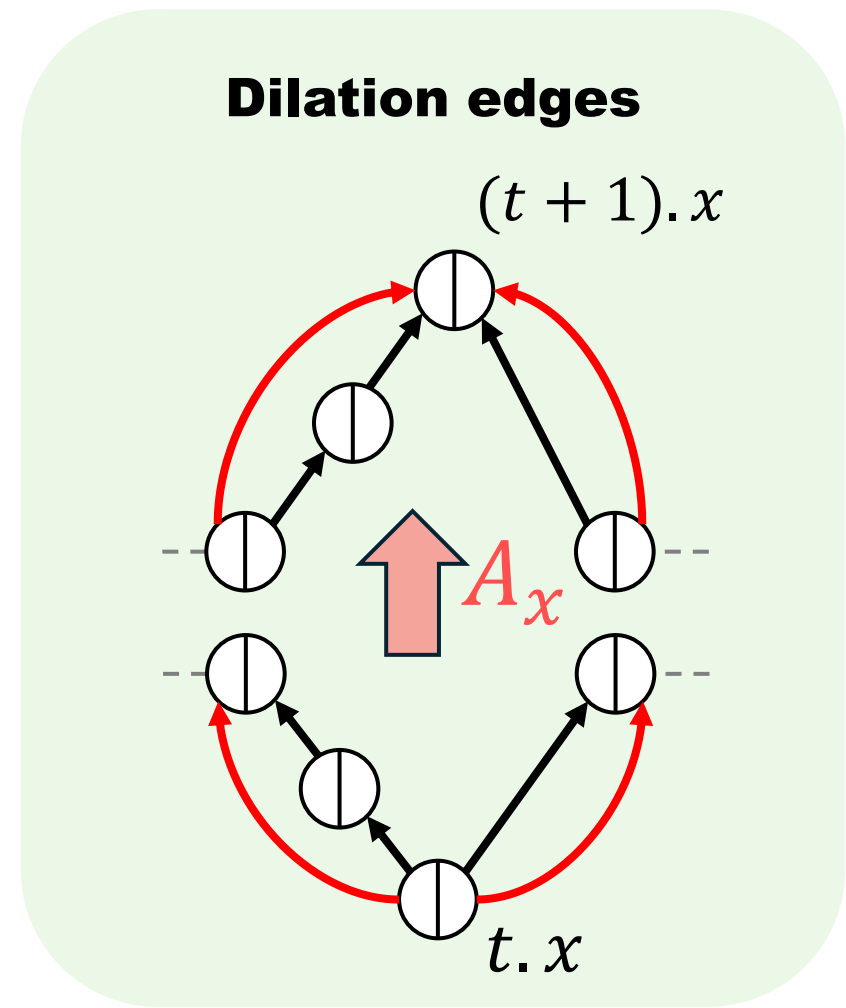
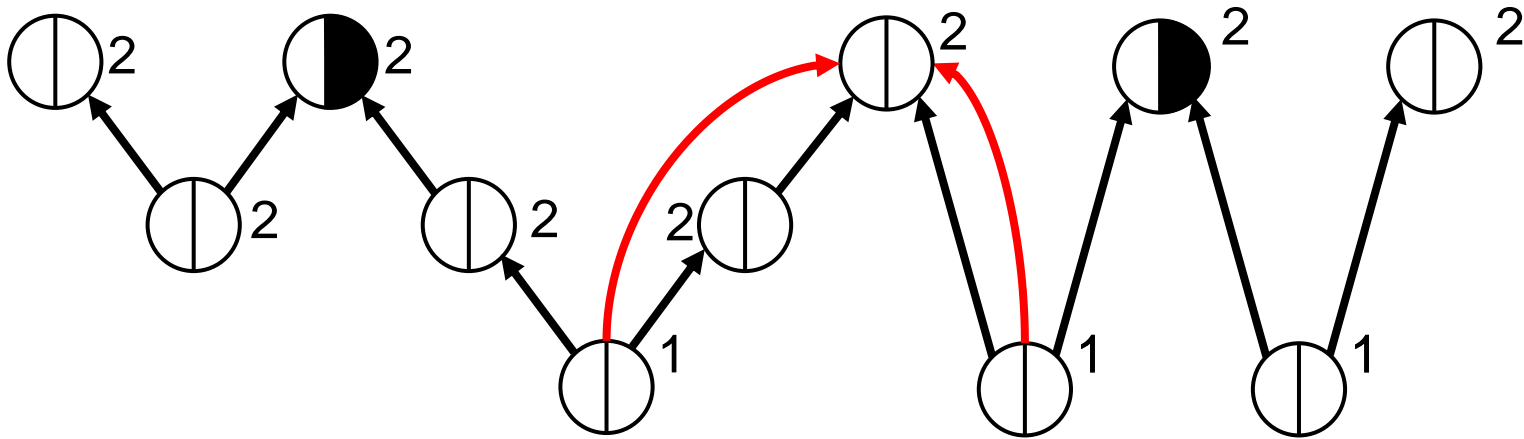




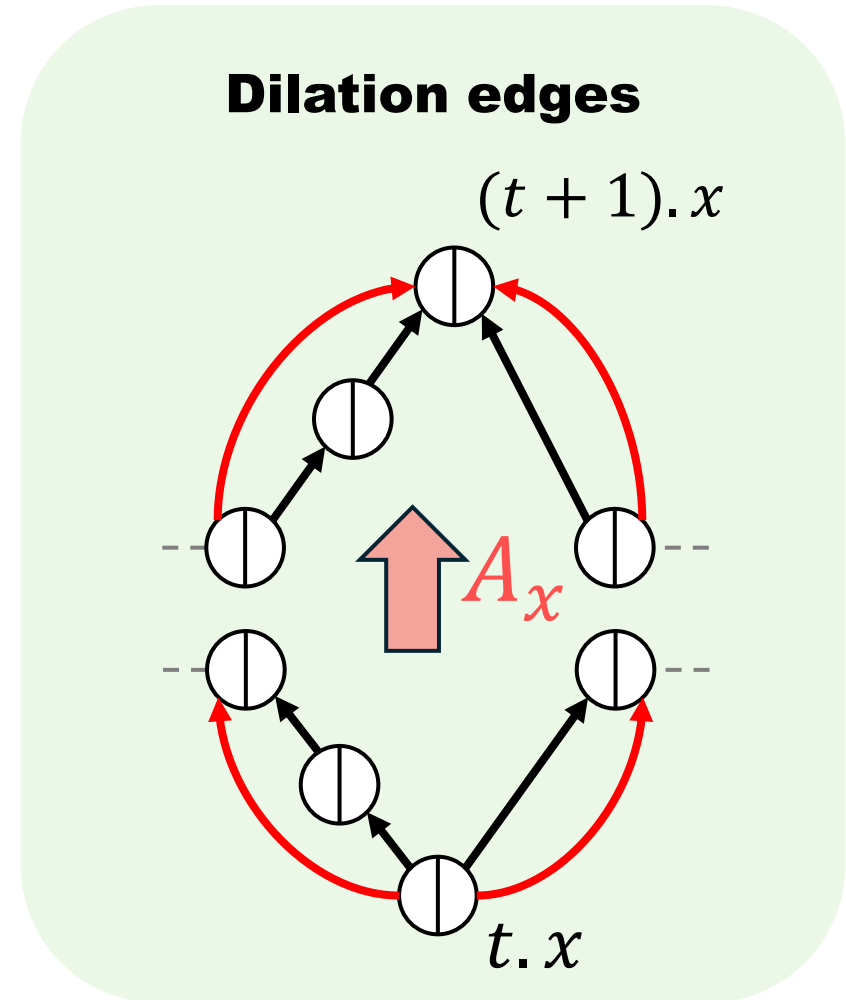
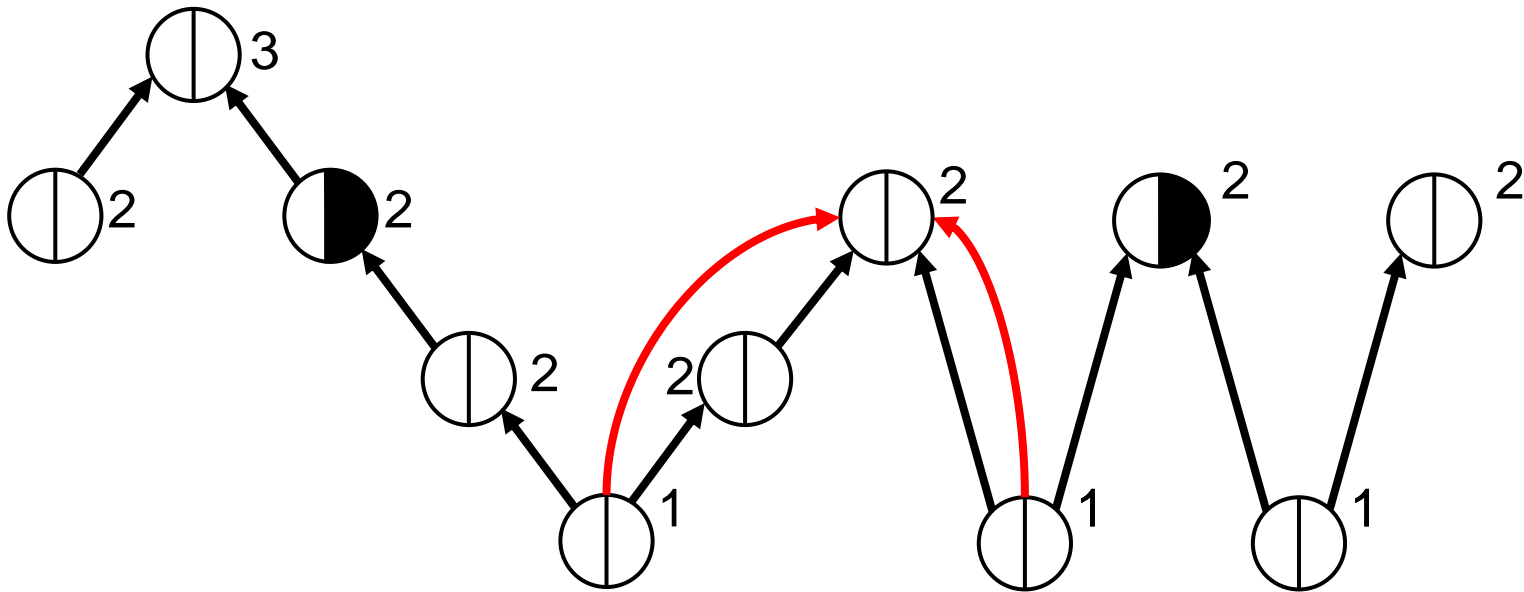
# Time dilation example



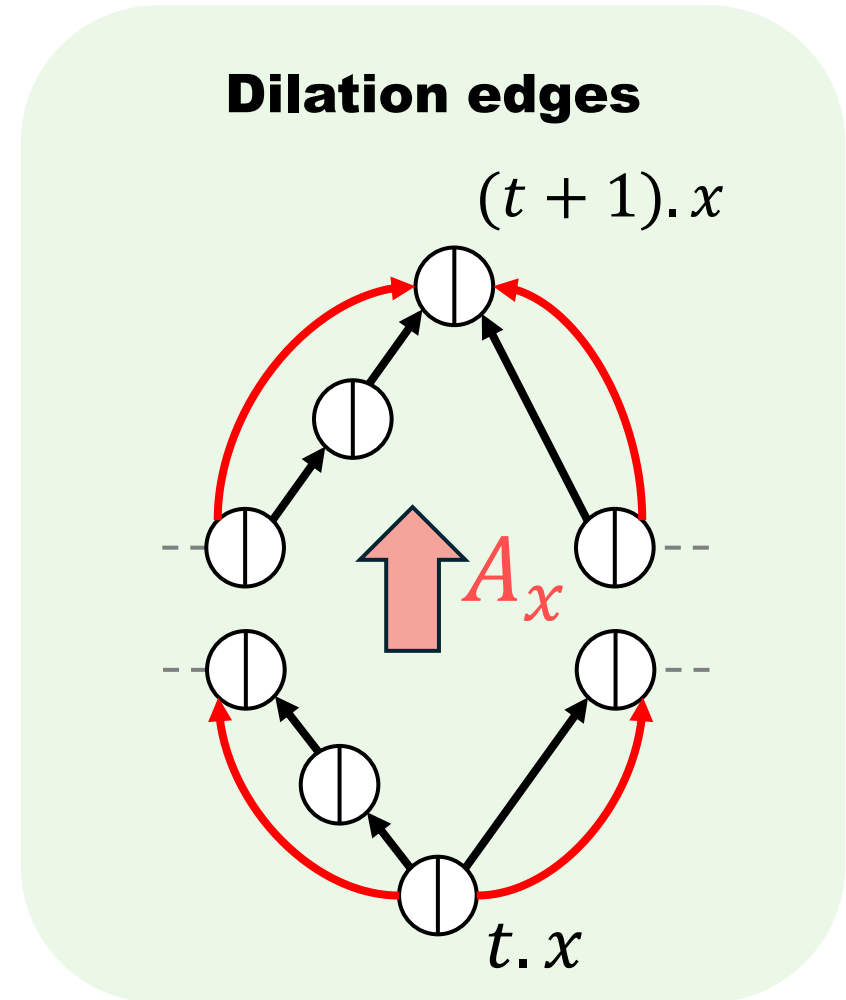
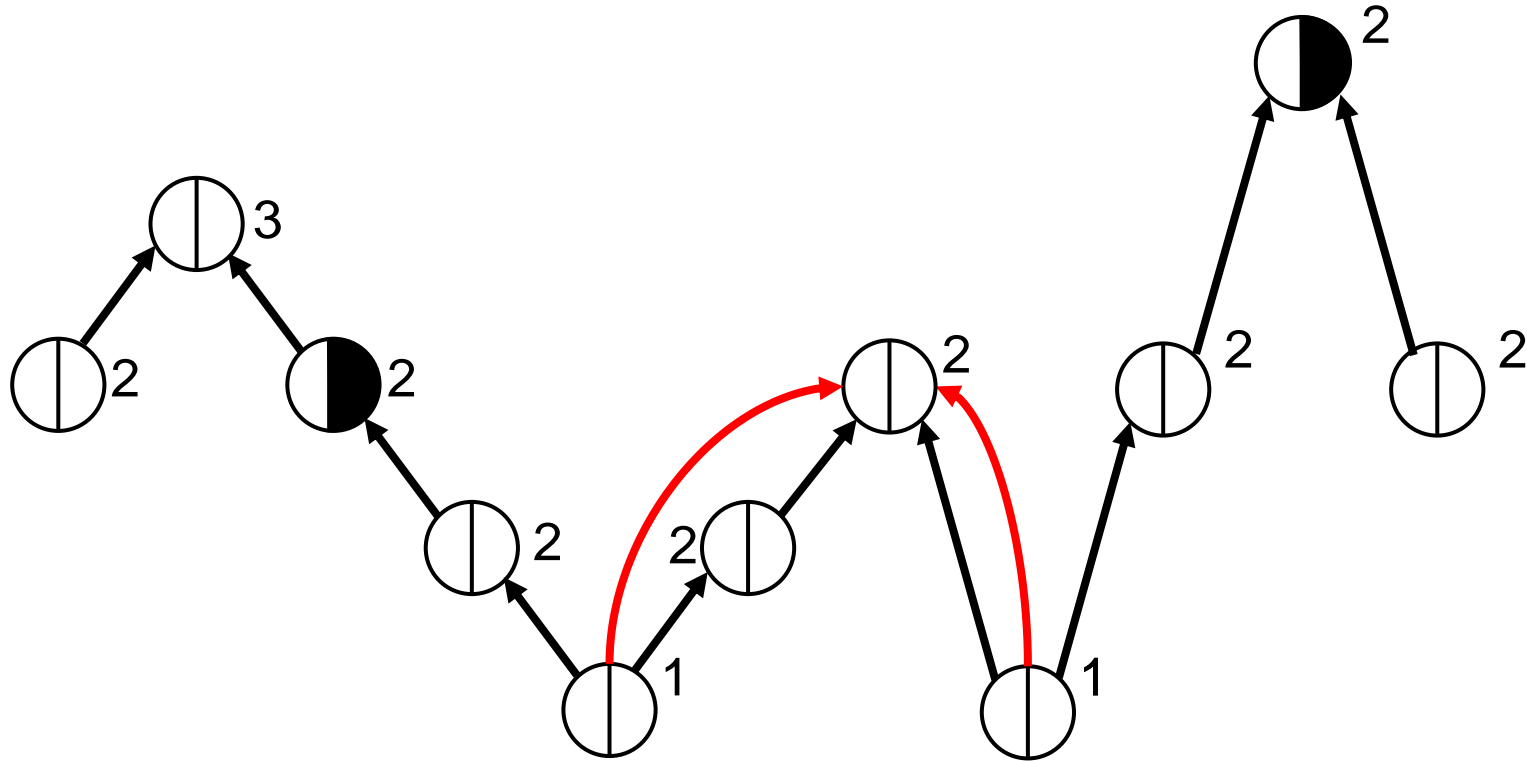
# Time dilation example



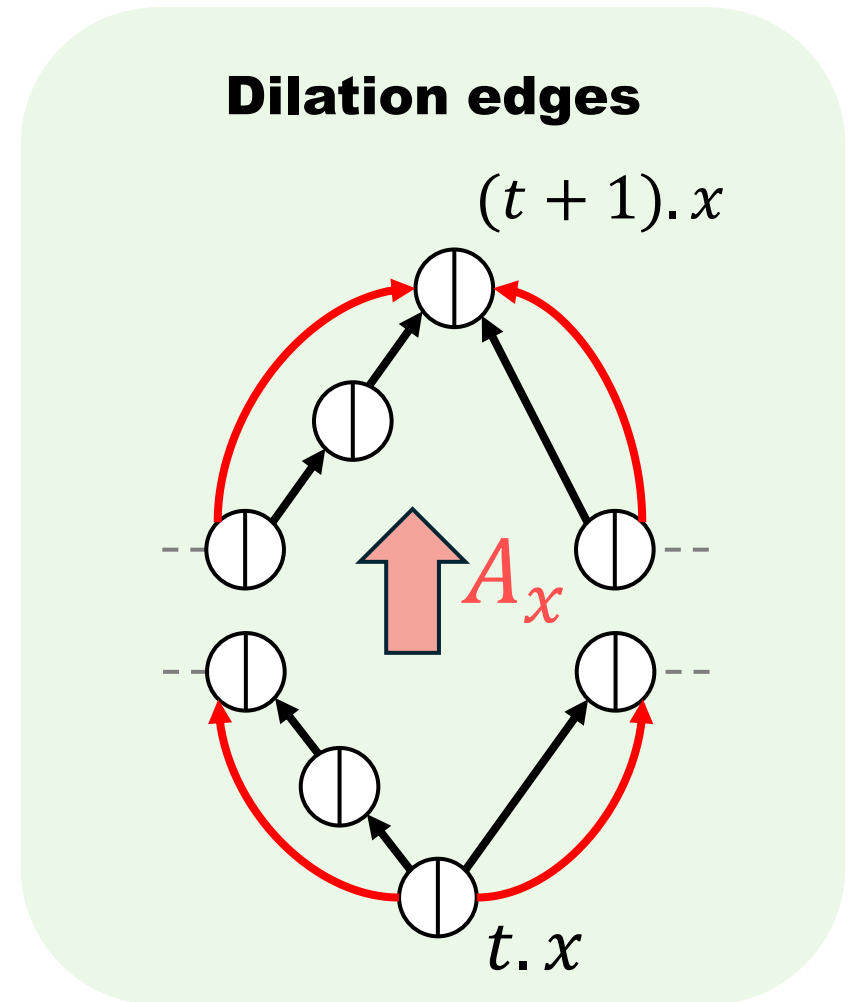
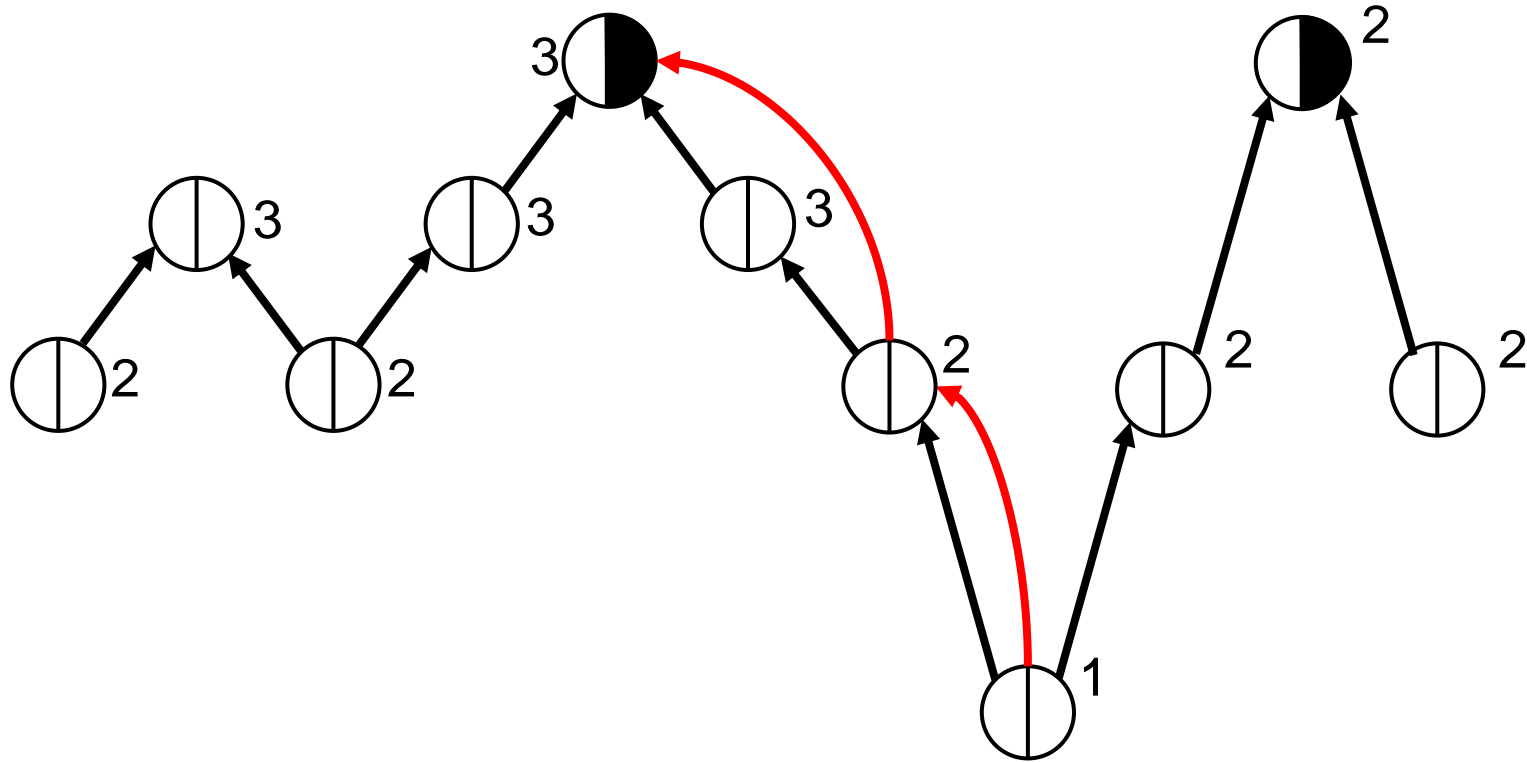
# Time dilation example



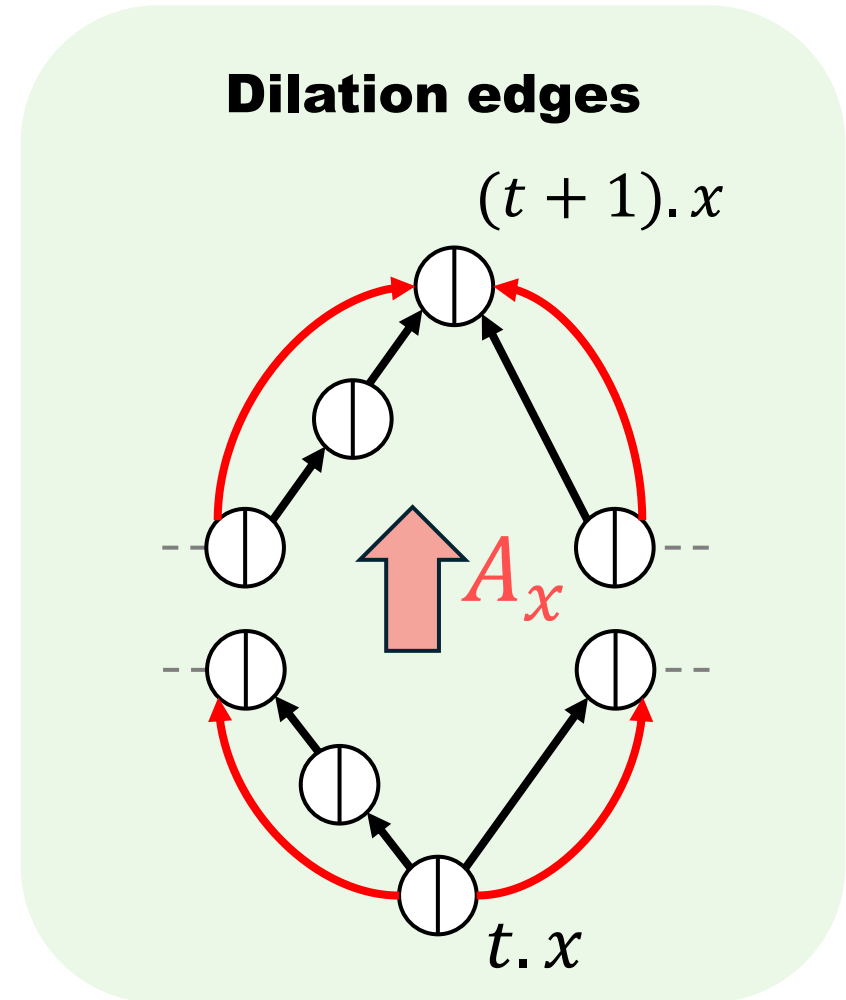
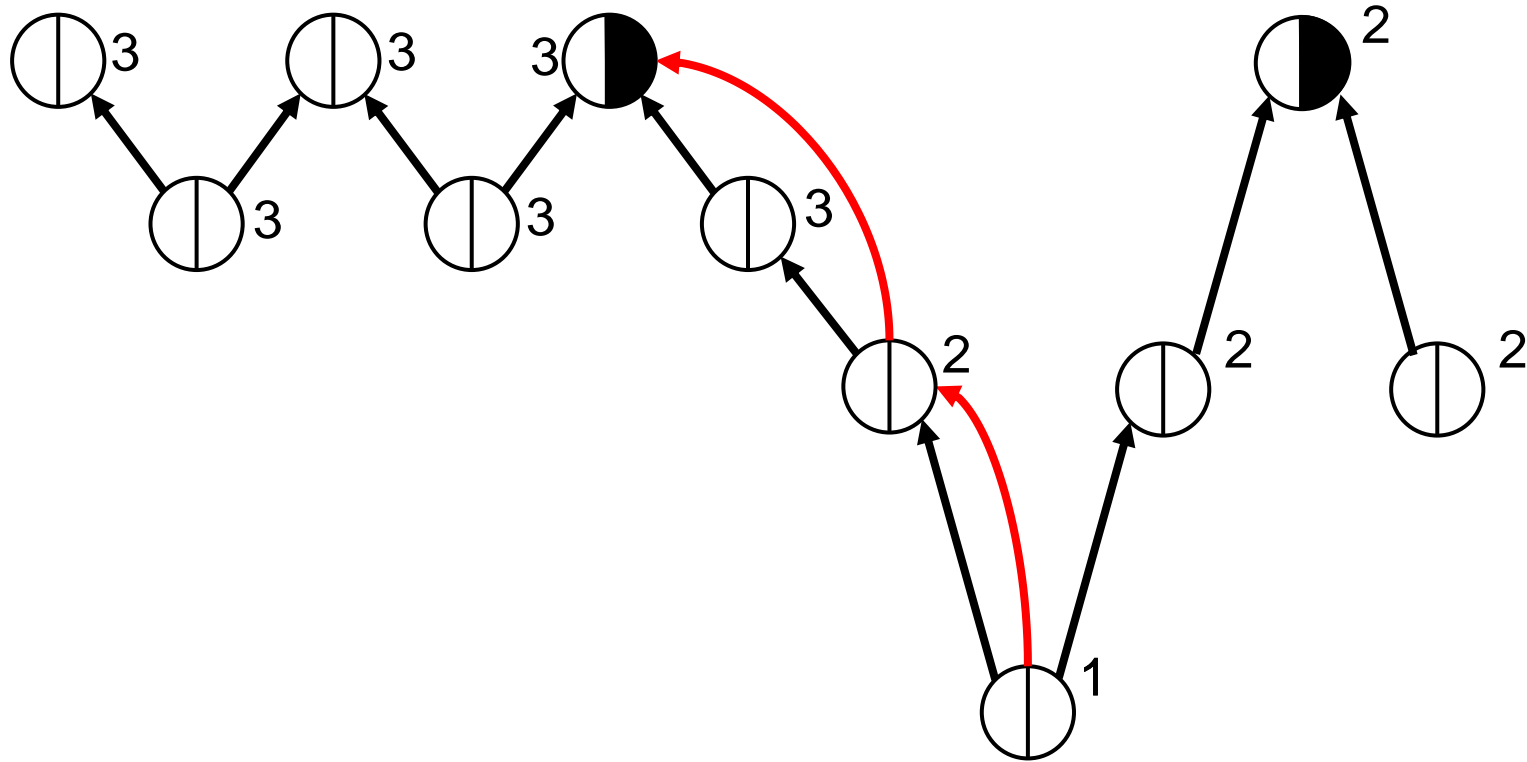
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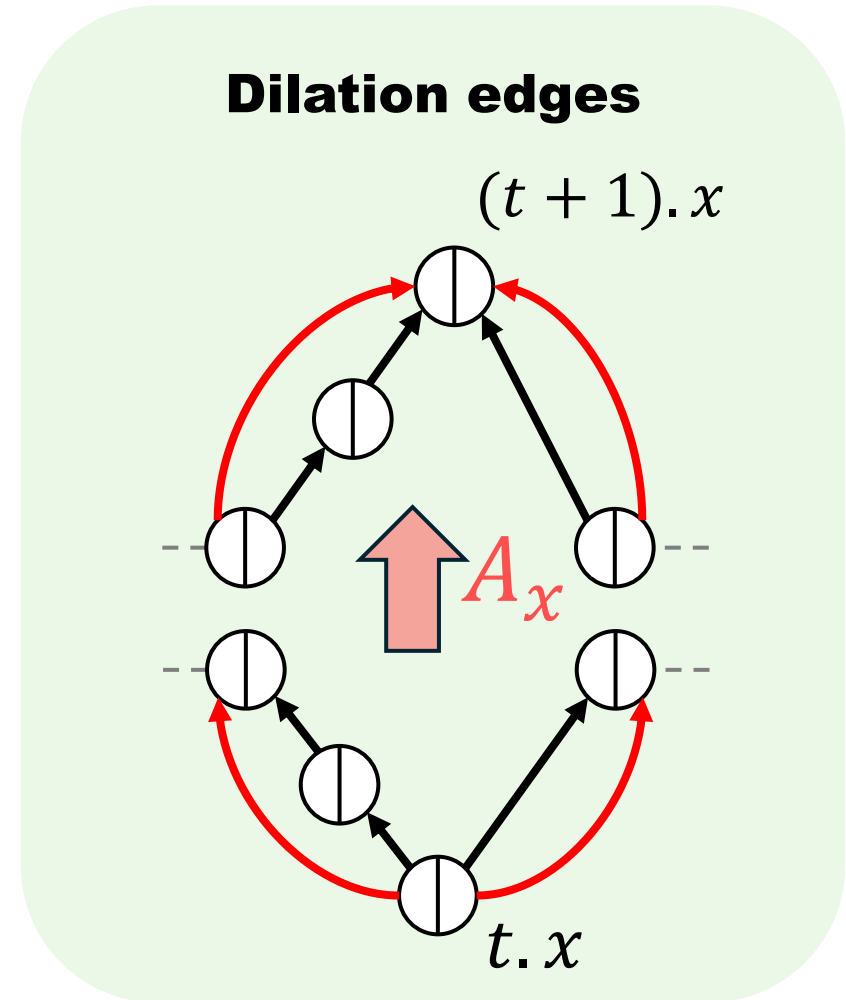
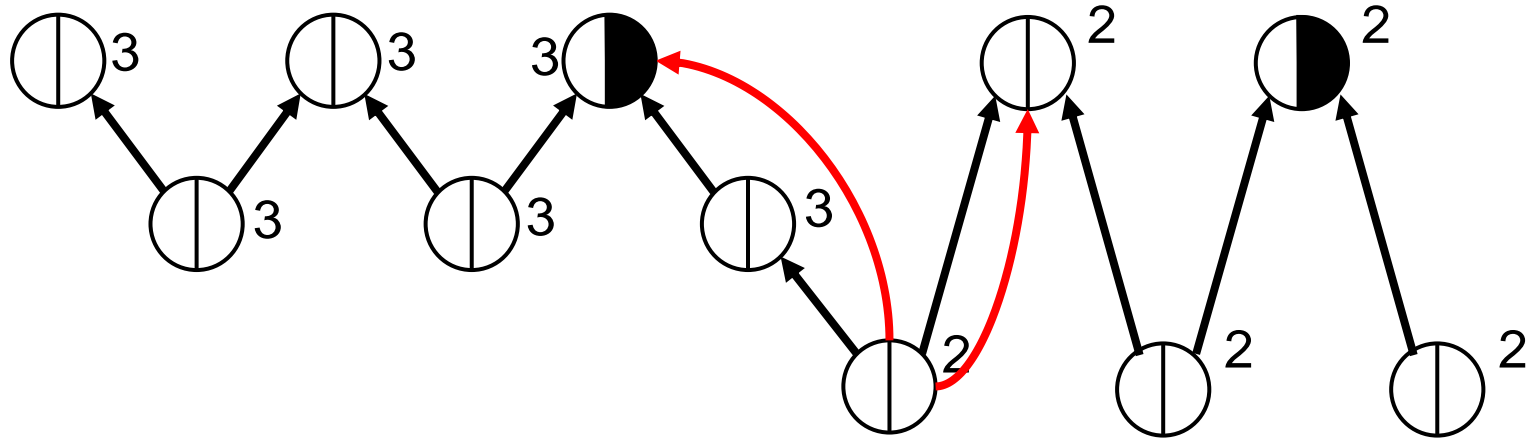
# Time dilation example



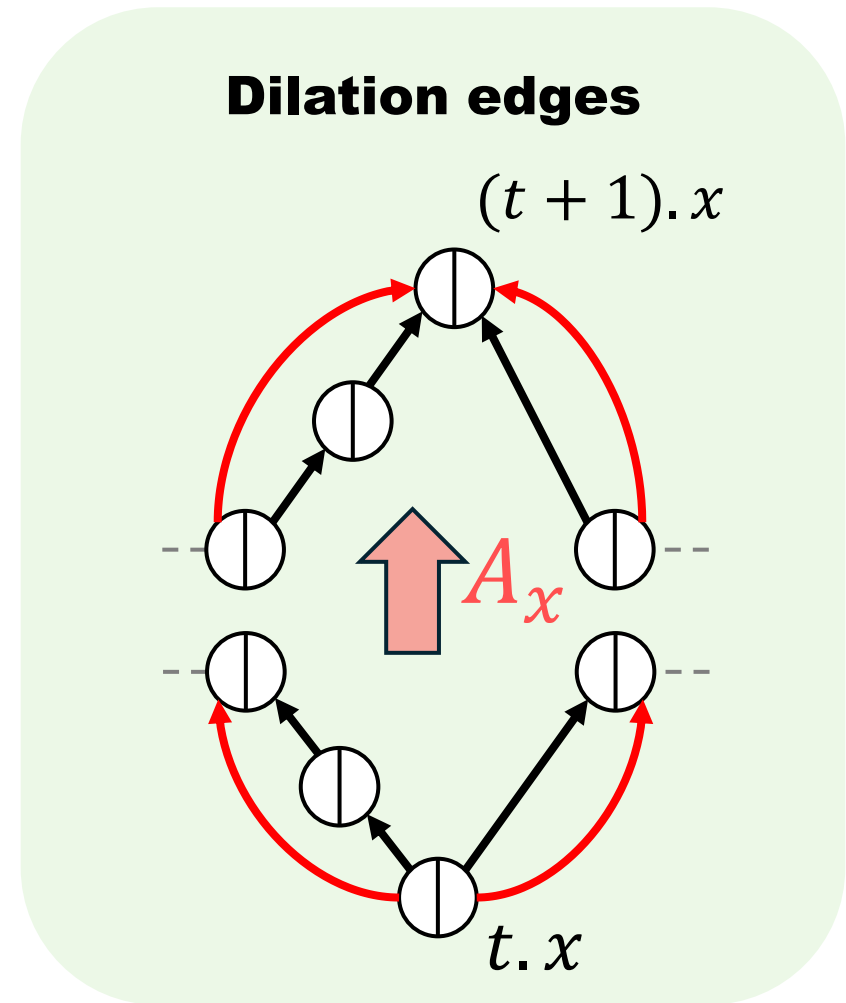
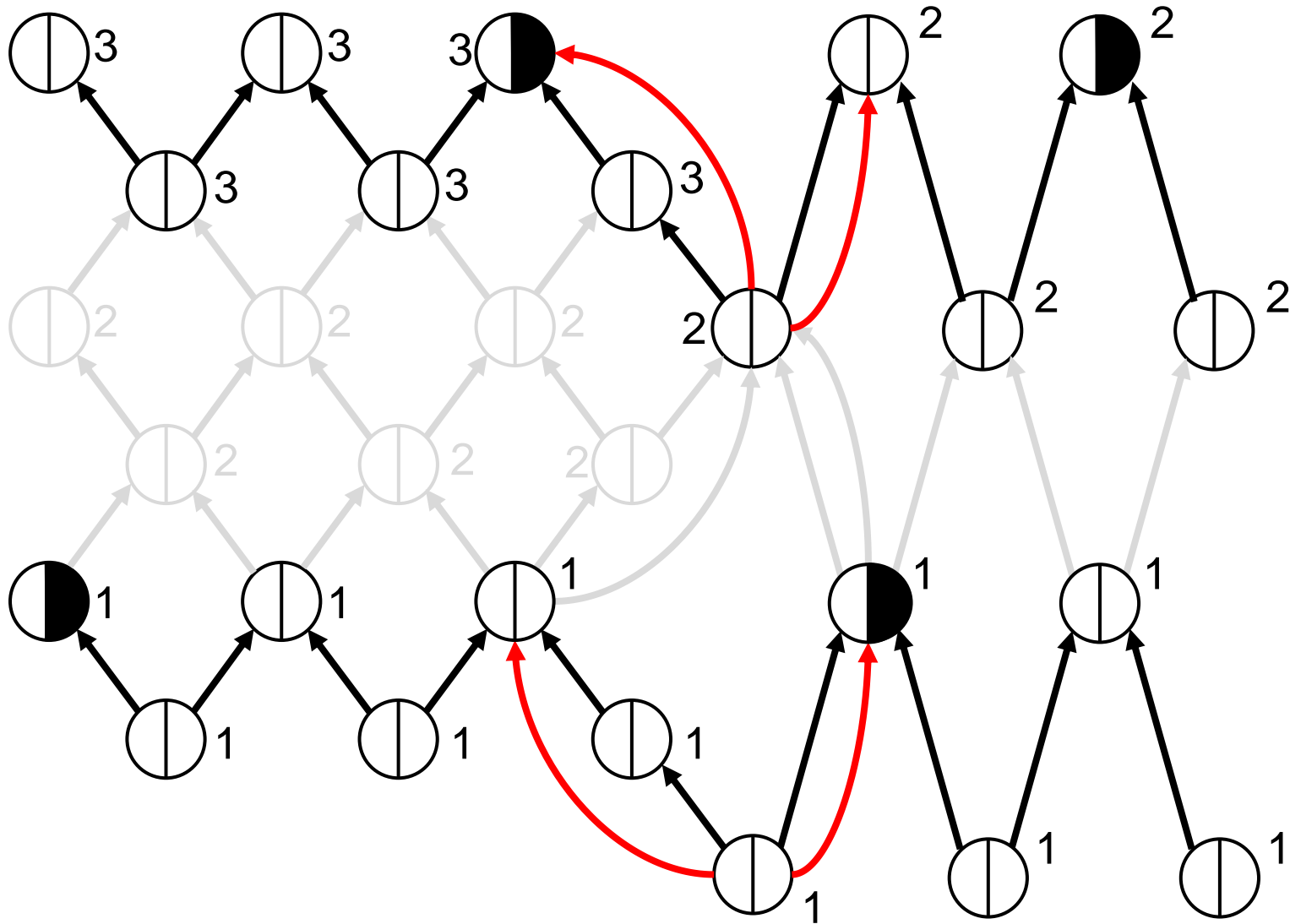
# Time dilation example



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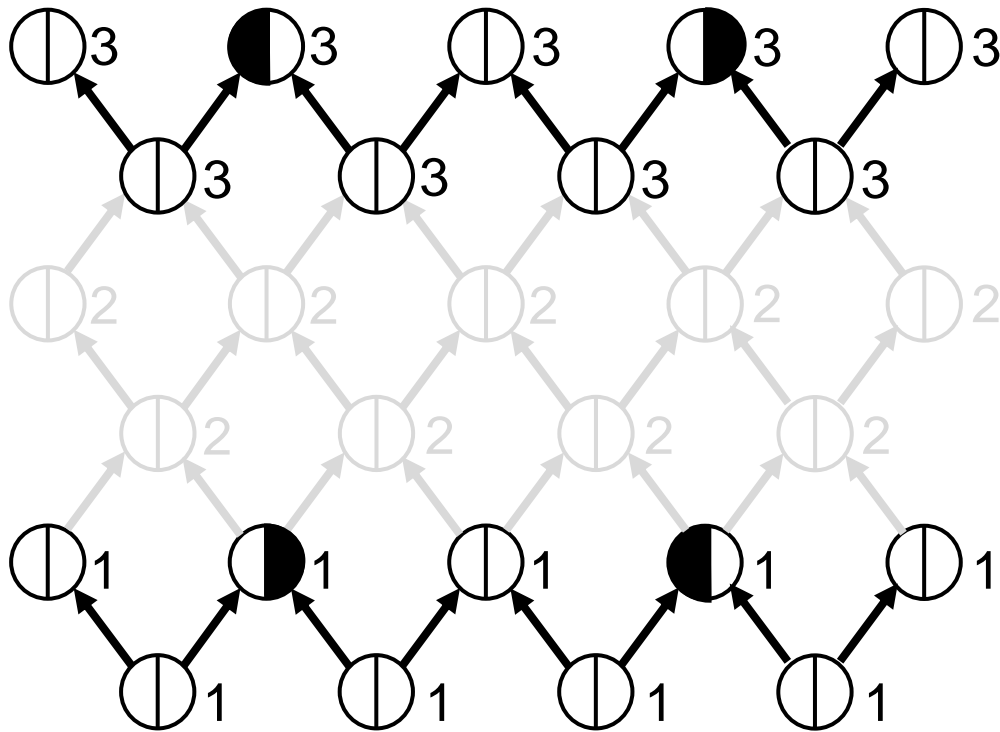
# Time dilation example



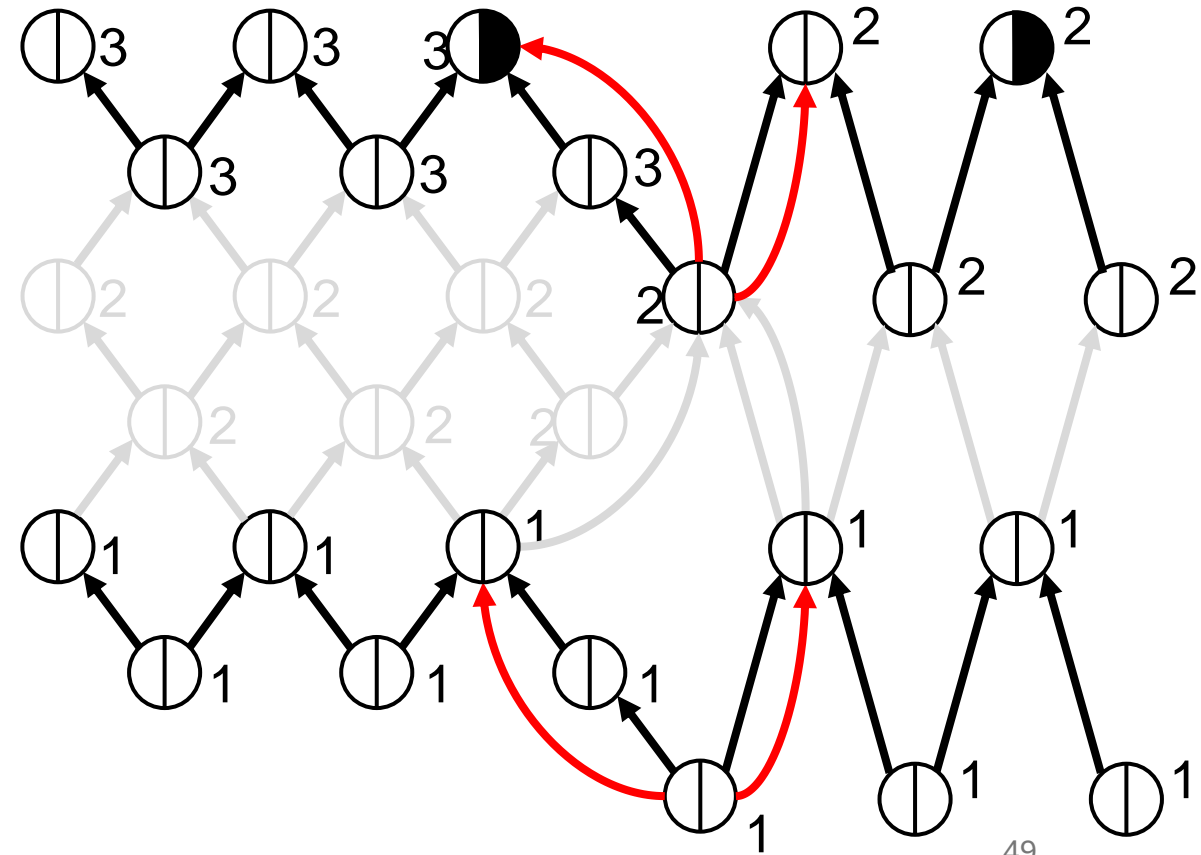


# Summary

Using graph rewriting we **can simulate synchronous** dynamical system ...

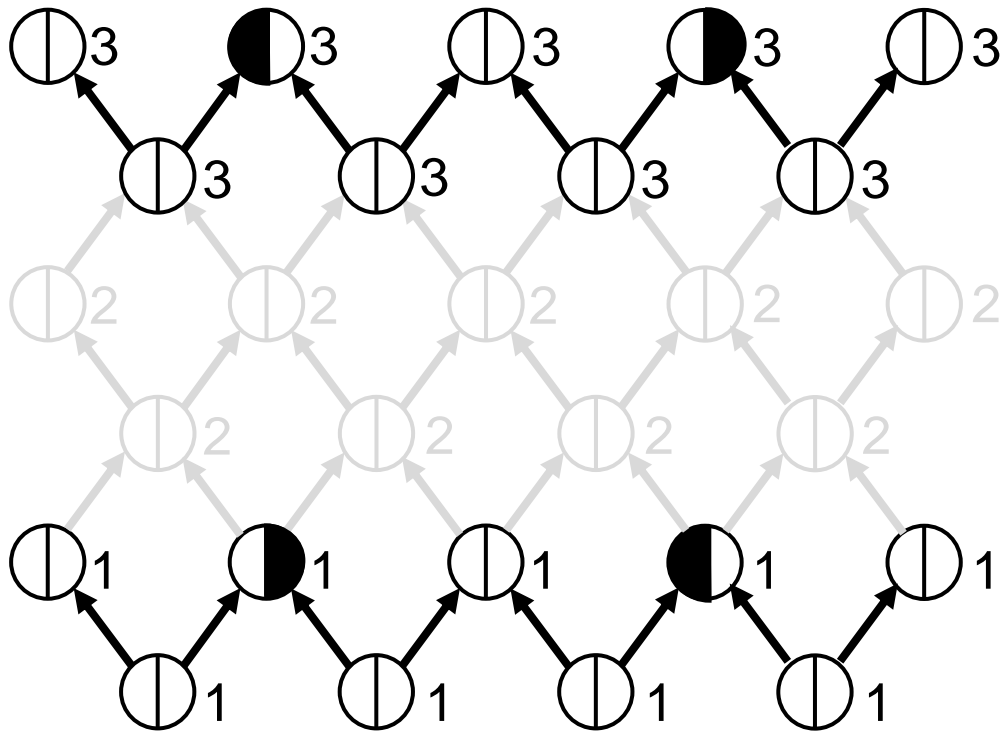


... but also represent some **intrinsically asynchronous** evolution.

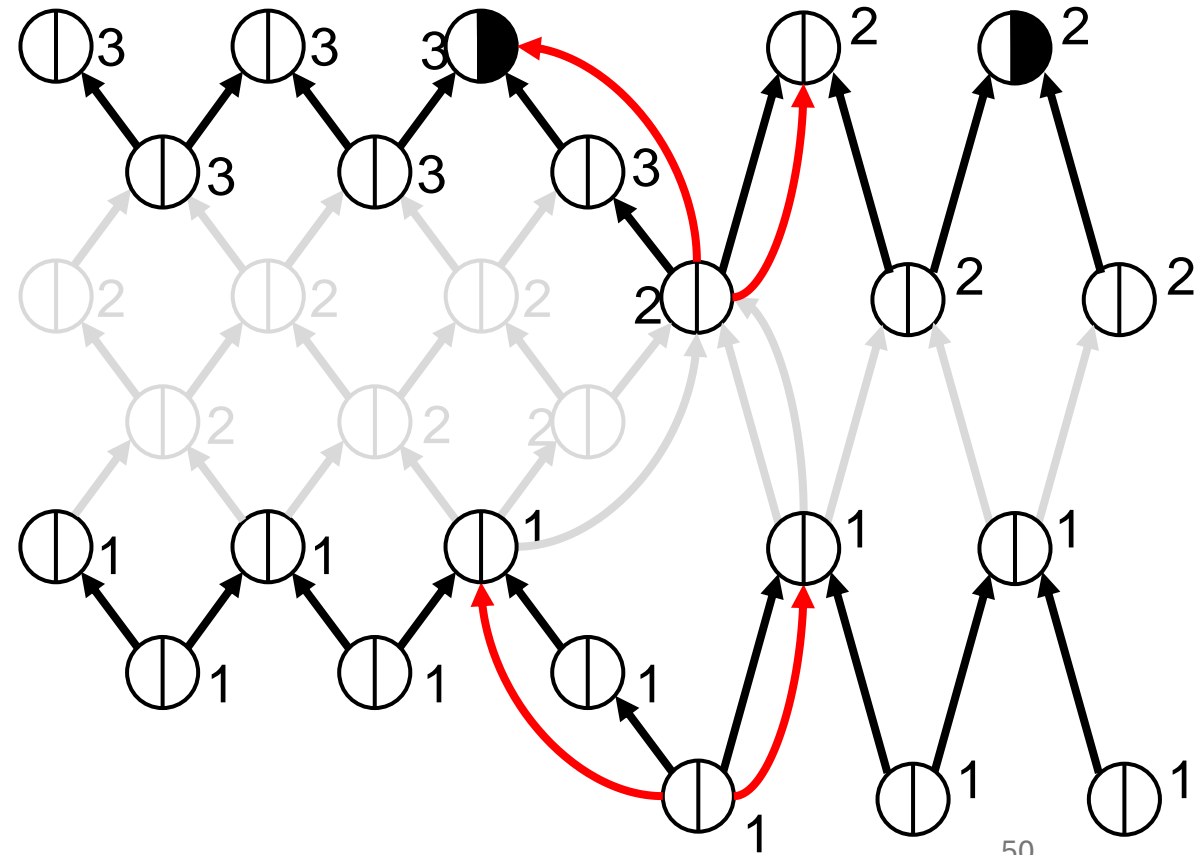


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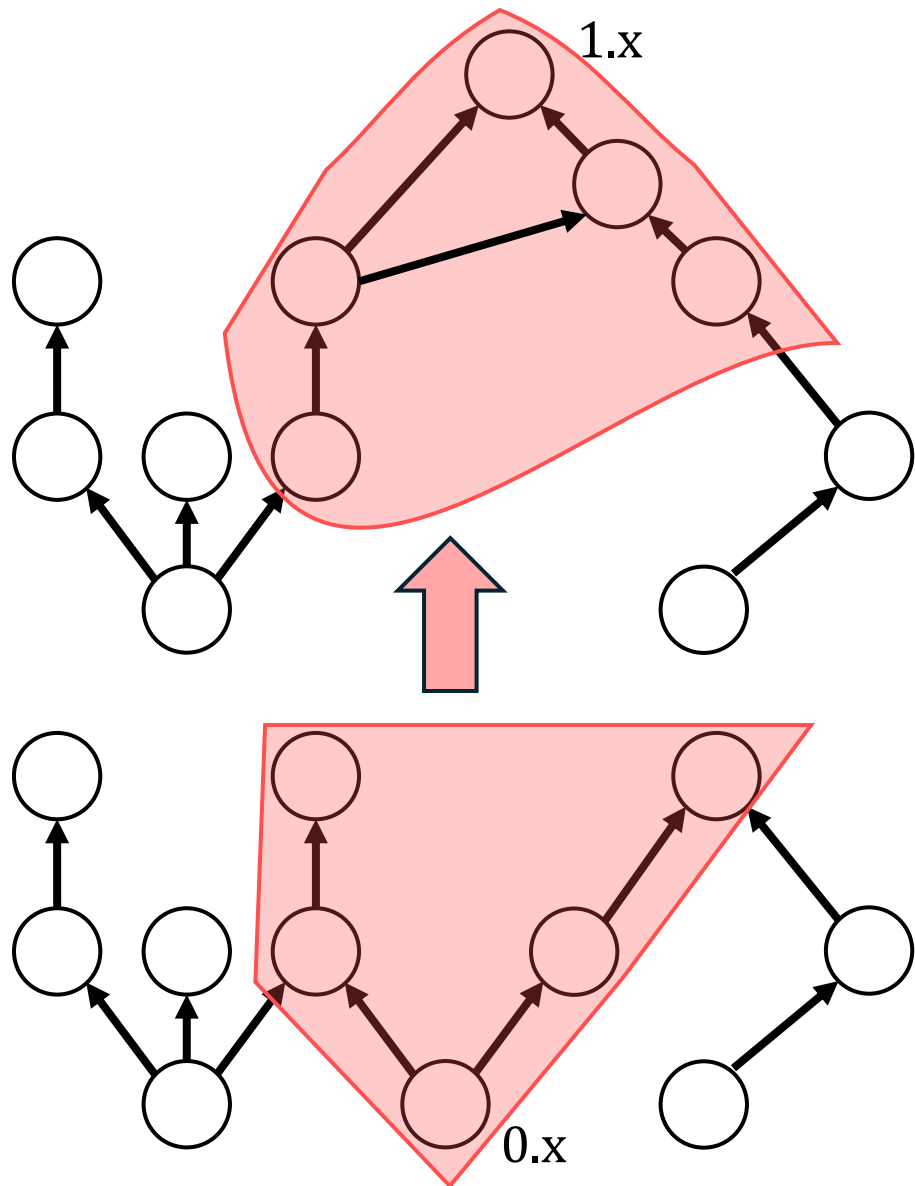
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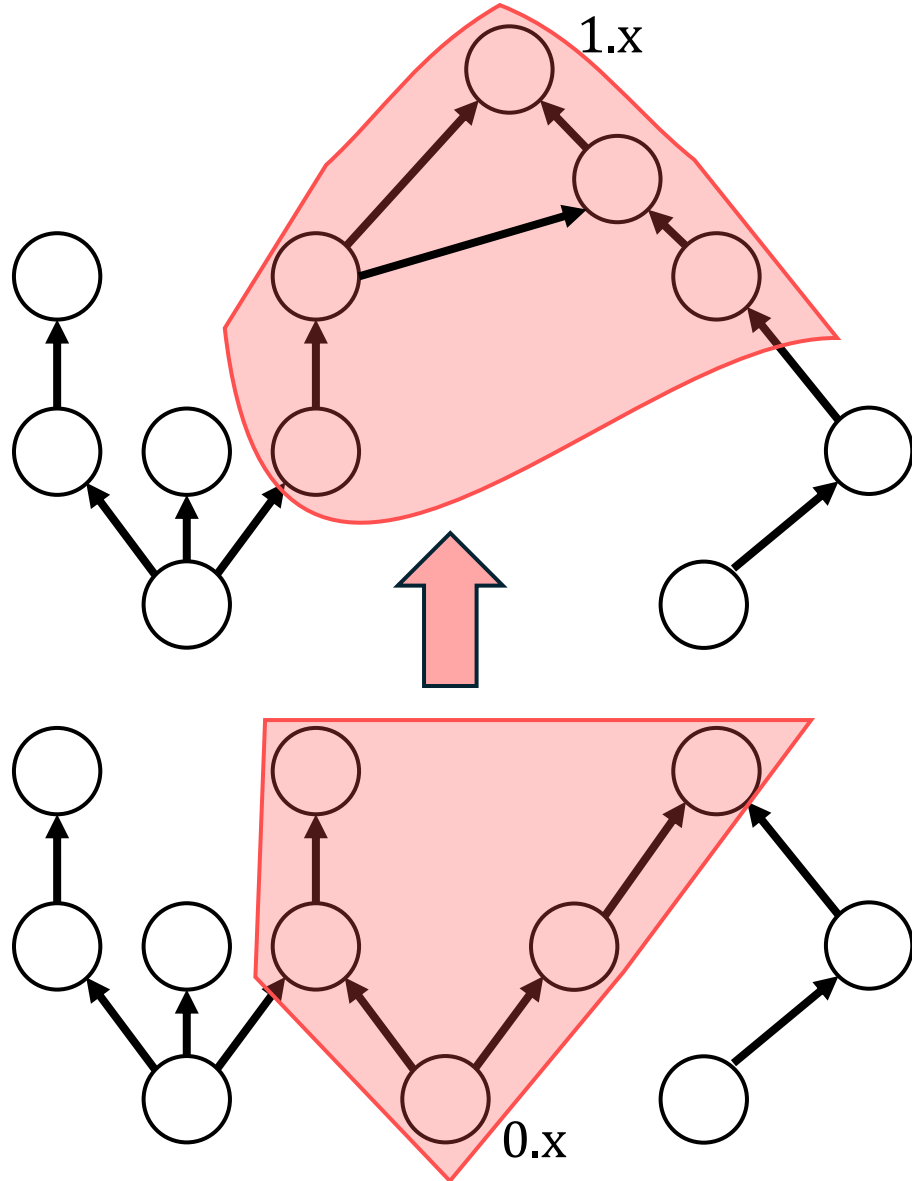
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# General framework



# General framework

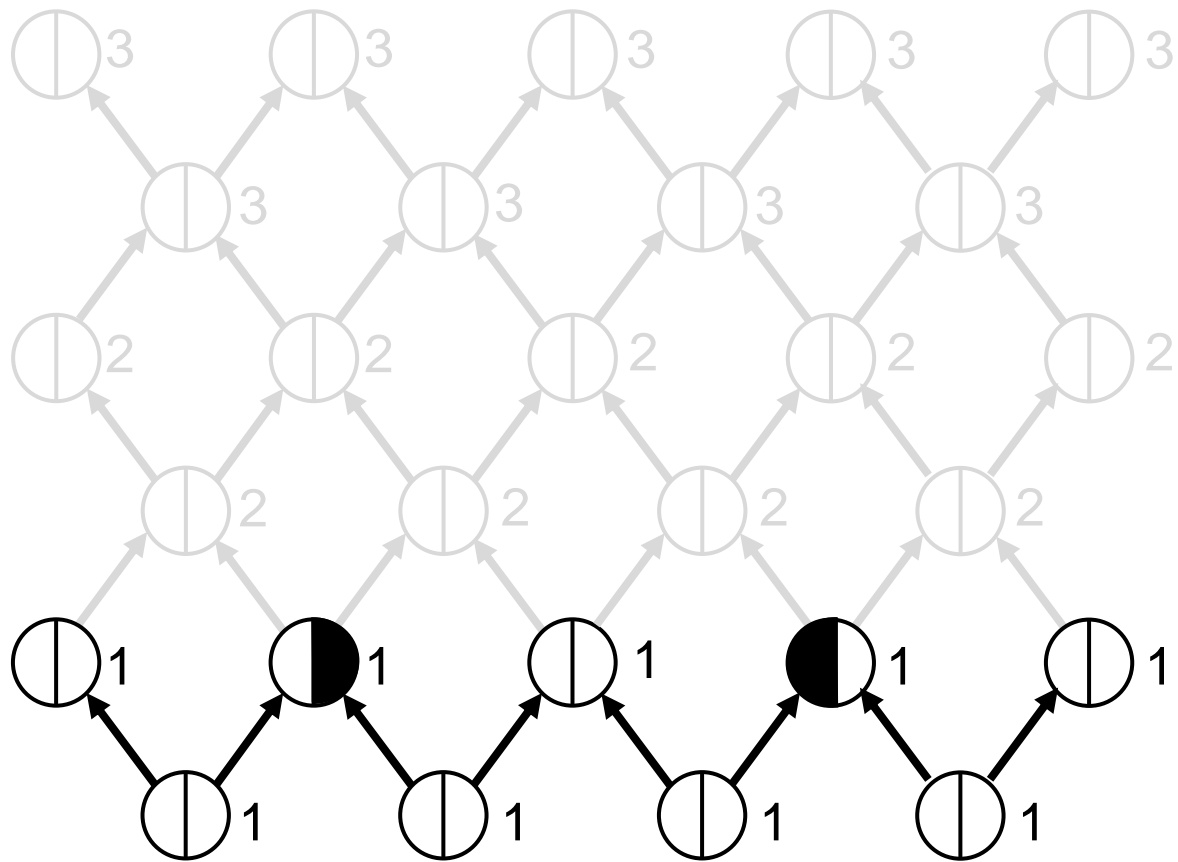


In general which local rewriting rules are physical ?

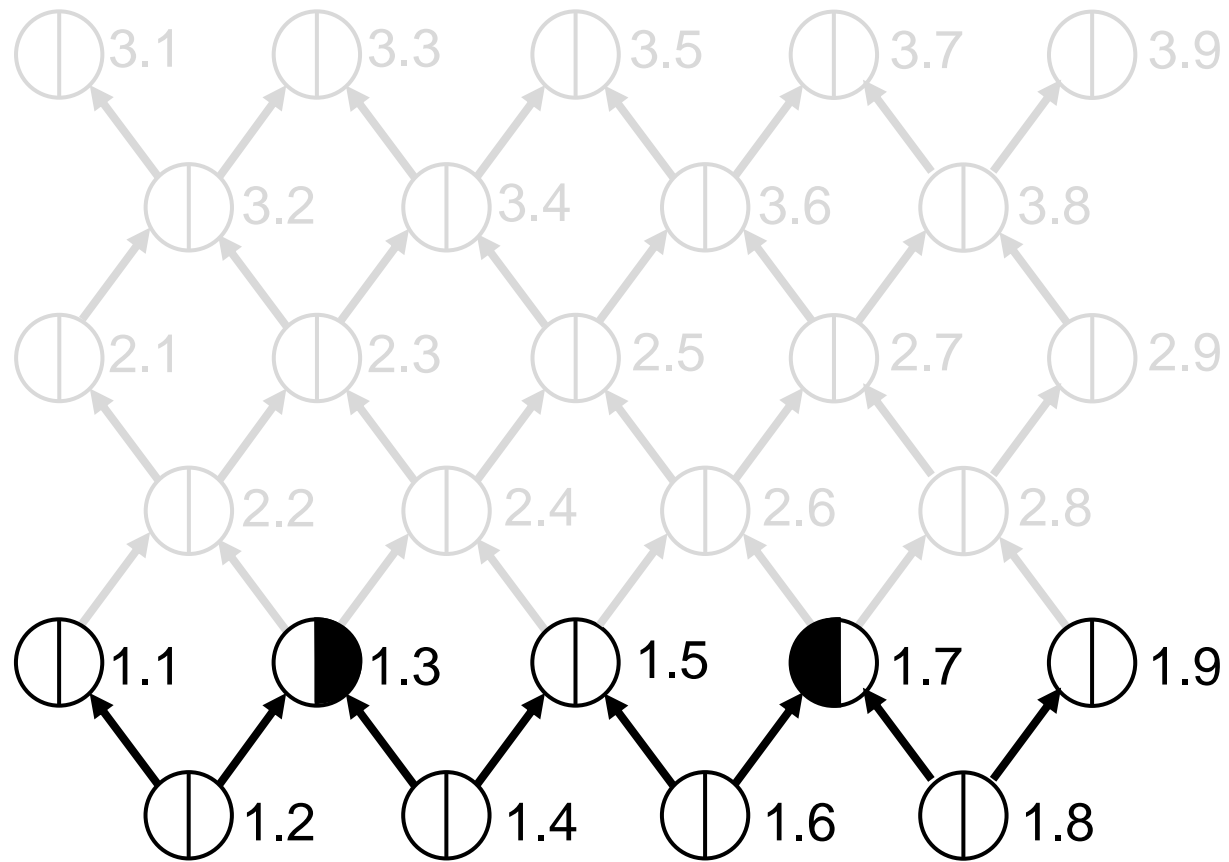
- **Determinism**
- **Reversibility**



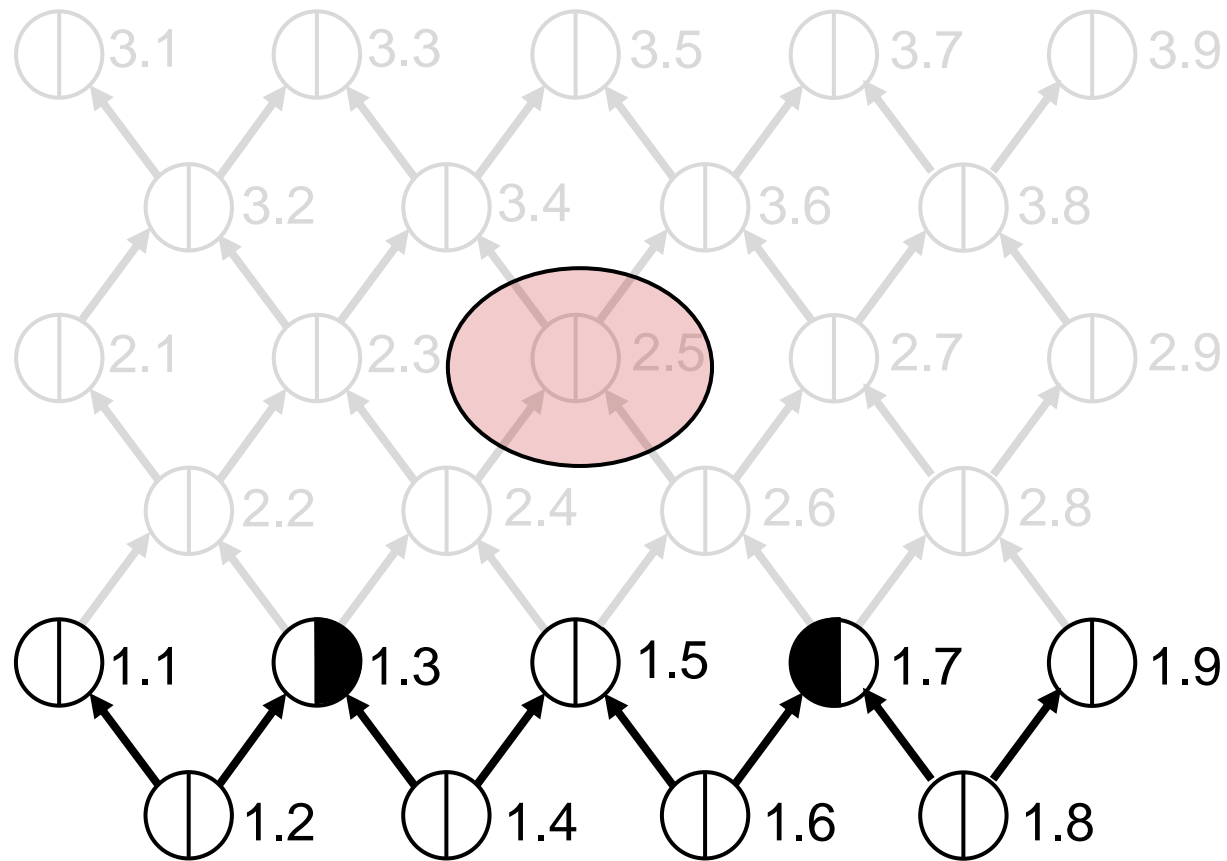
# A first attempt at defining determinism



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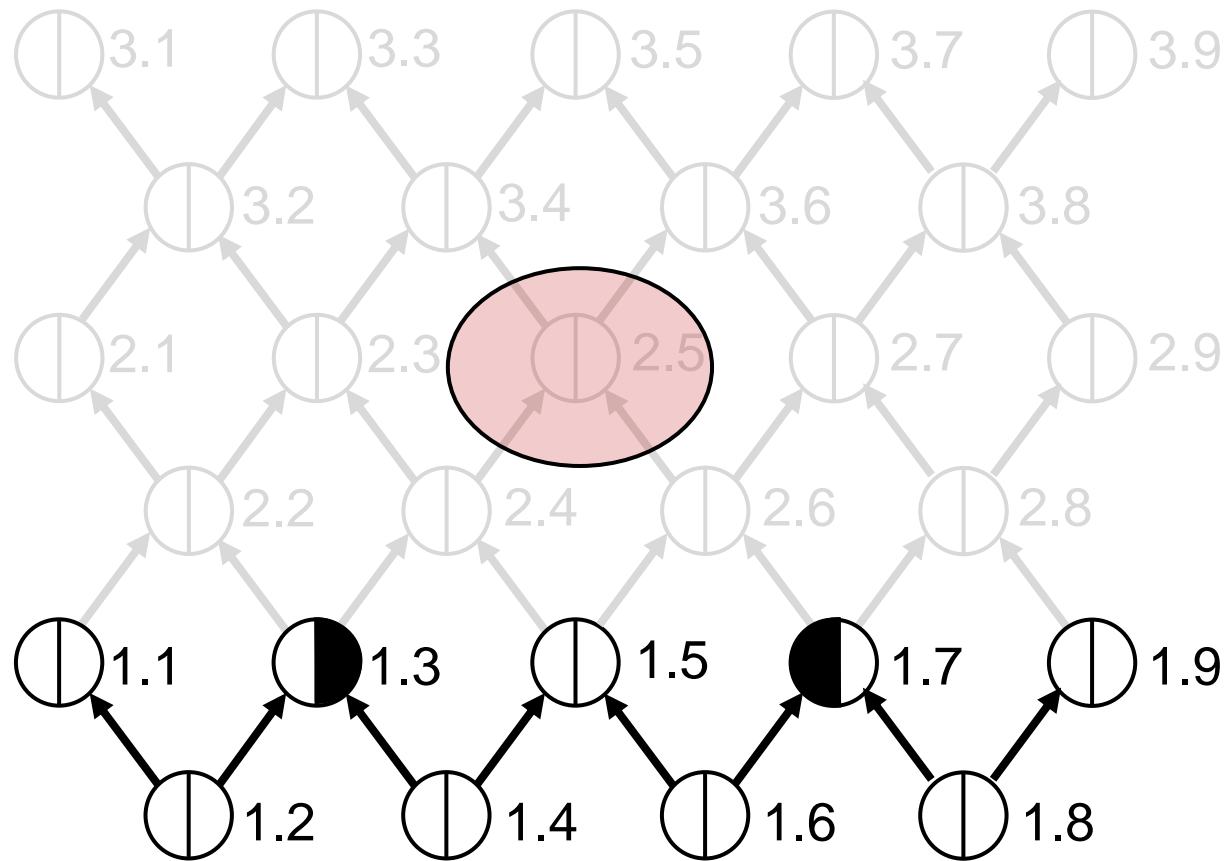
# A first attempt at defining determinism



## Determinism

The **state** of 2.5 is **always the same**. It does not depend on the rewriting strategy.

# A first attempt at defining determinism



## ~~Determinism~~

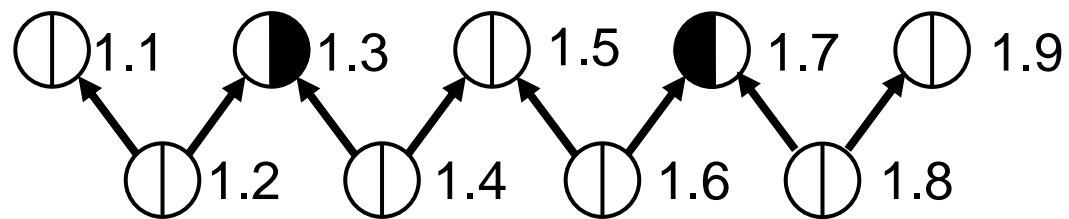
~~The state of 2.5 is always the same. It does not depend on the rewriting strategy.~~

It does depend on the local shape of the cut !



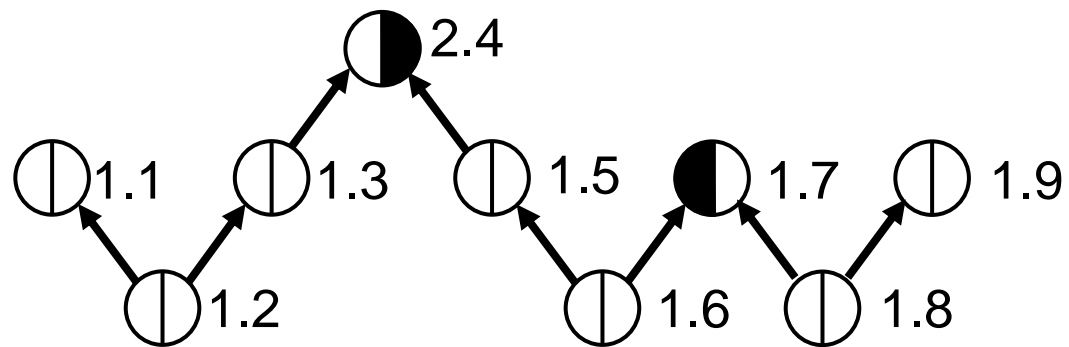
# States depend on the cut

$G$



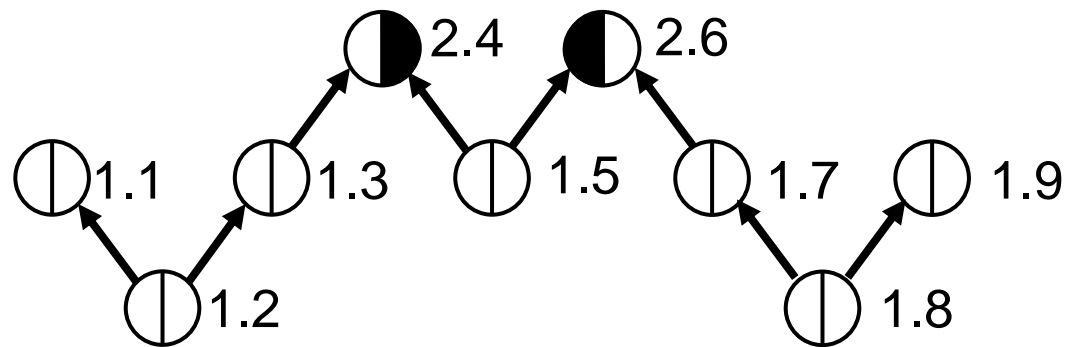
# States depend on the cut

$A_4G$



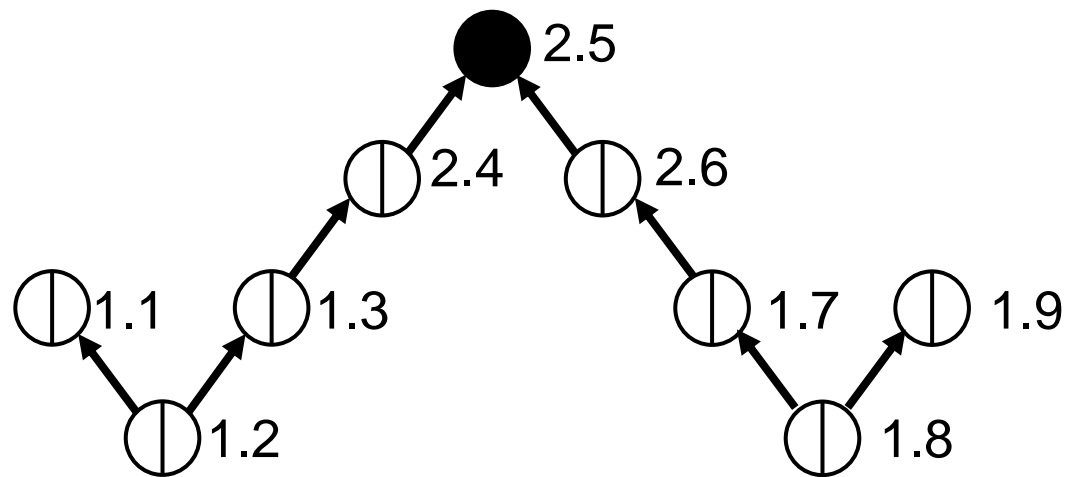
# States depend on the cut

$A_6 A_4 G$



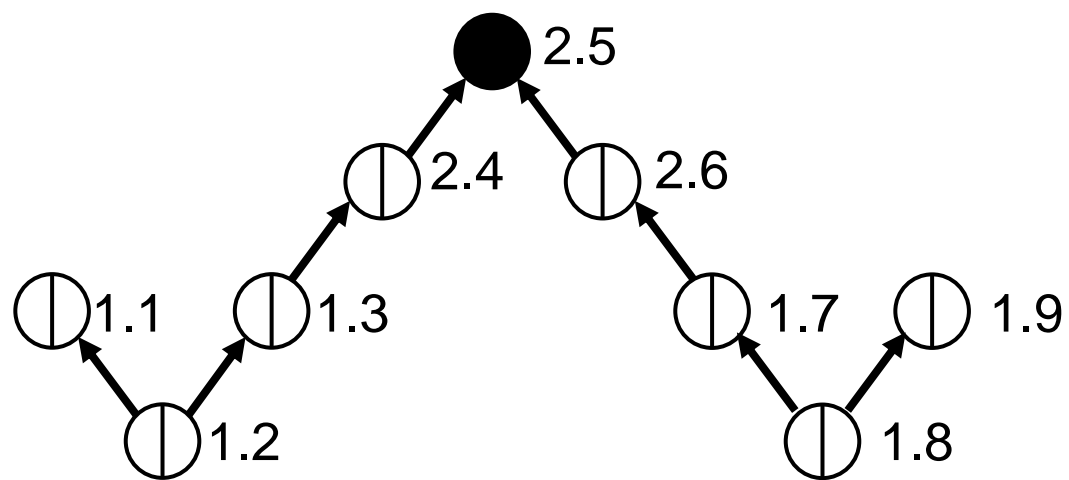
# States depend on the cut

$A_5 A_6 A_4 G$

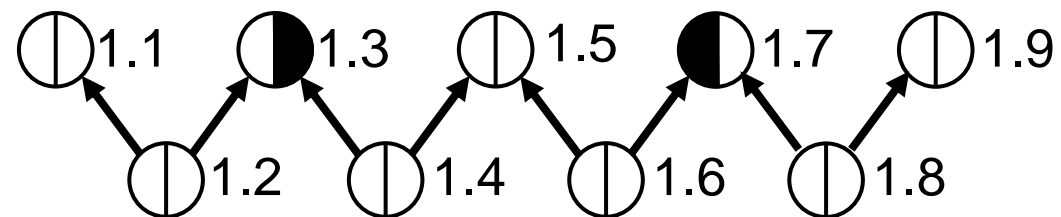


# States depend on the cut

$A_5 A_6 A_4 G$

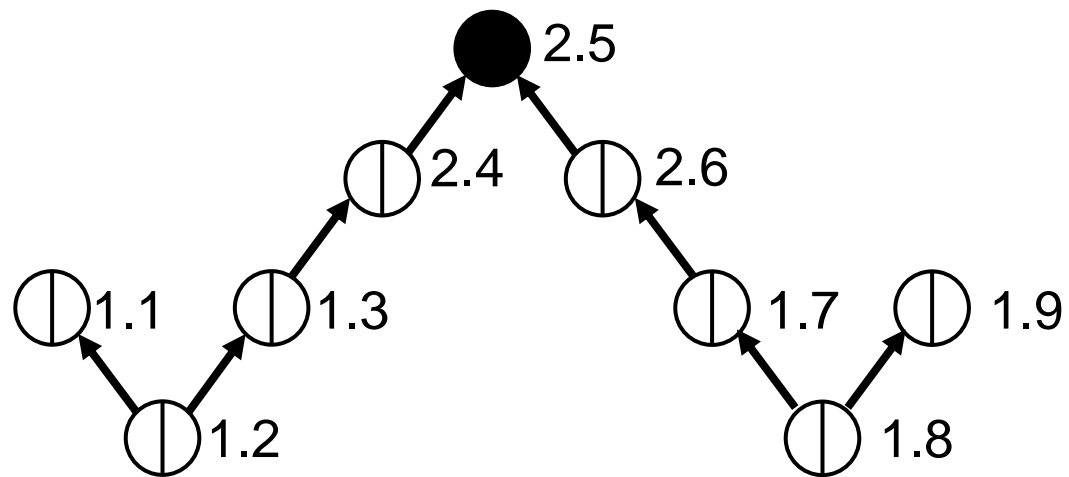


$G$

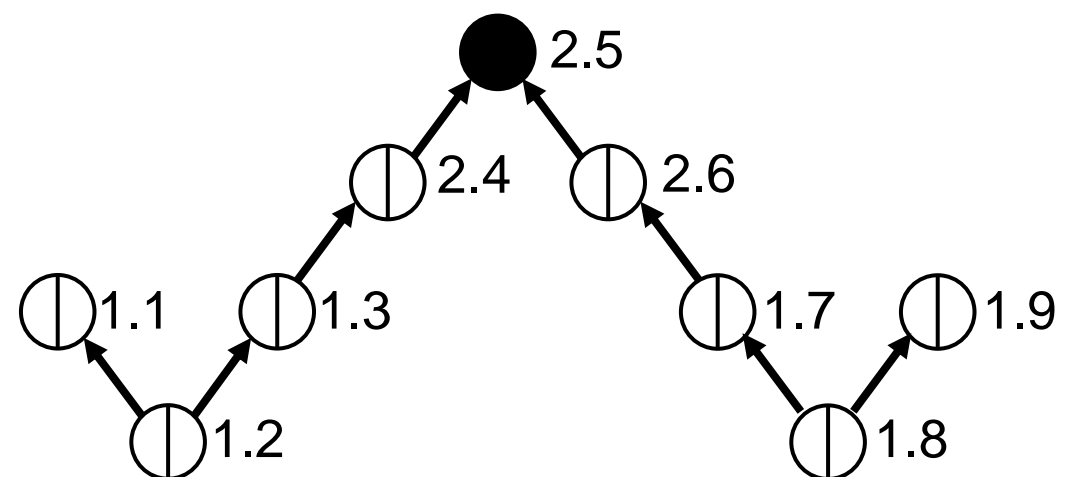


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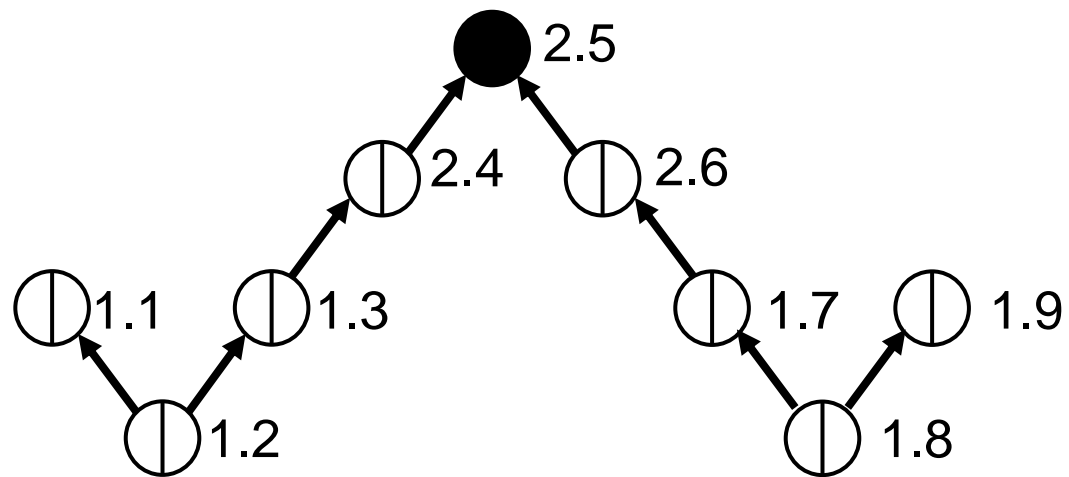


$A_5 A_6 A_4 G$

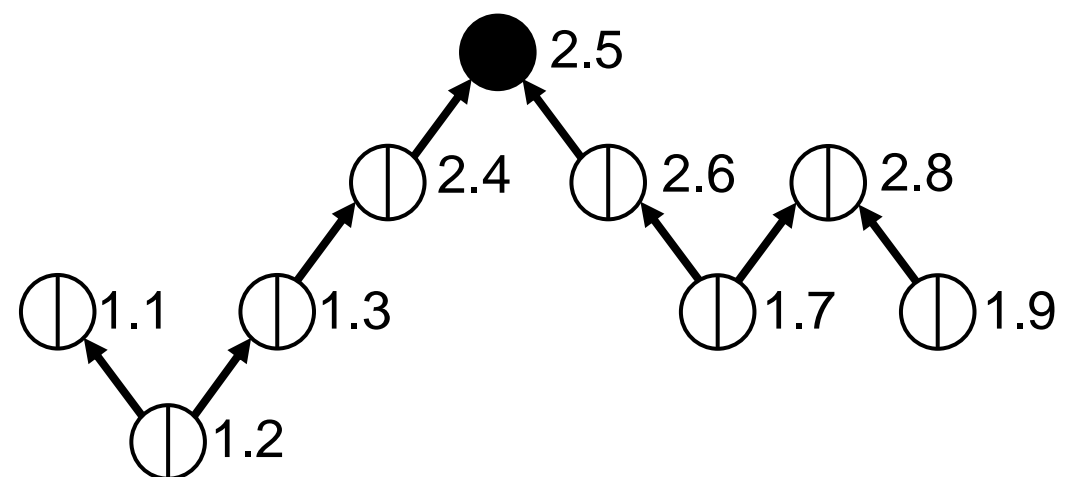


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$A_5 A_6 A_4 G$

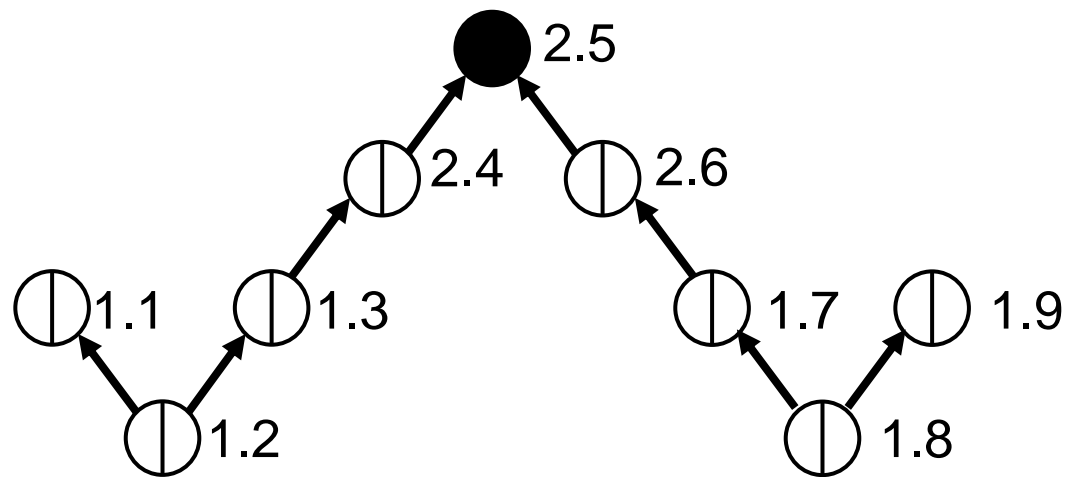


$A_8 A_5 A_6 A_4 G$

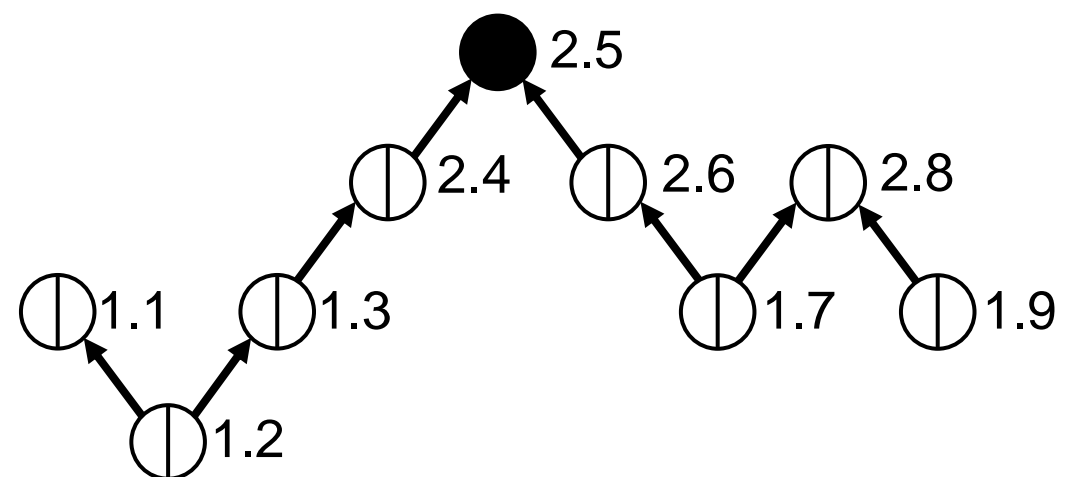


# States depend on the cut

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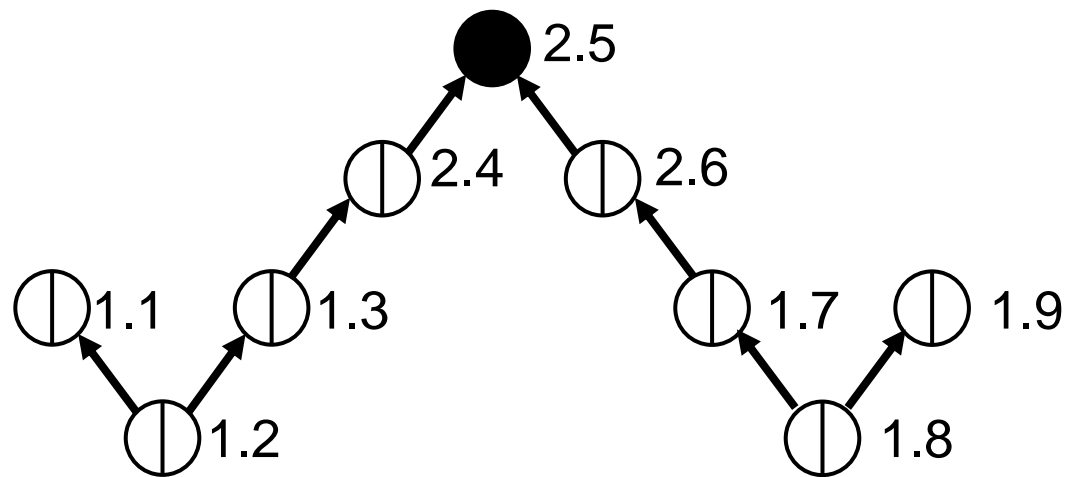
$A_8 A_5 A_6 A_4 G$



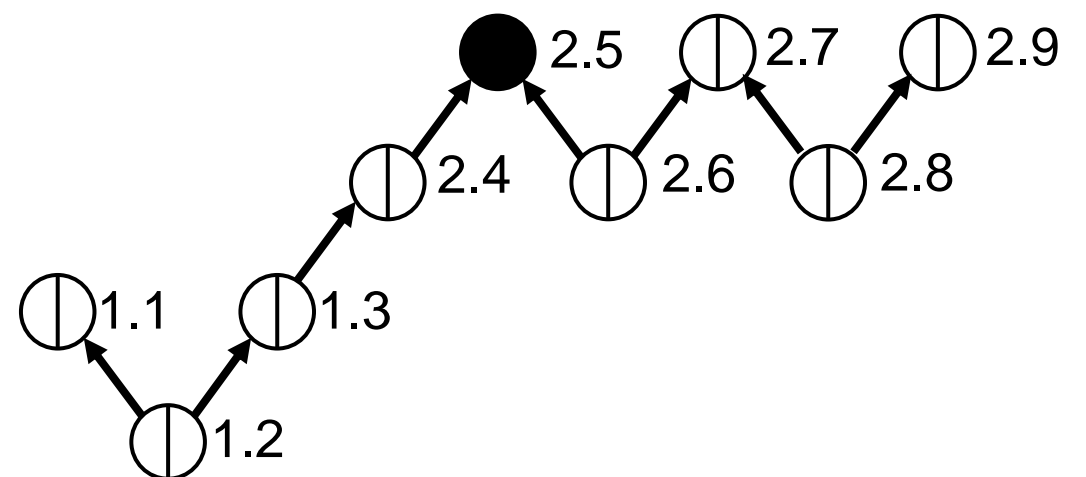


# States depend on the cut

$A_5 A_6 A_4 G$

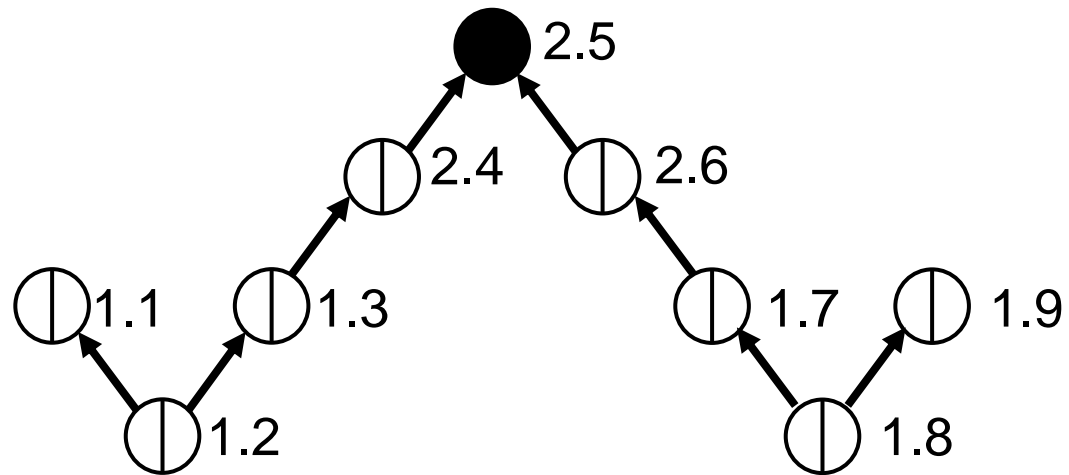


$A_9 A_7 A_8 A_5 A_6 A_4 G$

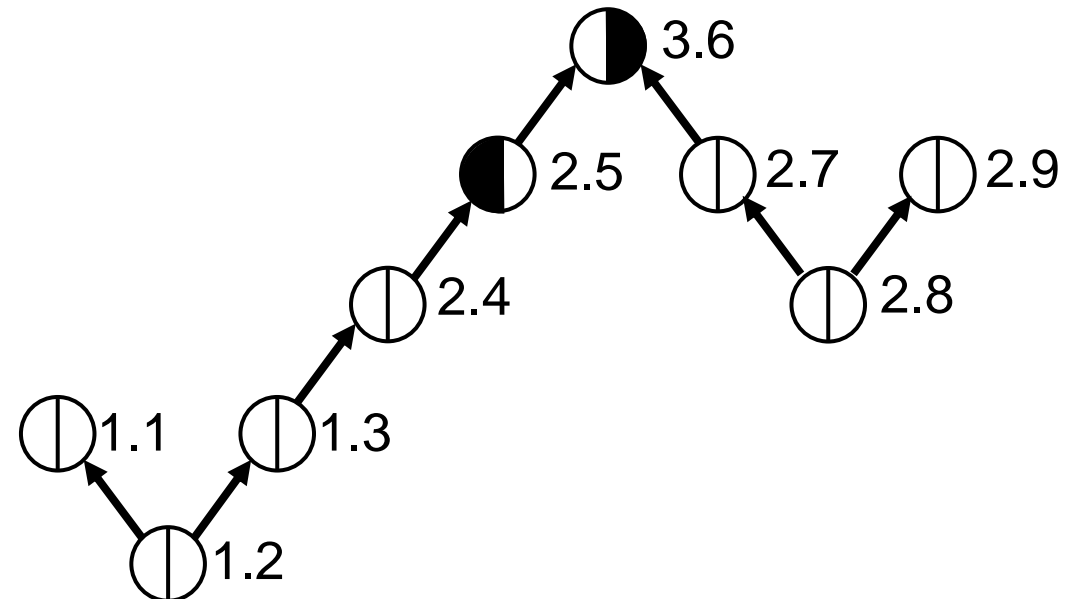


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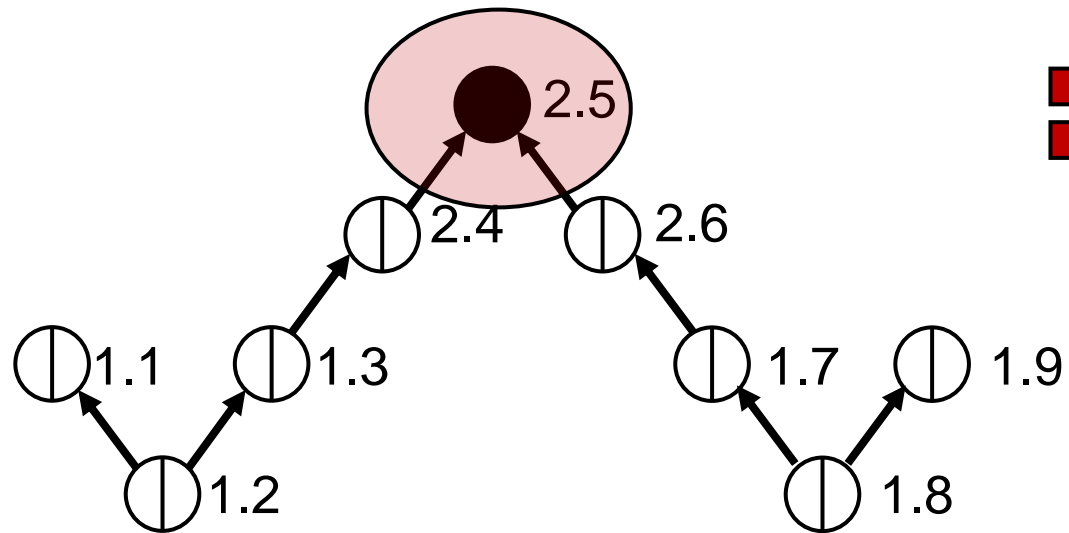


$A_6 A_9 A_8 A_5 A_4 G$



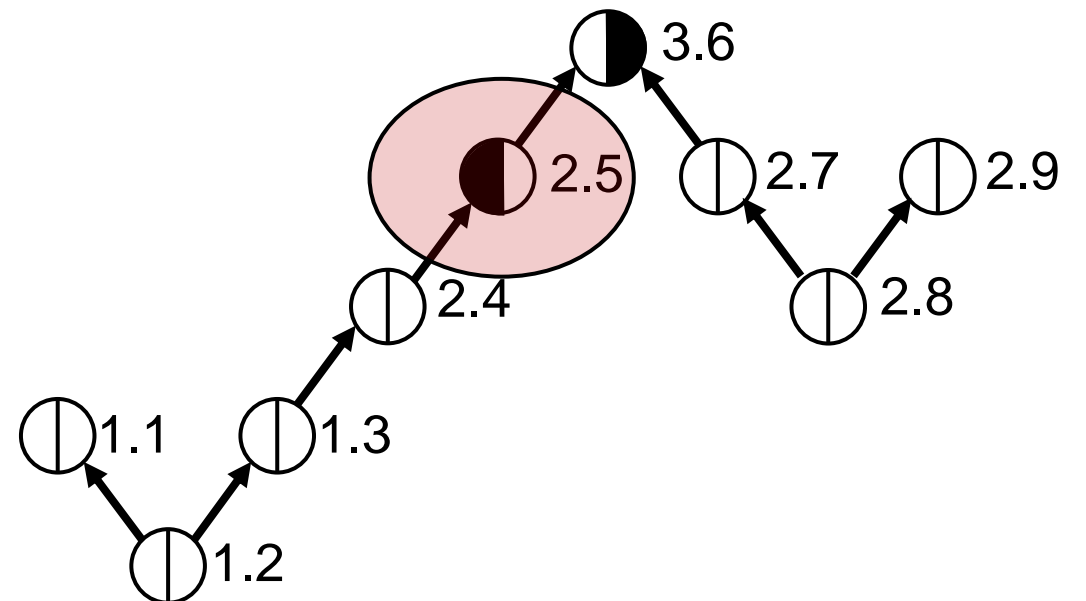
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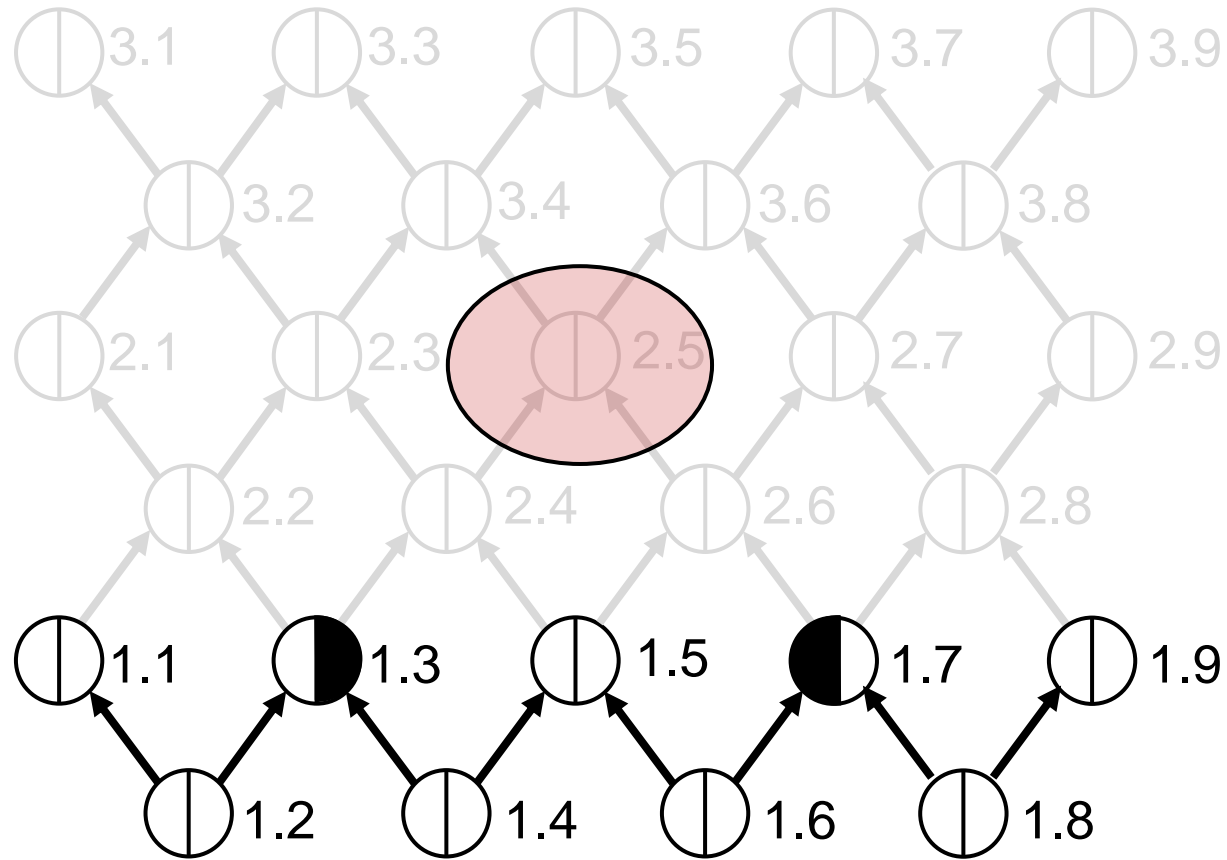


$\neq$

$A_6 A_9 A_8 A_5 A_6 A_4 G$



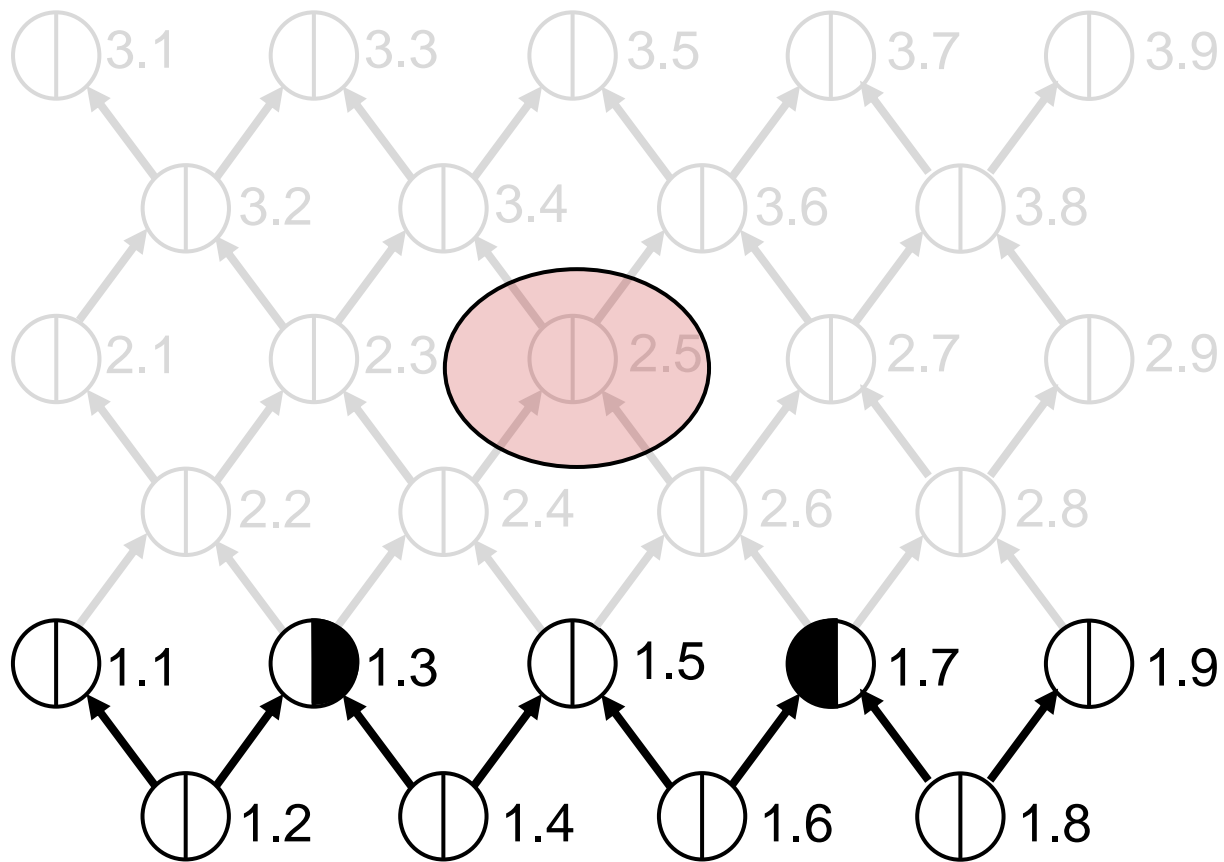
# Space-time Determinism



## Space-time Determinism

The **state** of 2.5 is **always the same for 2 locally identical cuts**. It does not depend on the rewriting strategy.

# Space-time Determinism

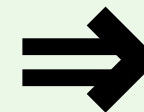


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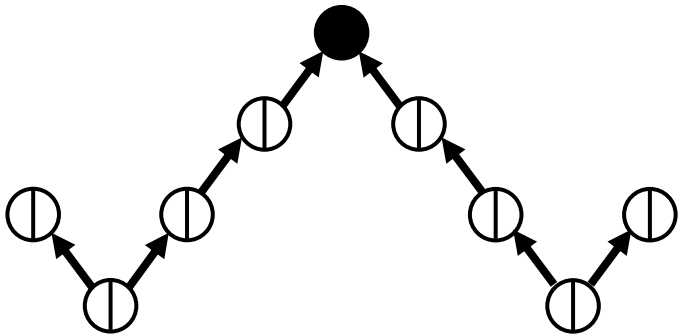
Same incoming edges



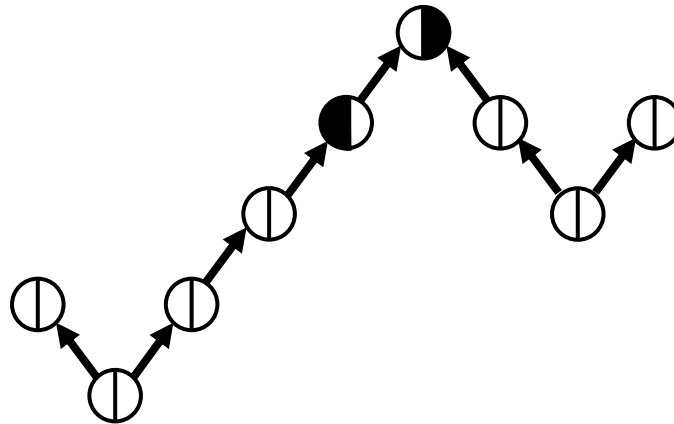
Same internal state and outgoing edges

# Space-time Determinism

$A_w G$



$A_{w'} G$

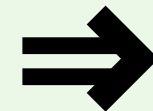


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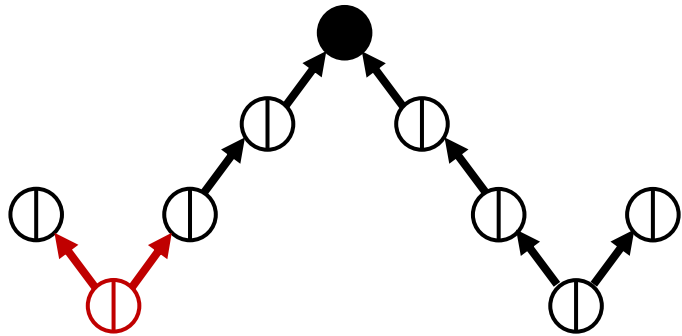
Same incoming edges



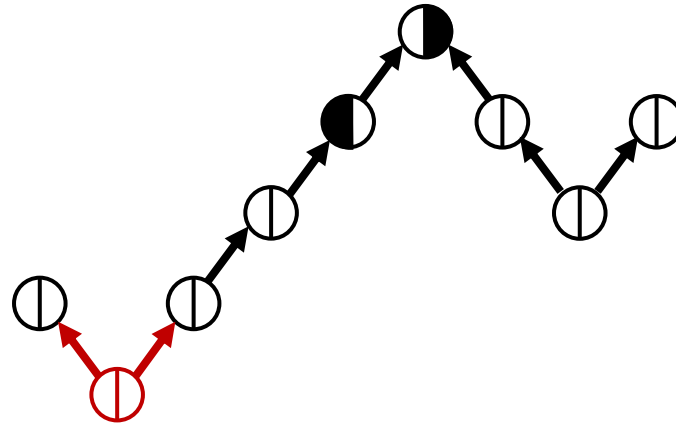
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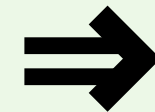


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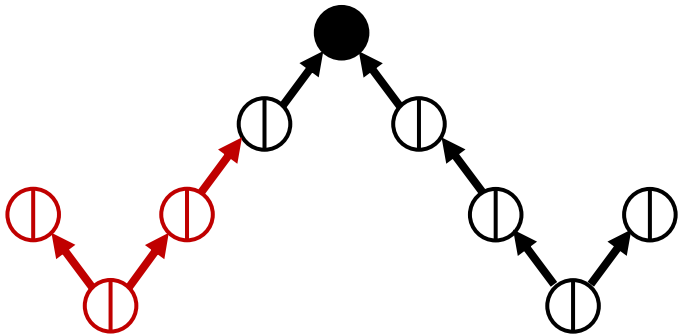
Same incoming edges



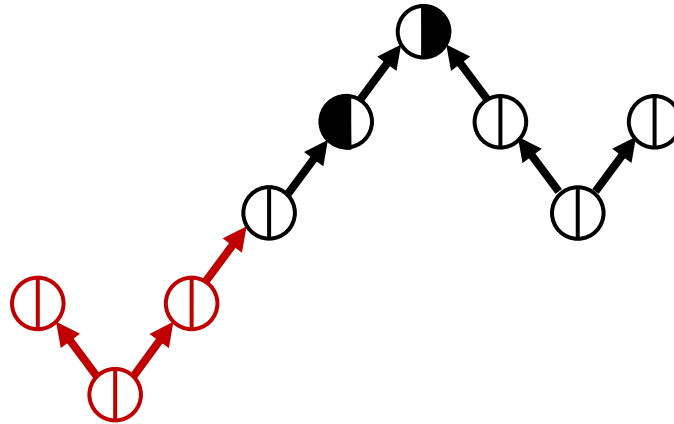
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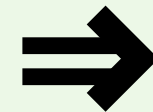


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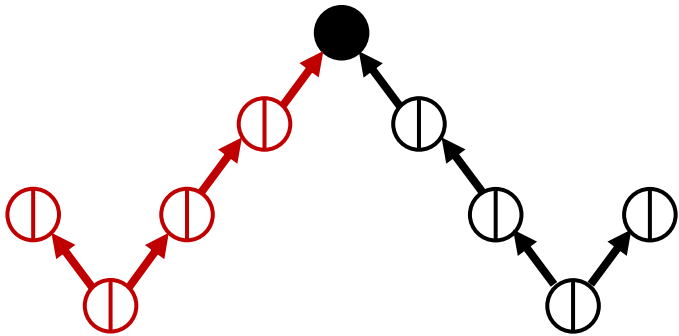


Same internal state and outgoing edges

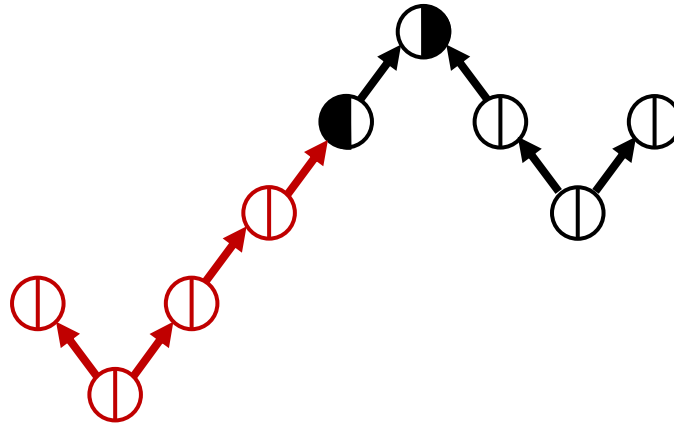


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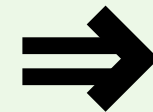


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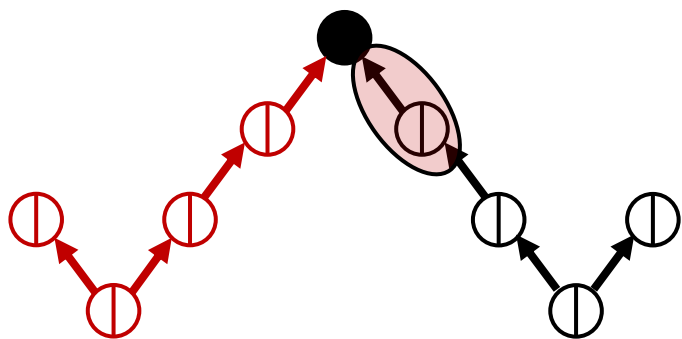
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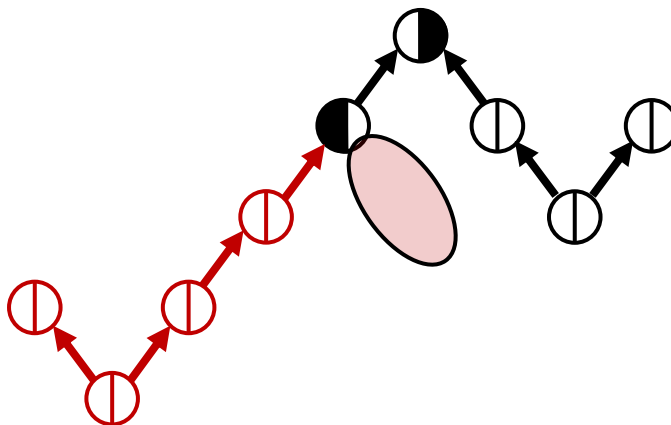
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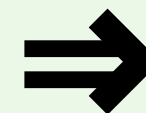


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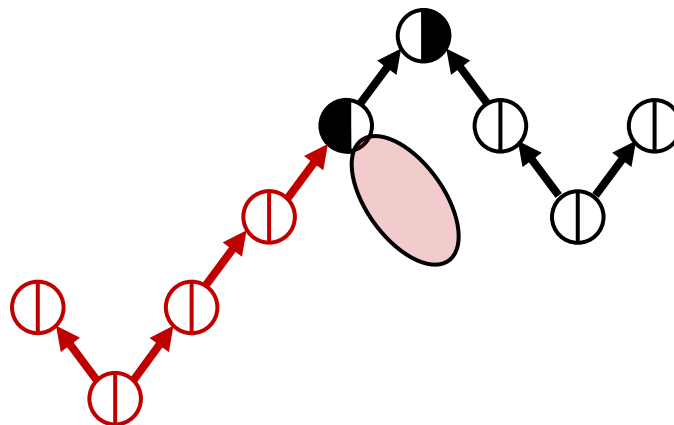
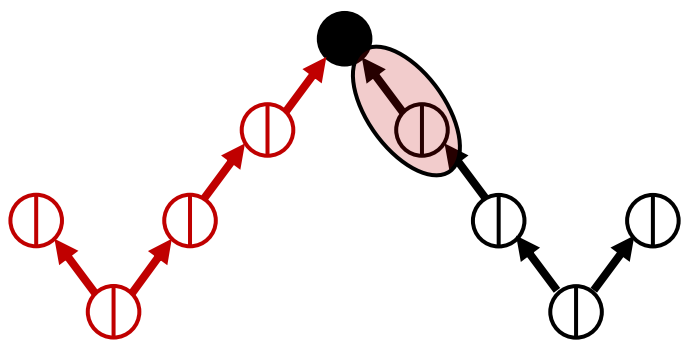
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$A_{w'} G$

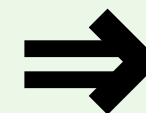


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Same internal state and outgoing edges

# Ensuring determinism

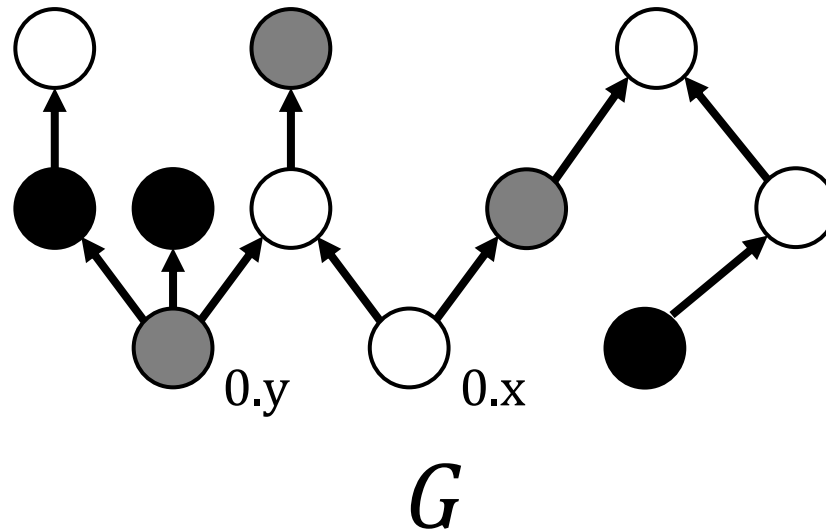
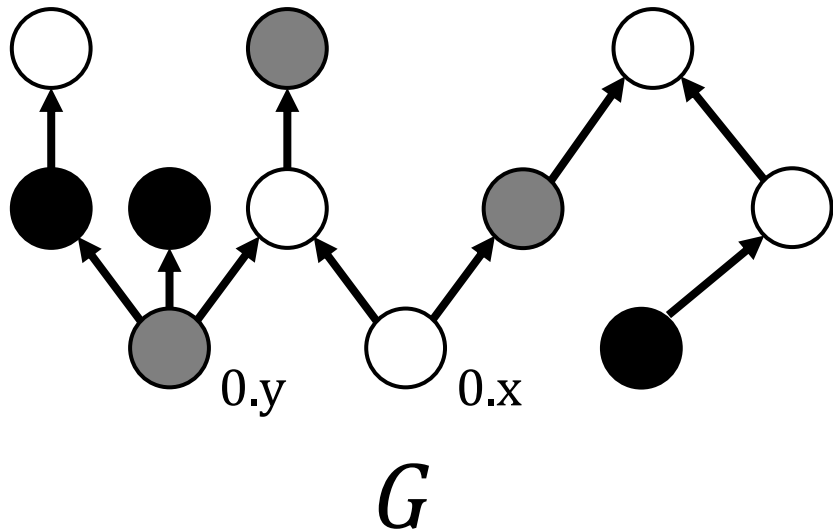
**Goal :** prove  $A$  deterministic, i.e. we always have  $A_w \parallel A_w'$ , which means :

Same incoming edges  $\Rightarrow$  Same internal state and outgoing edges

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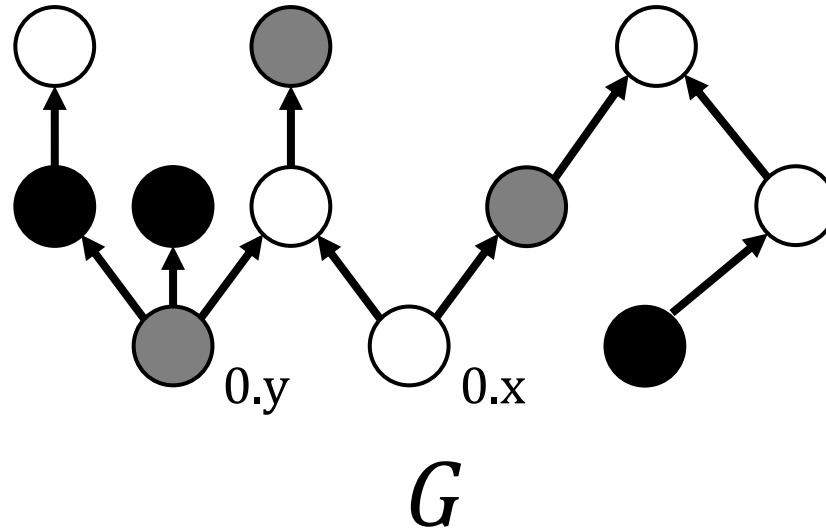
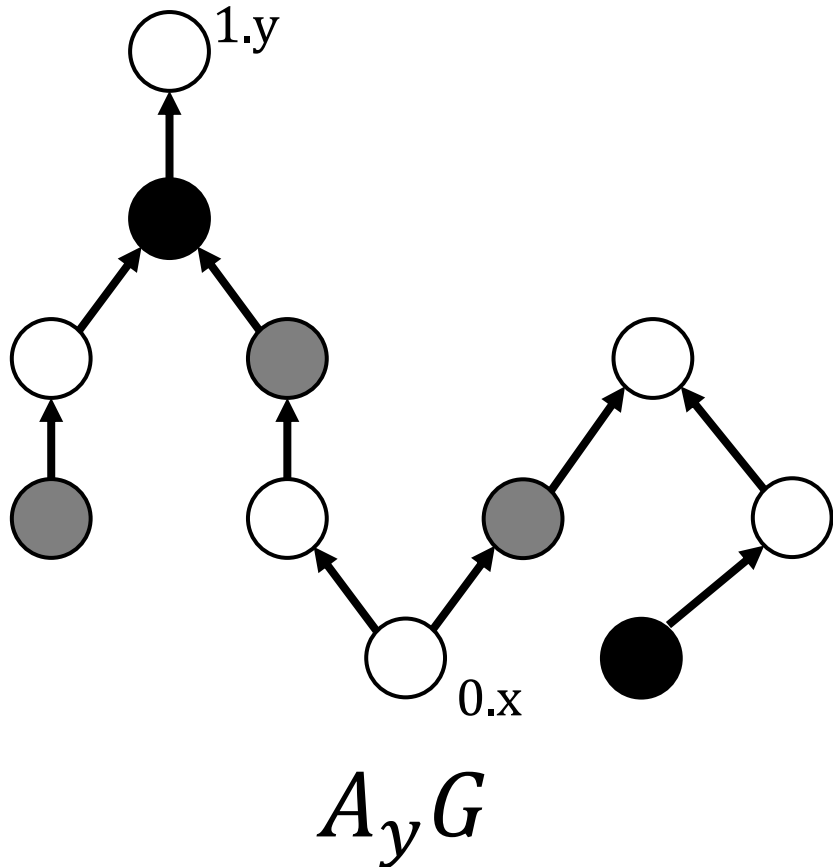
## Hypothesis

1. Commutative  
 $A_x A_y G = A_y A_x G$

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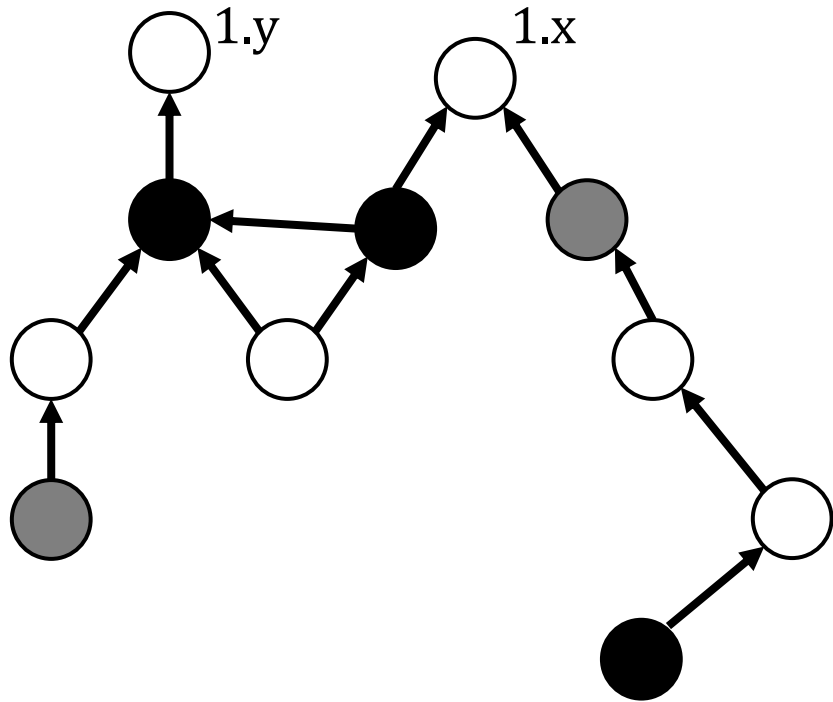
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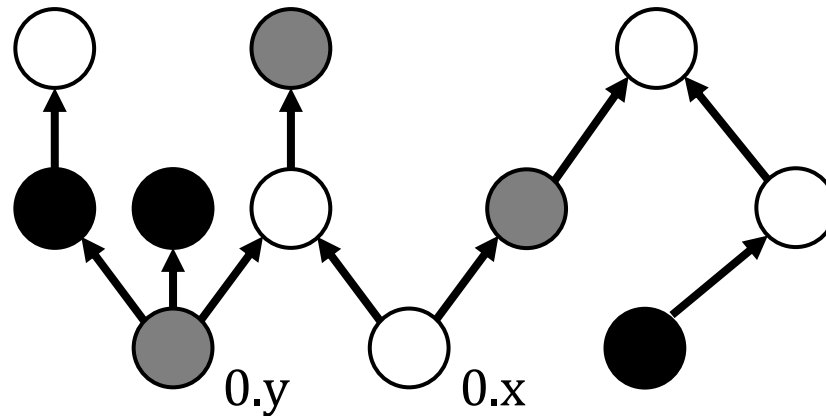
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$A_x A_y G$



$G$

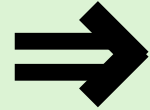
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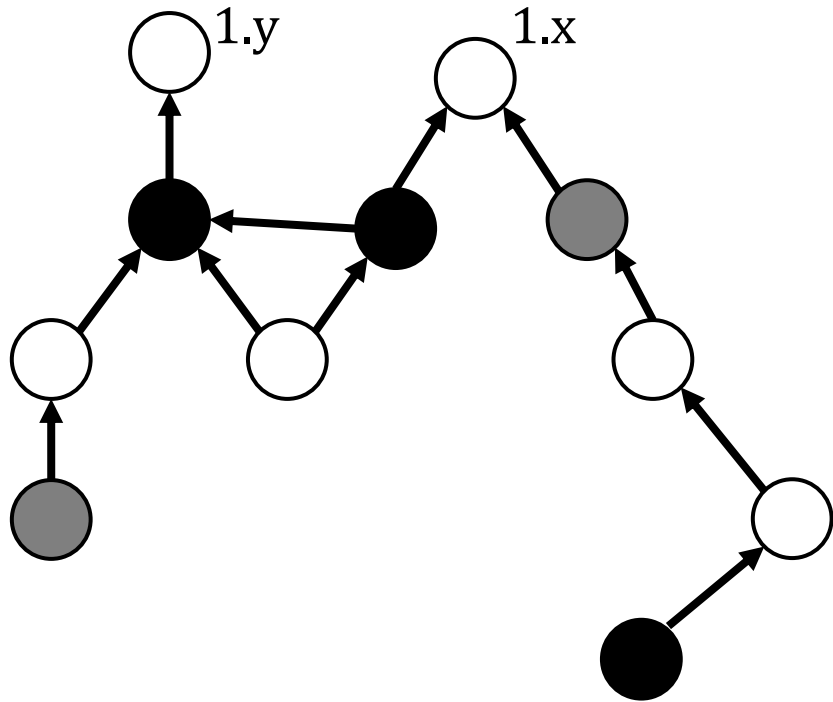
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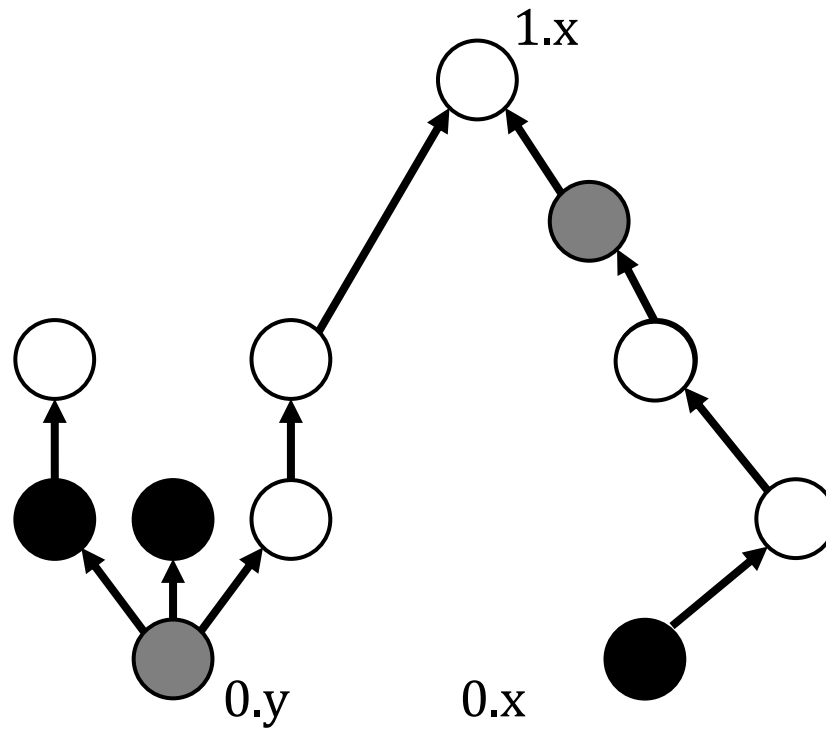
Same incoming edges



Same internal state and outgoing edges



$A_x A_y G$



$A_x G$

## Hypothesis

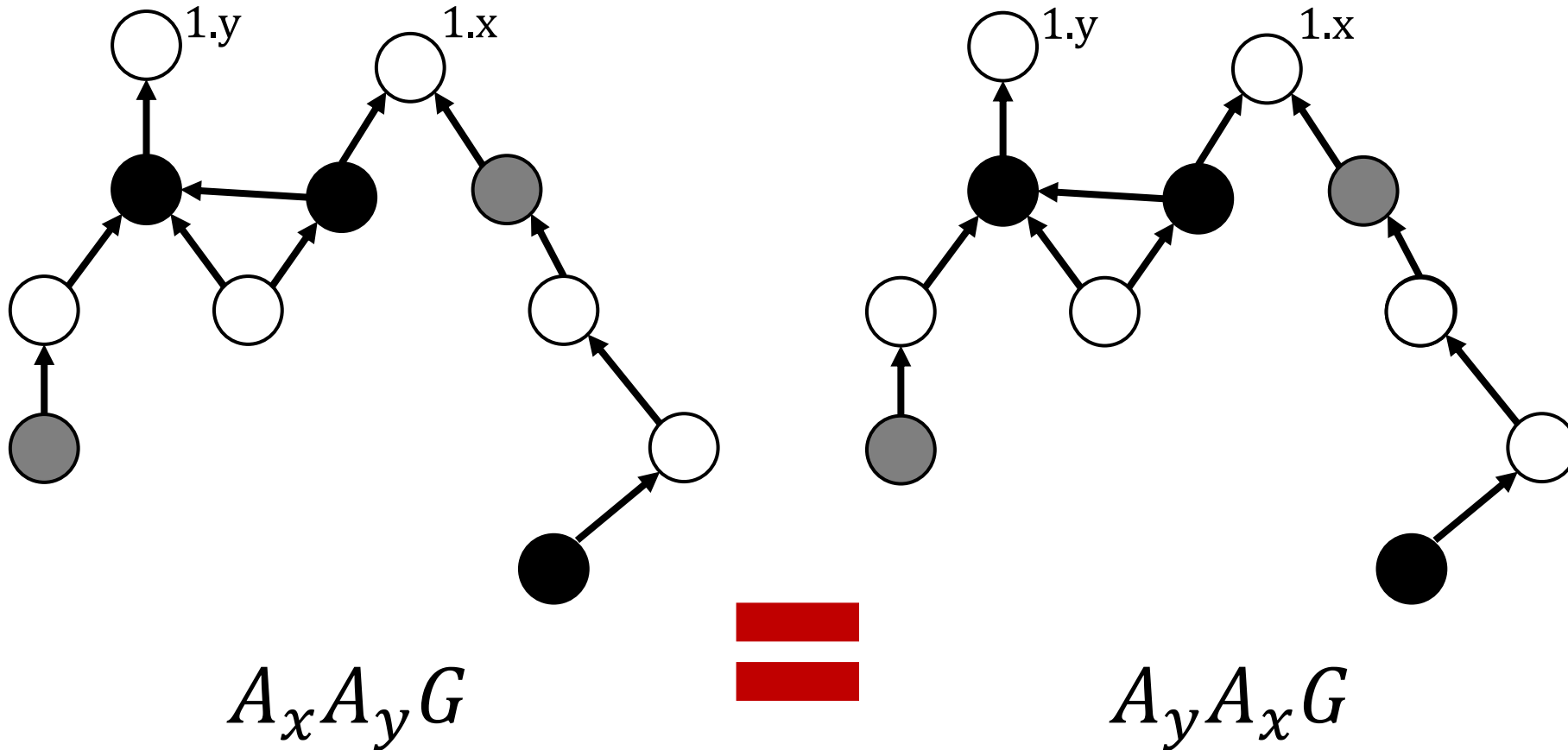
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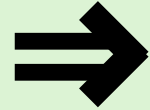
## Hypothesis

1. Commutative  
 $A_x A_y G = A_y A_x G$

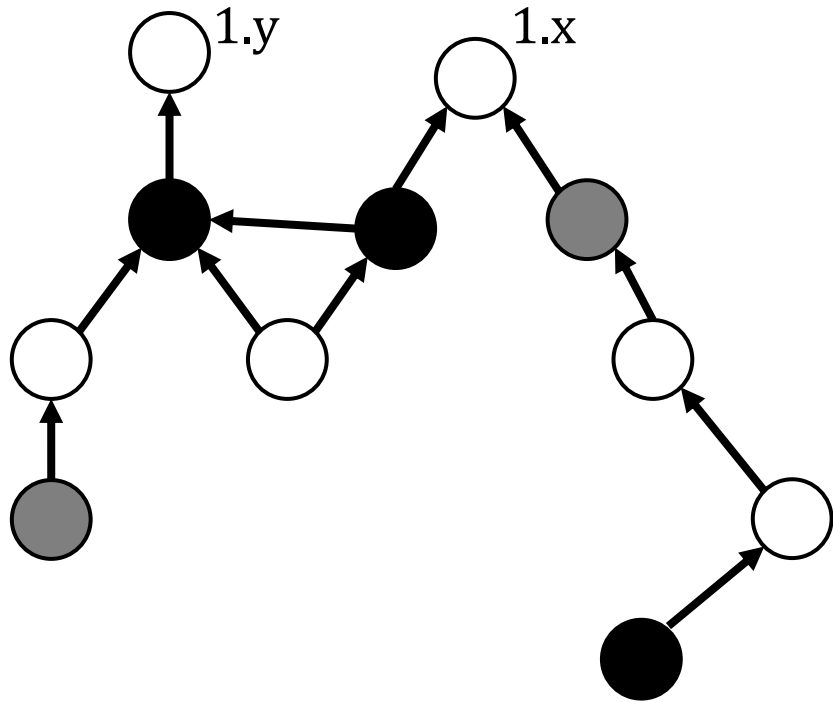
# Ensuring determinism

**Goal :** prove  $A$  deterministic, i.e. we always have  $A_w || A_w$ , which means :

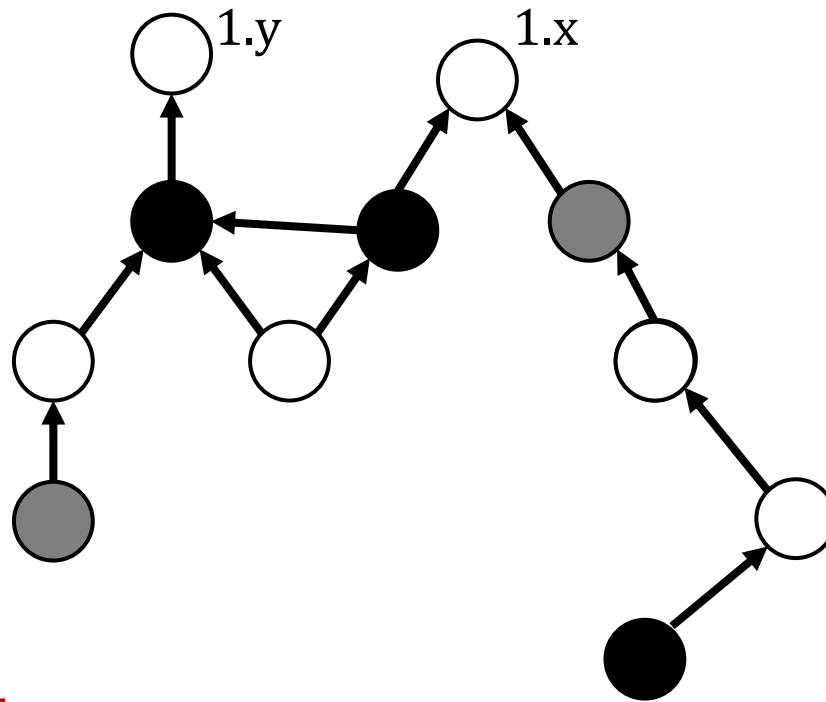
Same incoming edges



Same internal state and outgoing edges



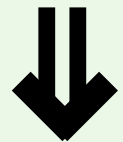
$A_x A_y G$



$A_y A_x G$

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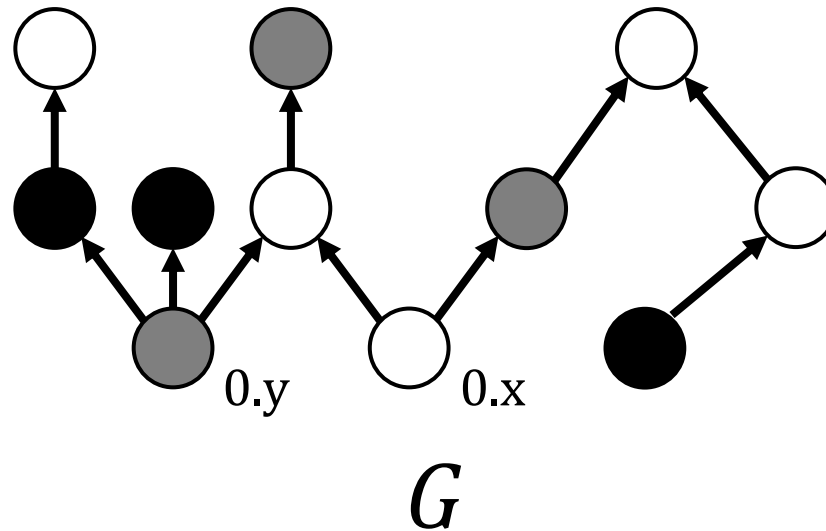
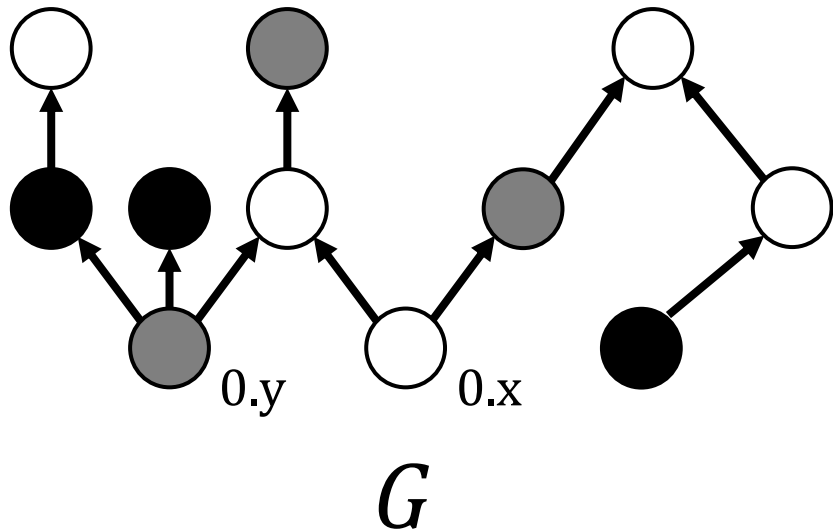
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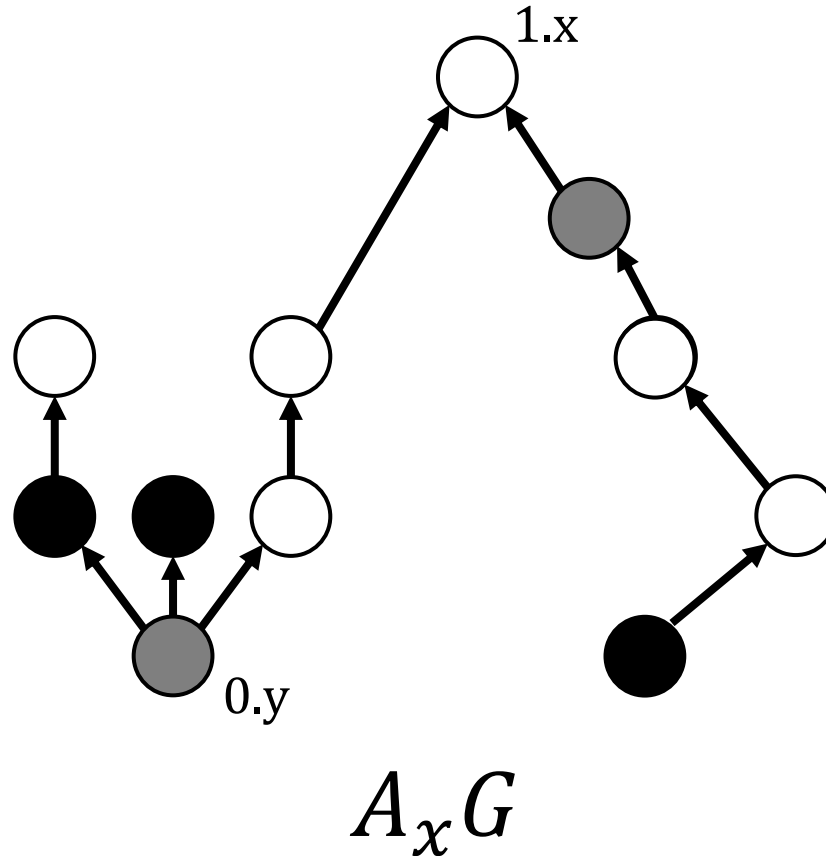
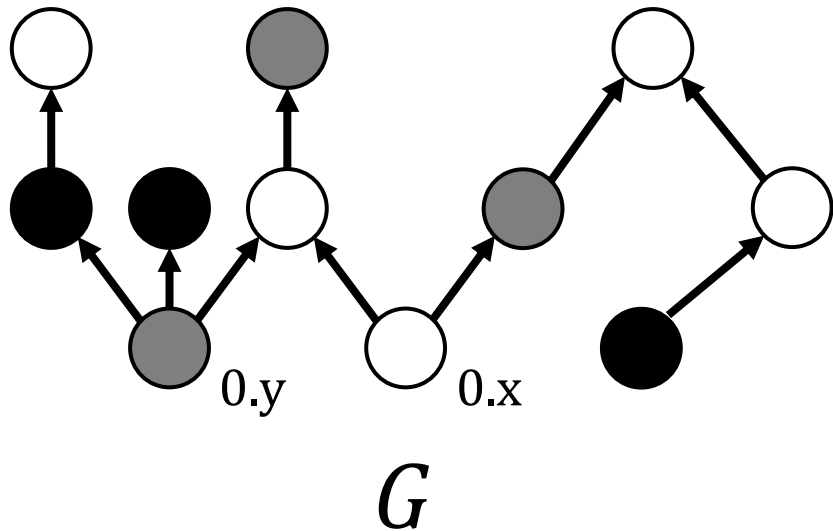
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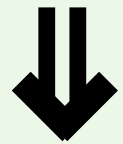
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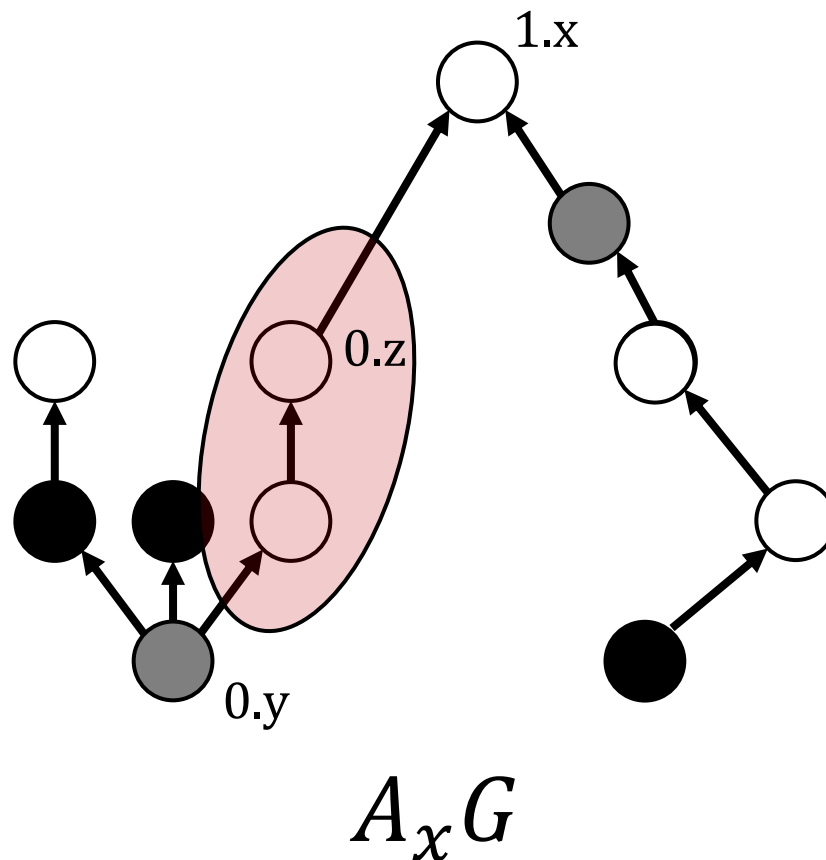
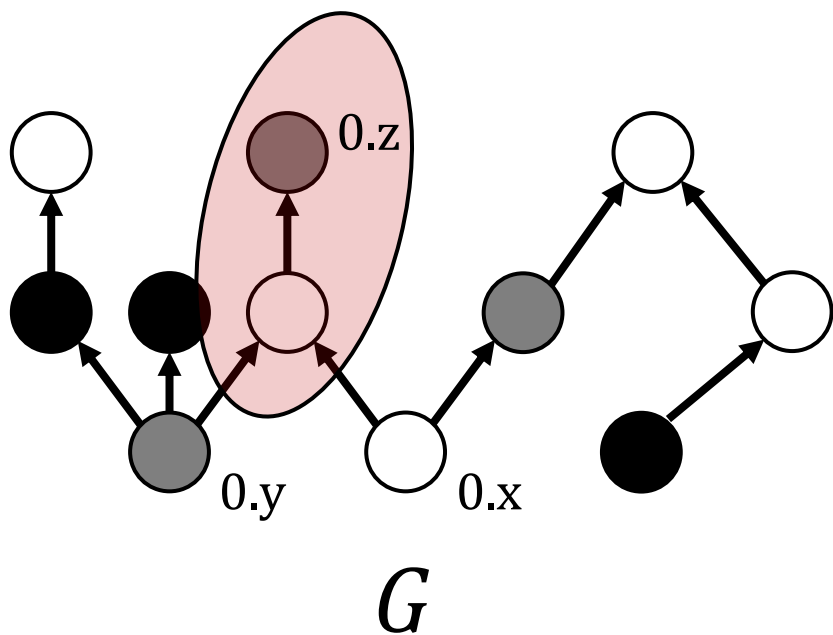
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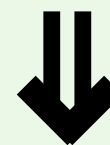
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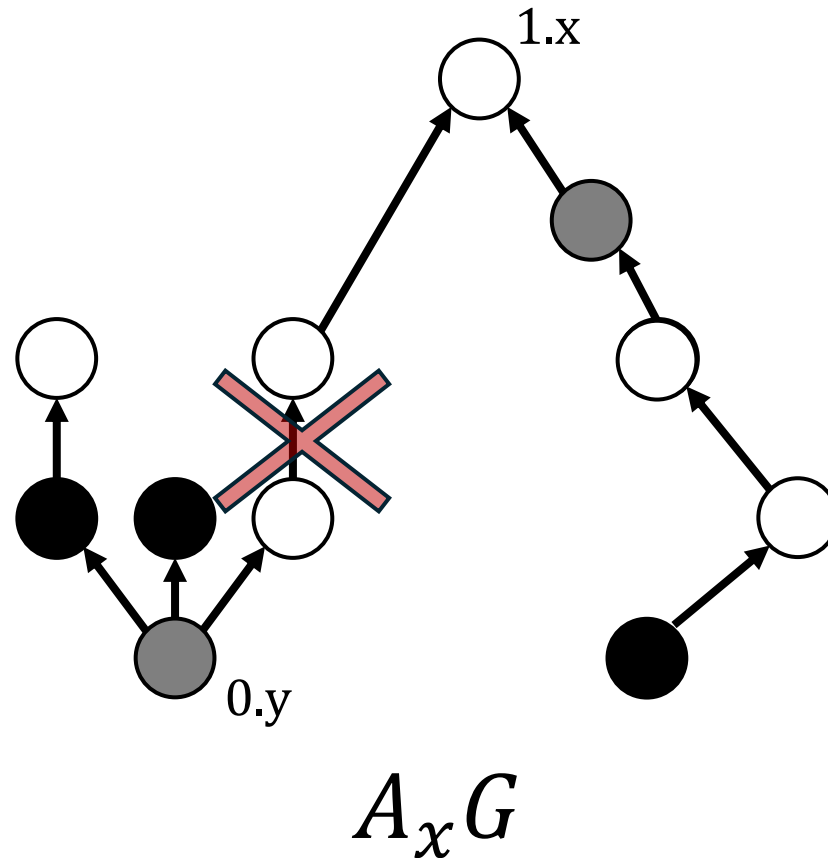
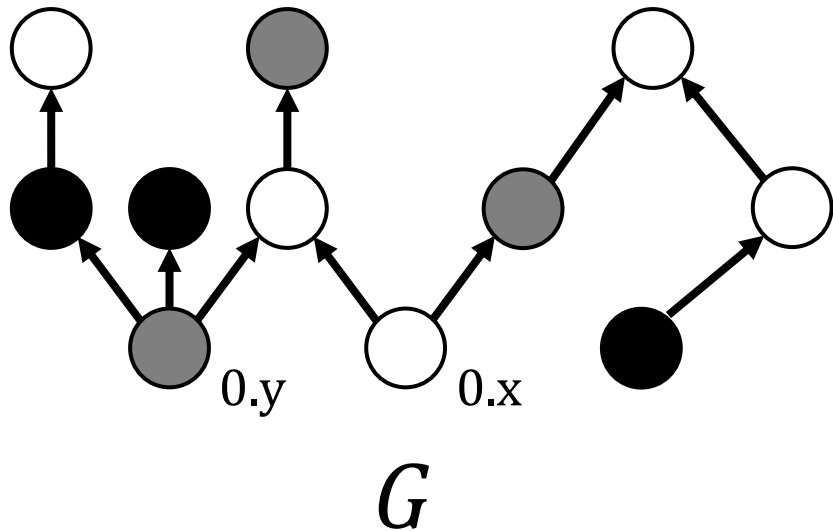
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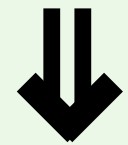
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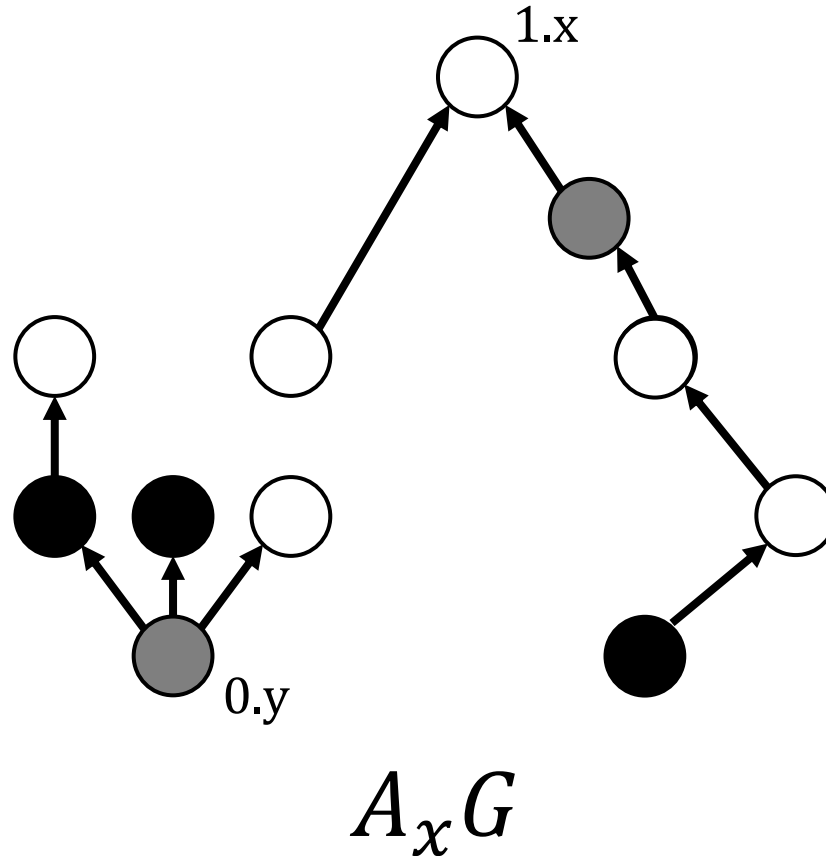
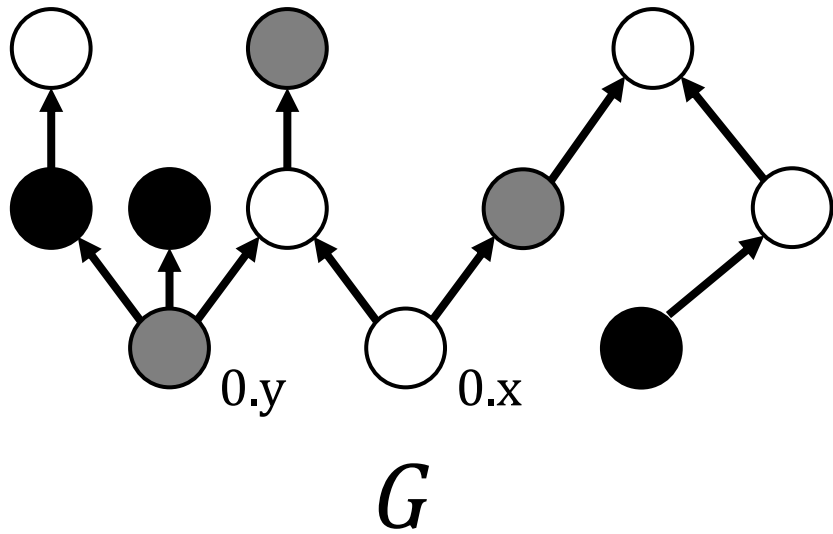
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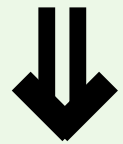
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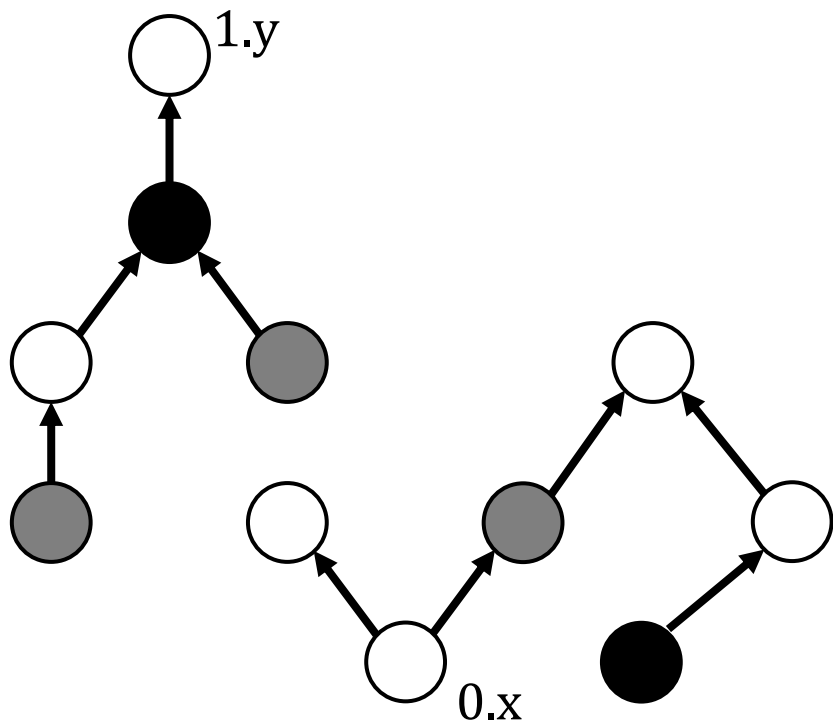
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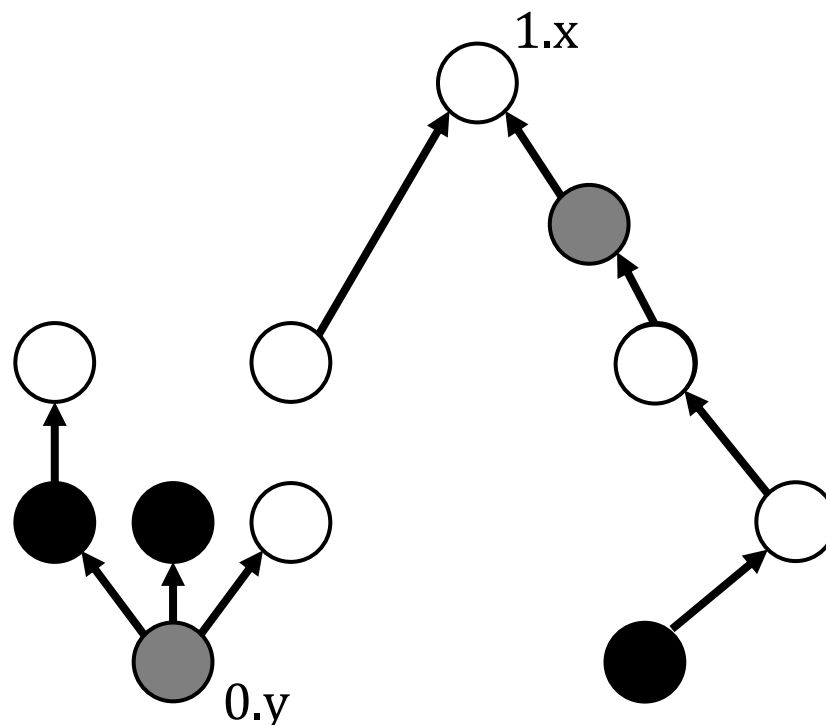
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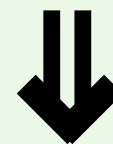
$A_y G$



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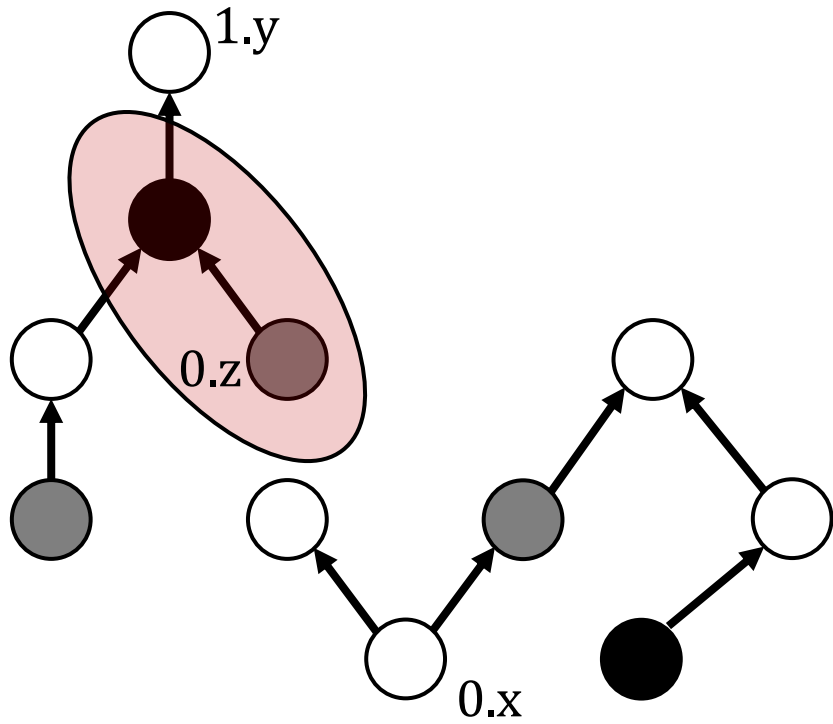
1.  $A_x A_y G || A_y A_x G$
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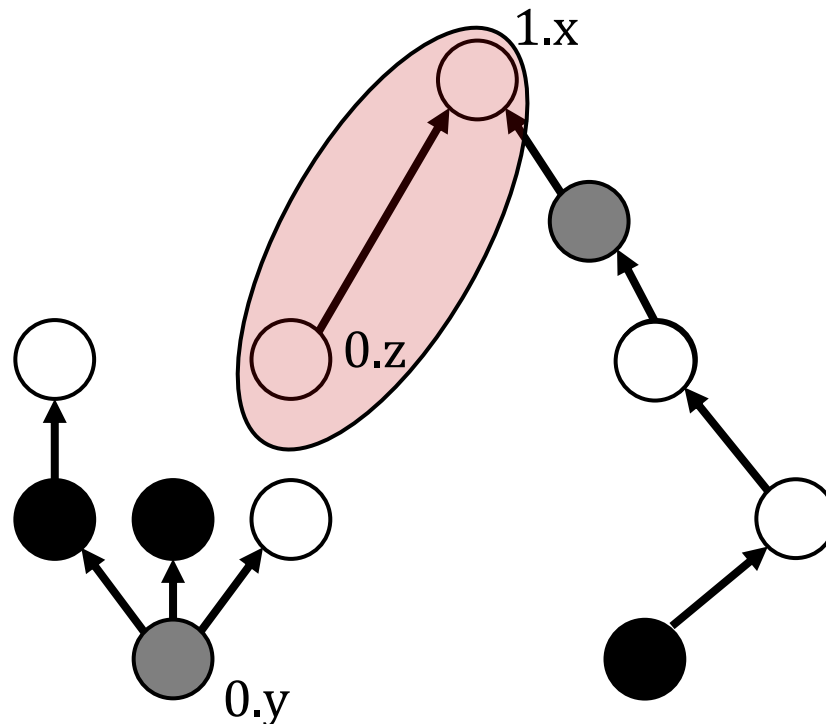
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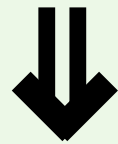
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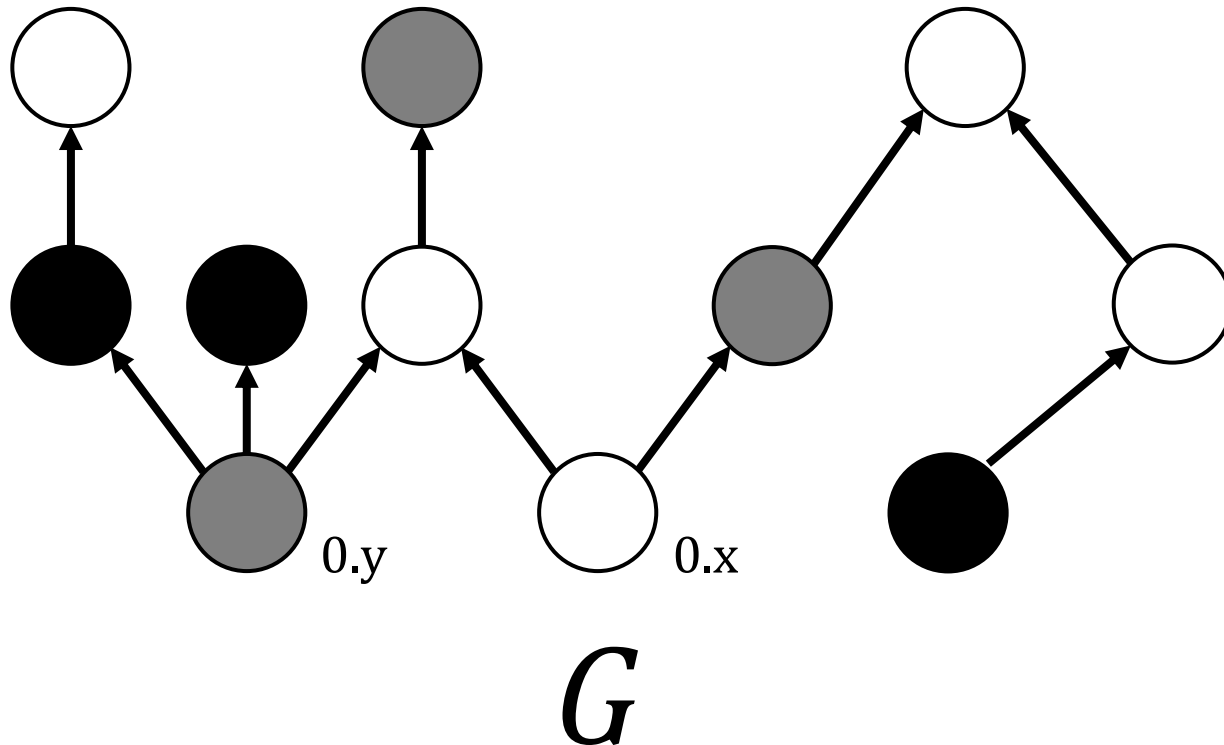
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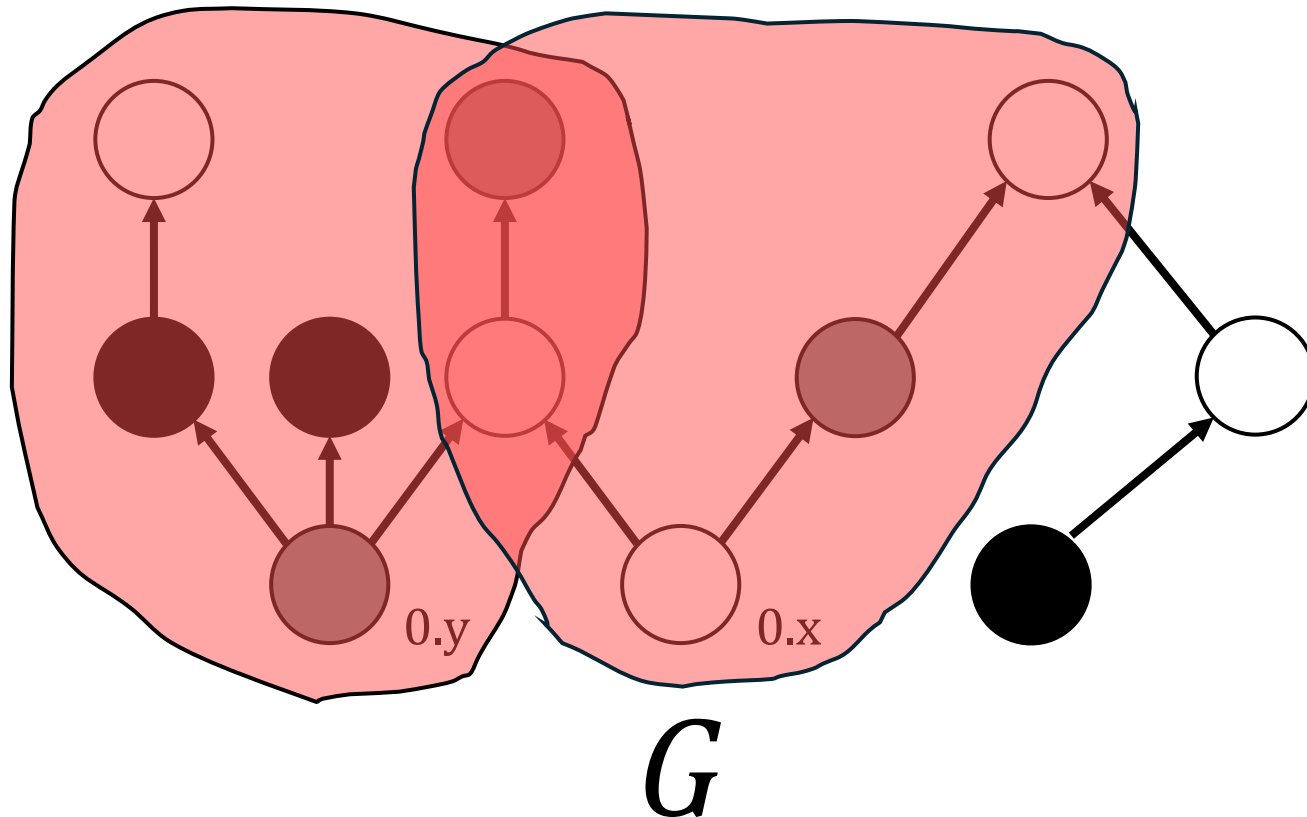
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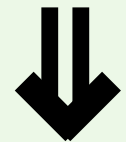
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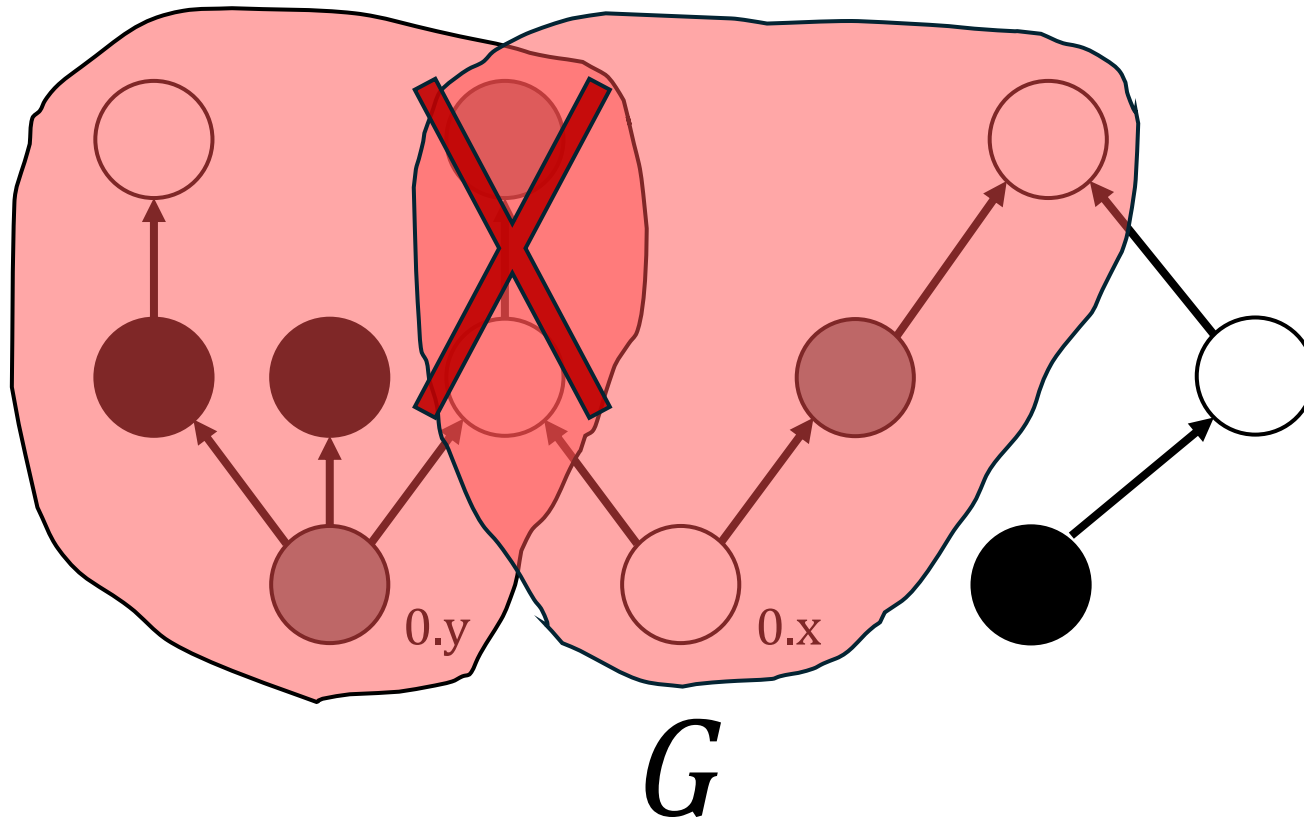
## Conclusion

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## Hypothesis

1. Commutative  
 $A_x A_y G = A_y A_x G$
2. Edge decreasing
3. Private



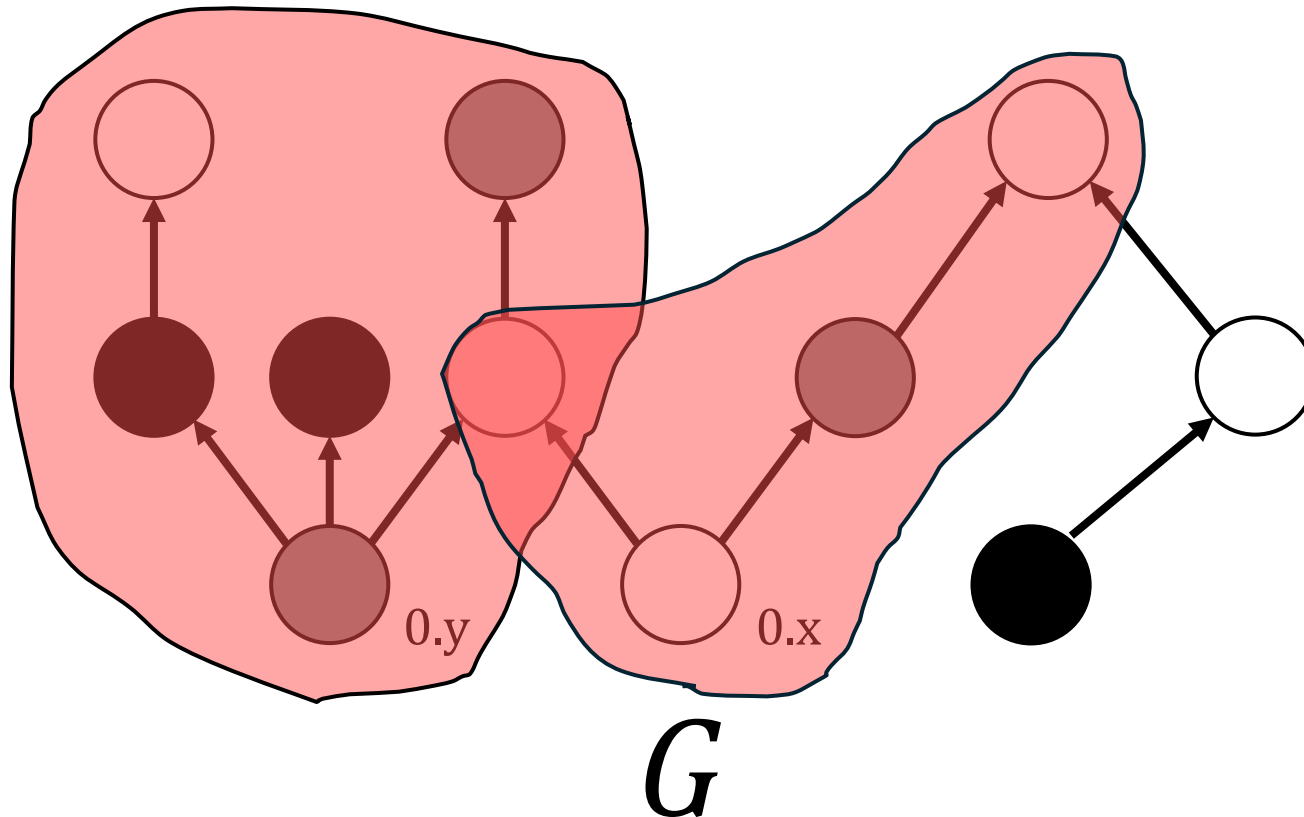
## Conclusion

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# Ensuring determinism

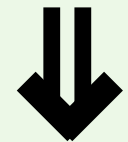
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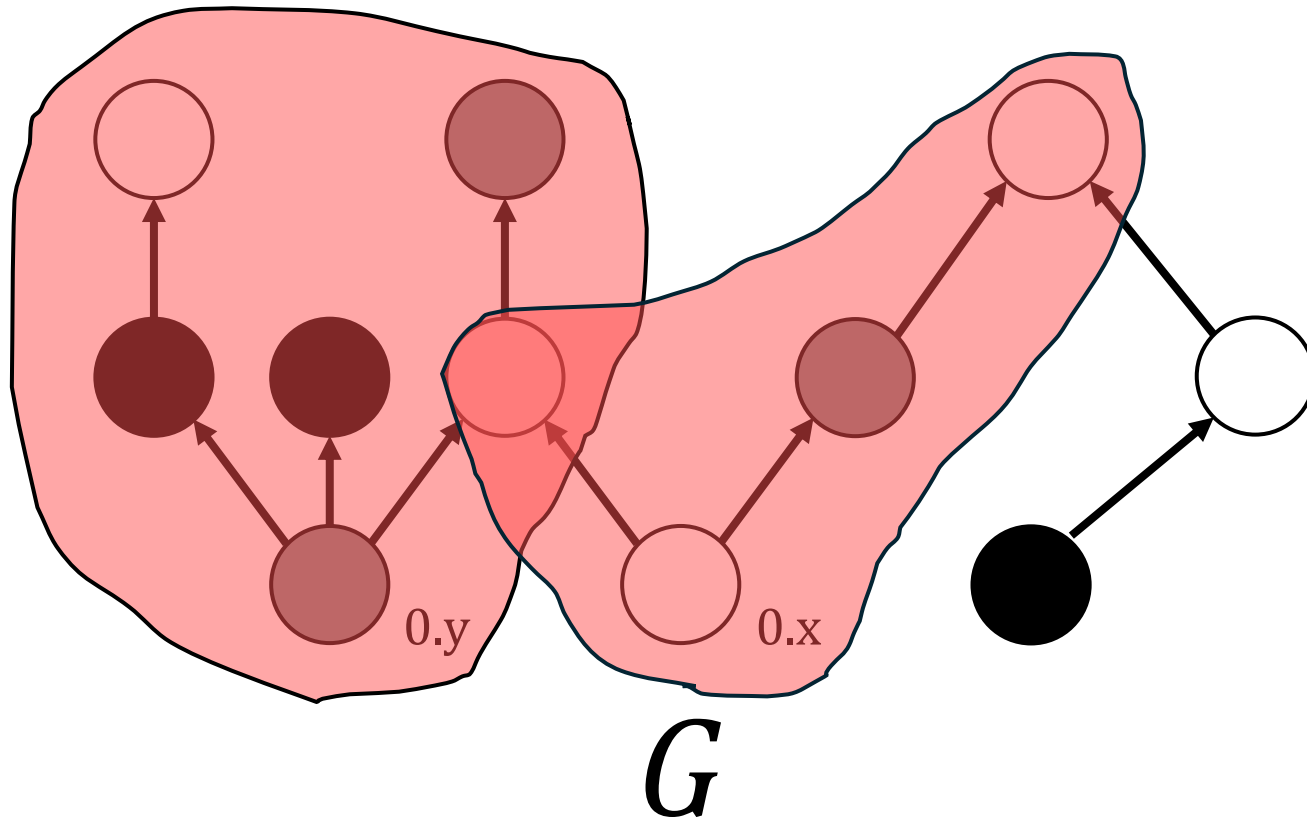
## Conclusion

1.  $A_x A_y G || A_y A_x G$
2.  $A_x G || G$
3.  $A_x G || A_y G$

# Ensuring determinism

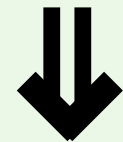
**Goal :** prove  $A$  deterministic, i.e. we always have  $A_w || A_w'$ , which means :

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## Hypothesis

1. Commutative  
 $A_x A_y G = A_y A_x G$
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## Conclusion

1.  $A_x A_y G || A_y A_x G$
2.  $A_x G || G$
3.  $A_x G || A_y G$
4.  $A_w G || A_w' G$

# Ensuring determinism

## **Theorem 1**

Any commutative, edge decreasing and private local rule is deterministic.

# Ensuring determinism

## Theorem 1

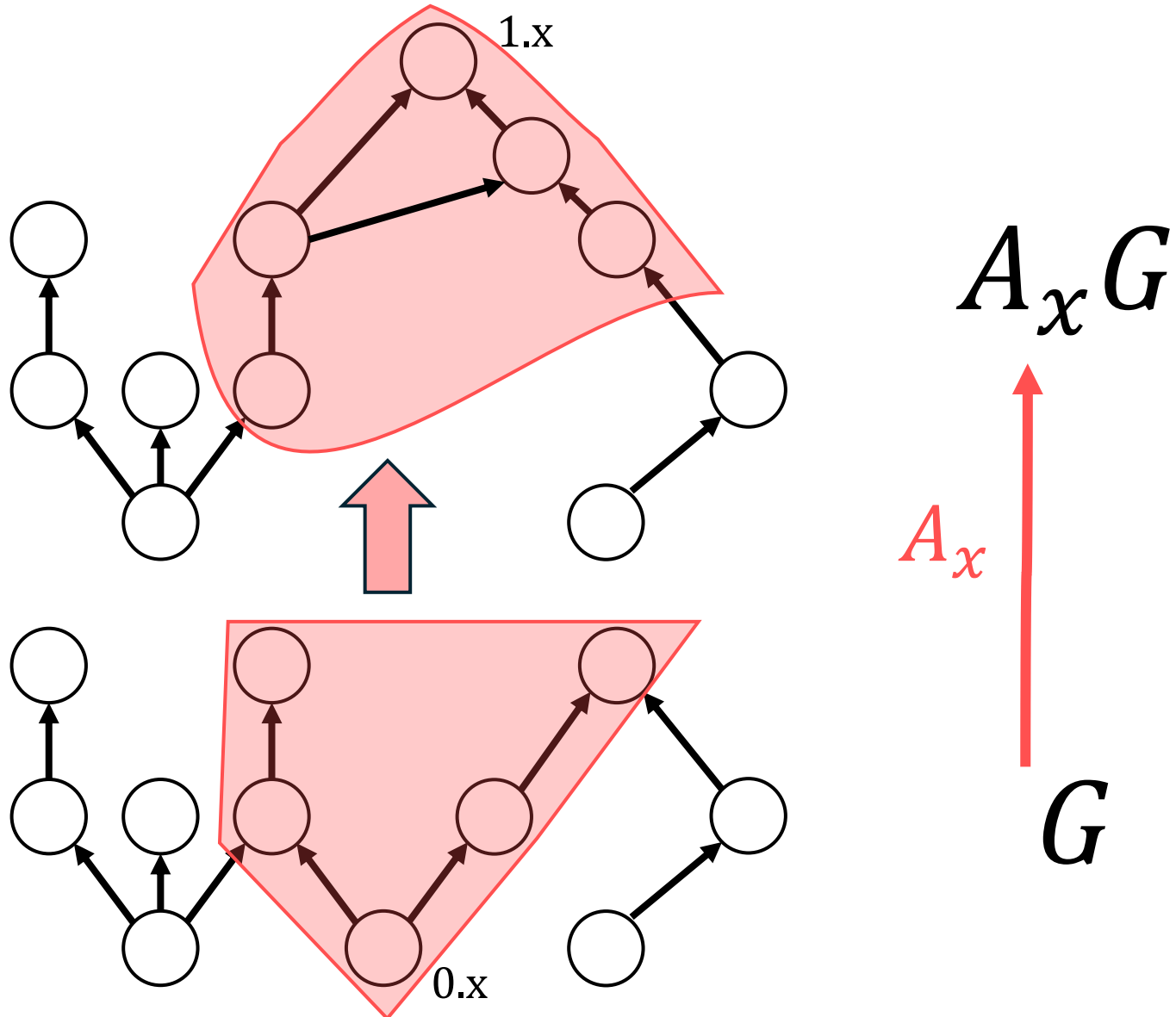
Any commutative, edge decreasing and private local rule is deterministic.

**In general which local rewriting rules are physical ?**

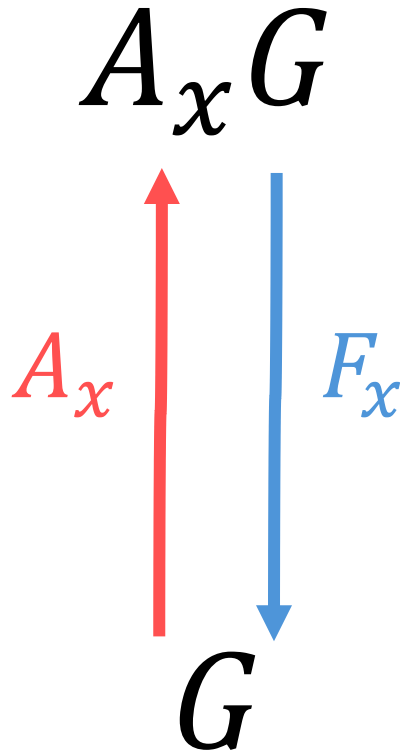
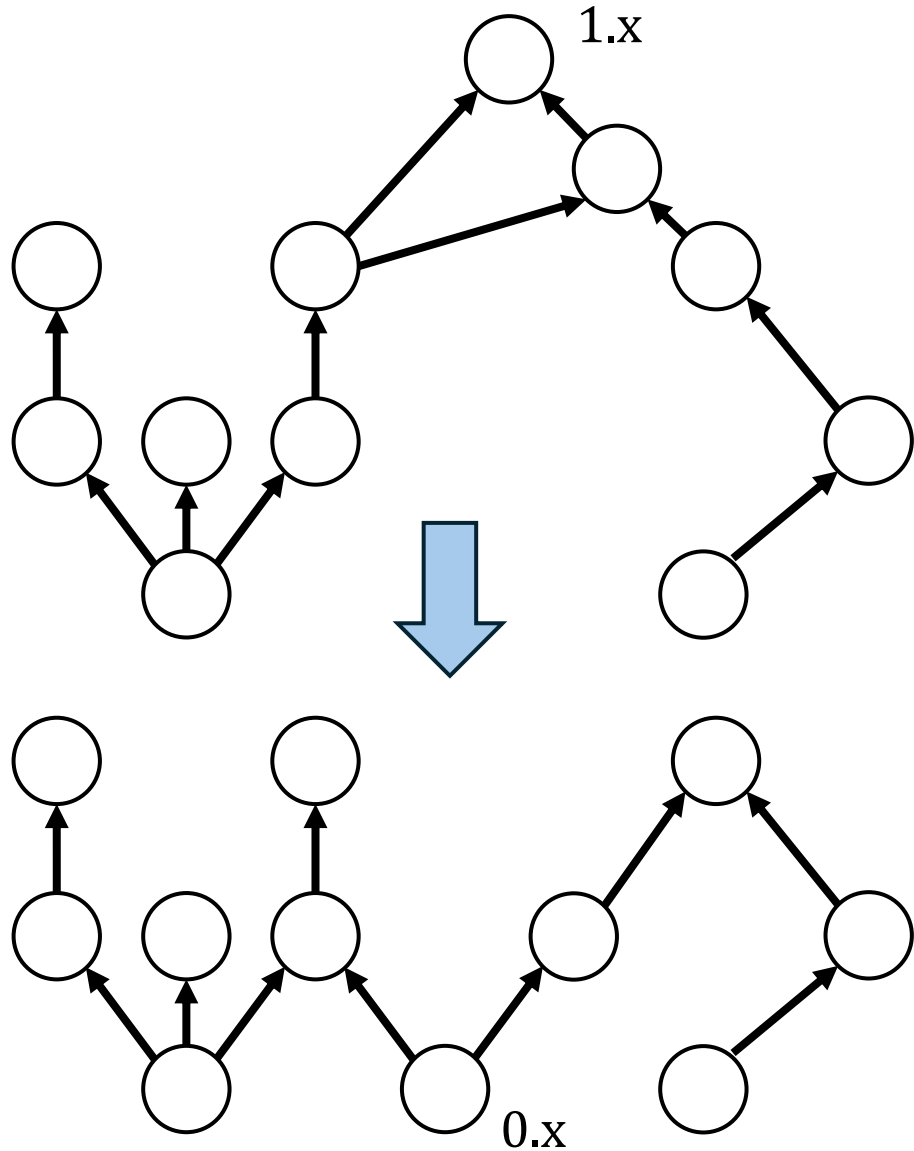
- **Determinism** **OK**
- **Reversibility** 



# Defining Reversibility



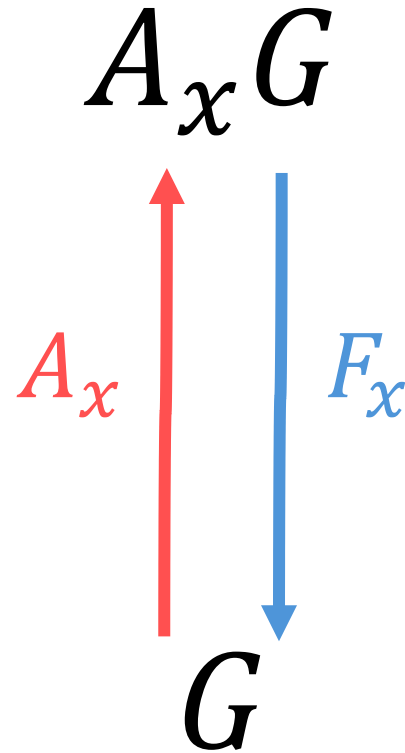
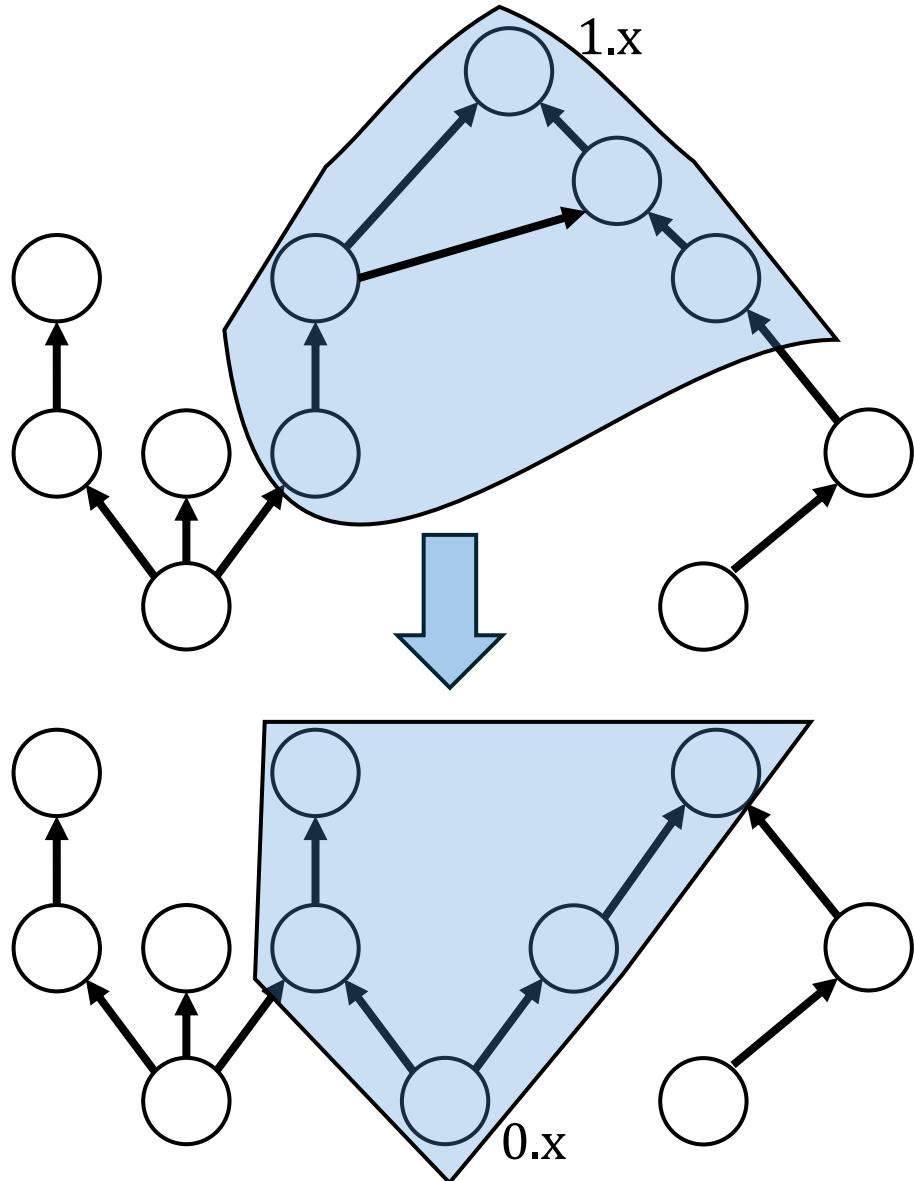
# Defining Reversibility



## Option 1

- $F$  is a function s.t.  
 $F_x A_x G = G$
- **Problem** : non physical, does not match reversibility in CA, ...

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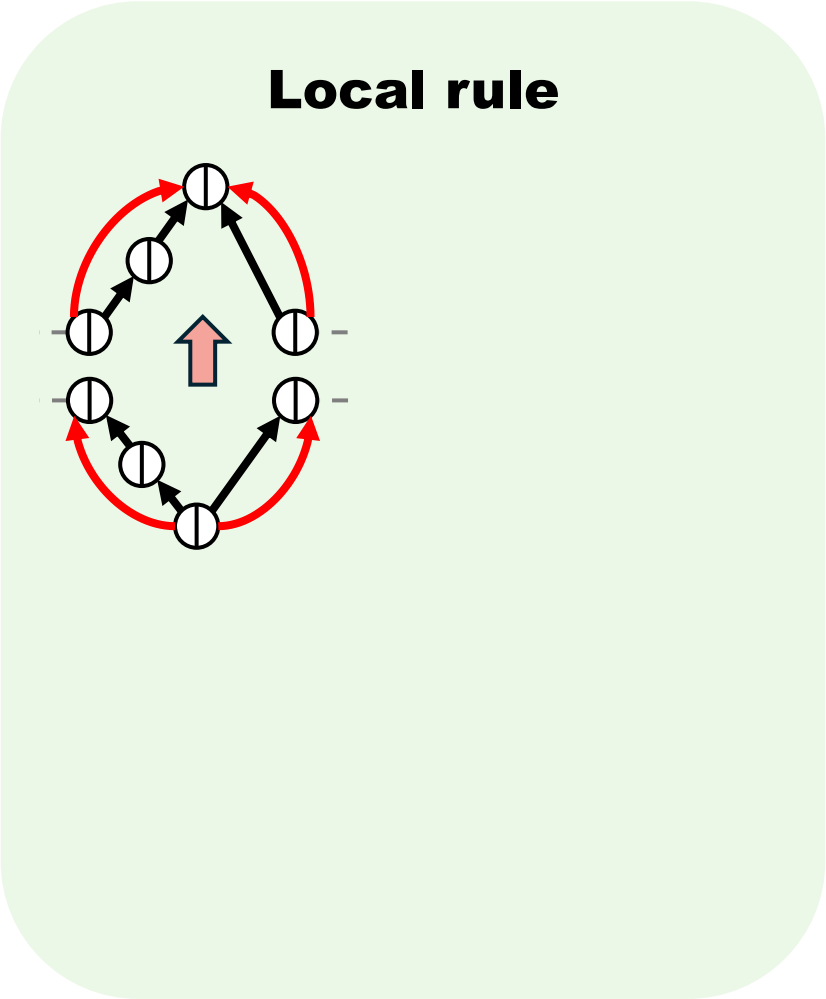
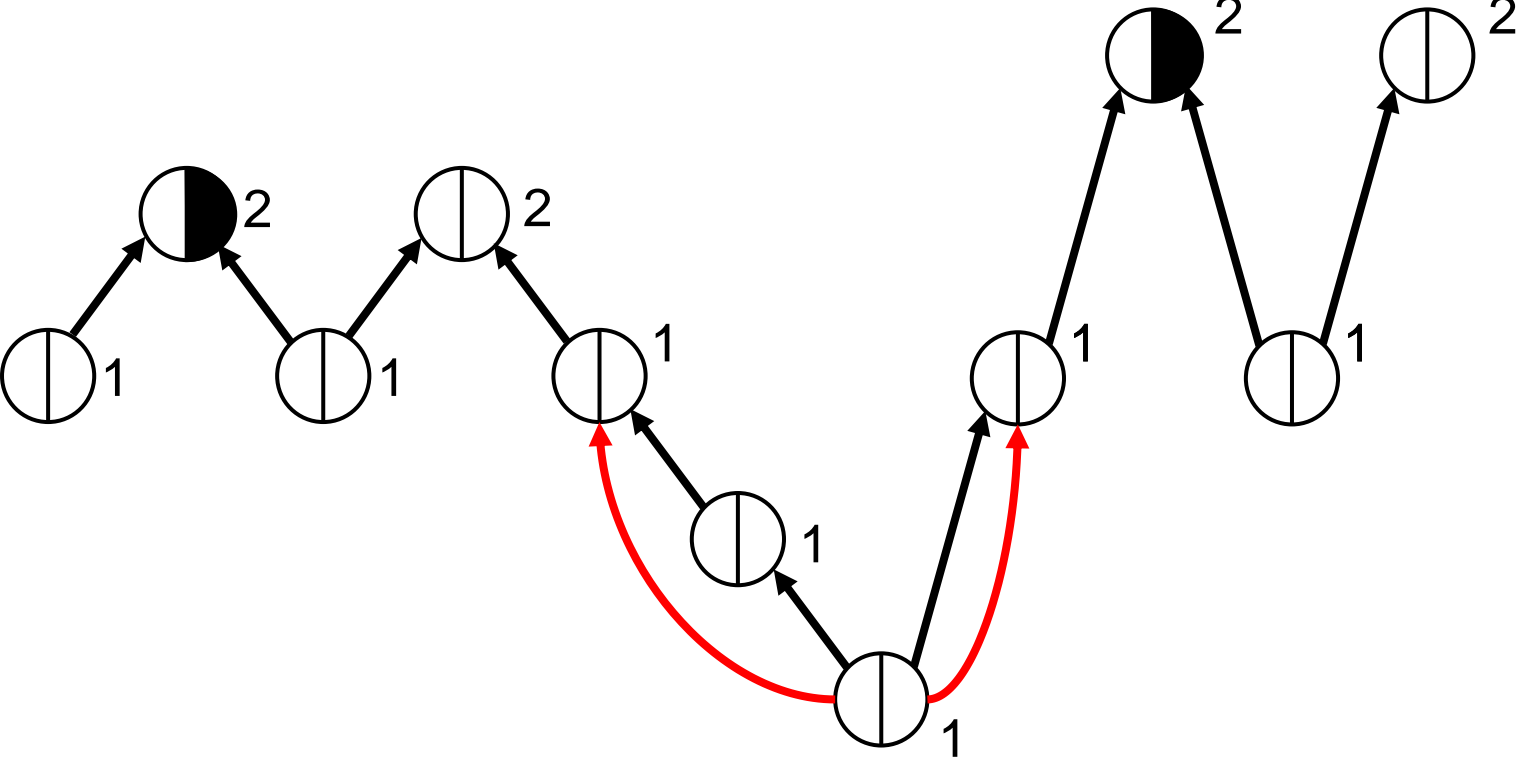
## Option 2

- $F$  is a local rule s.t.  

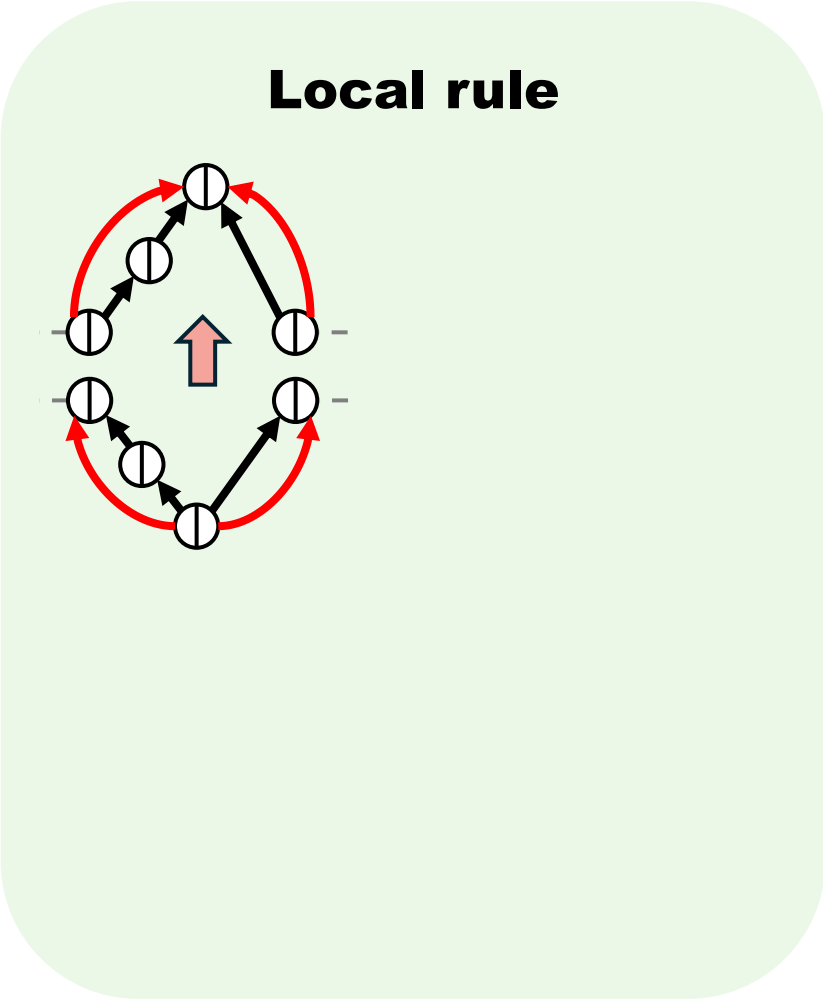
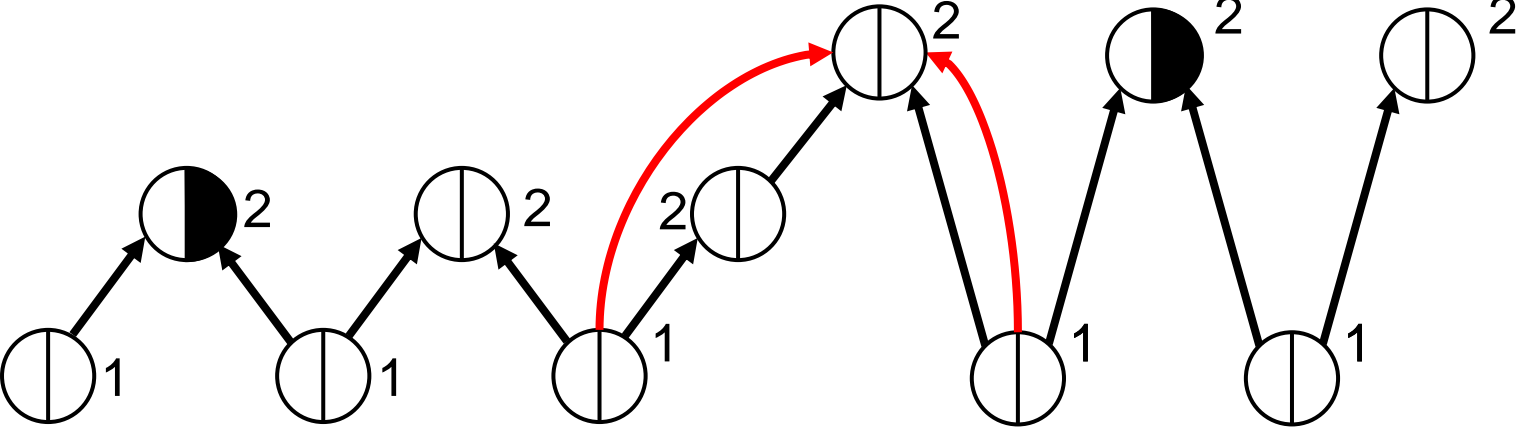
$$F_x A_x G = G$$
- Then it must be s.t.  

$$A_x F_x G' = G'$$

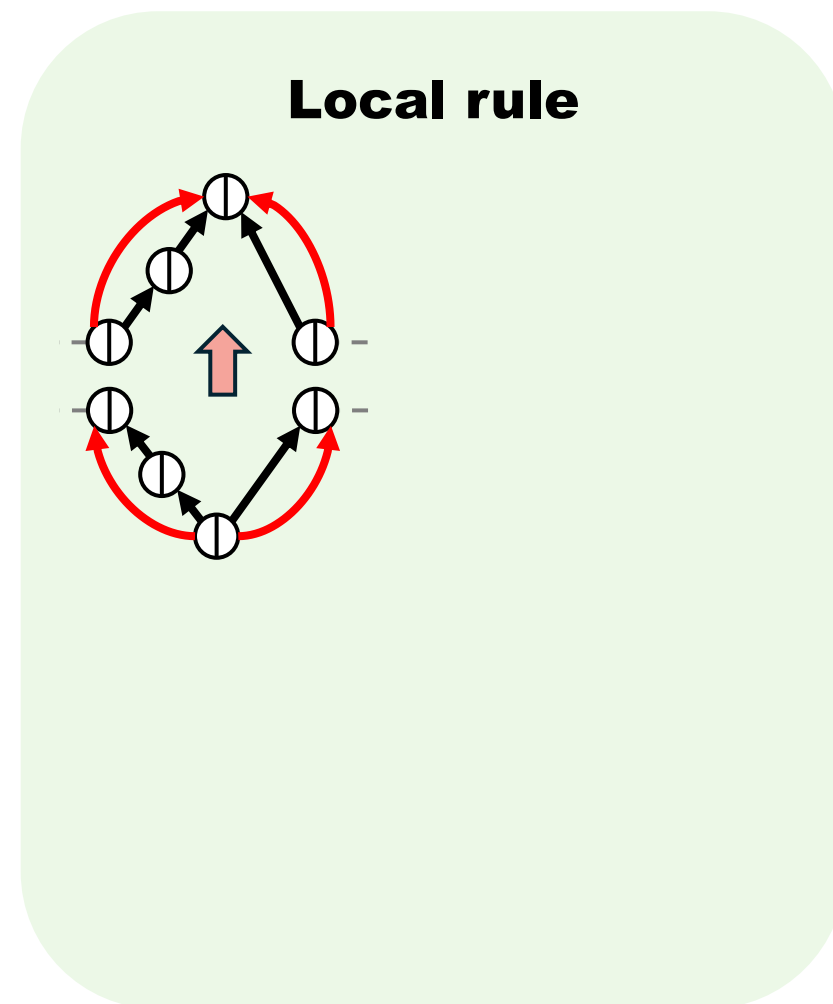
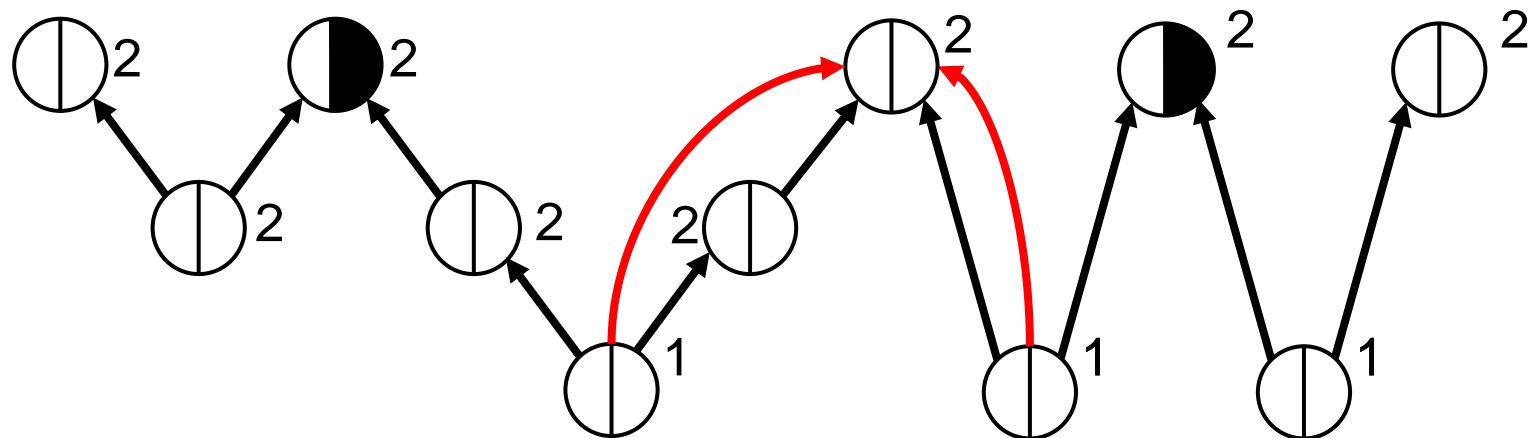
# Reversible time dilation



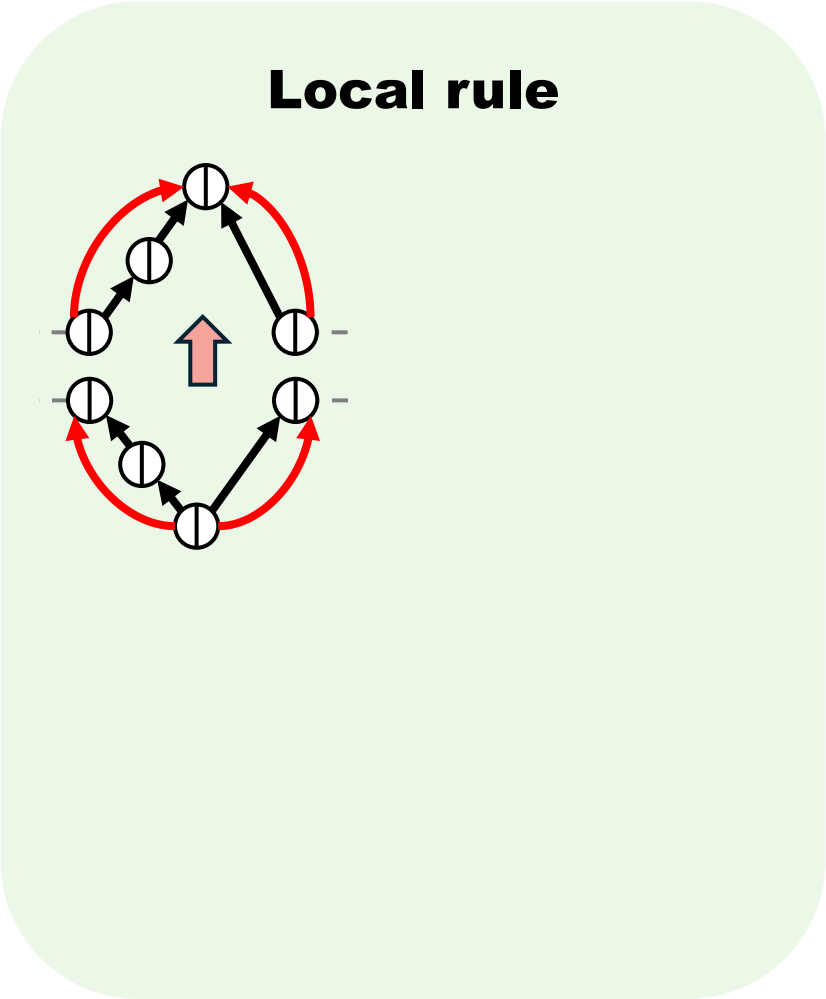
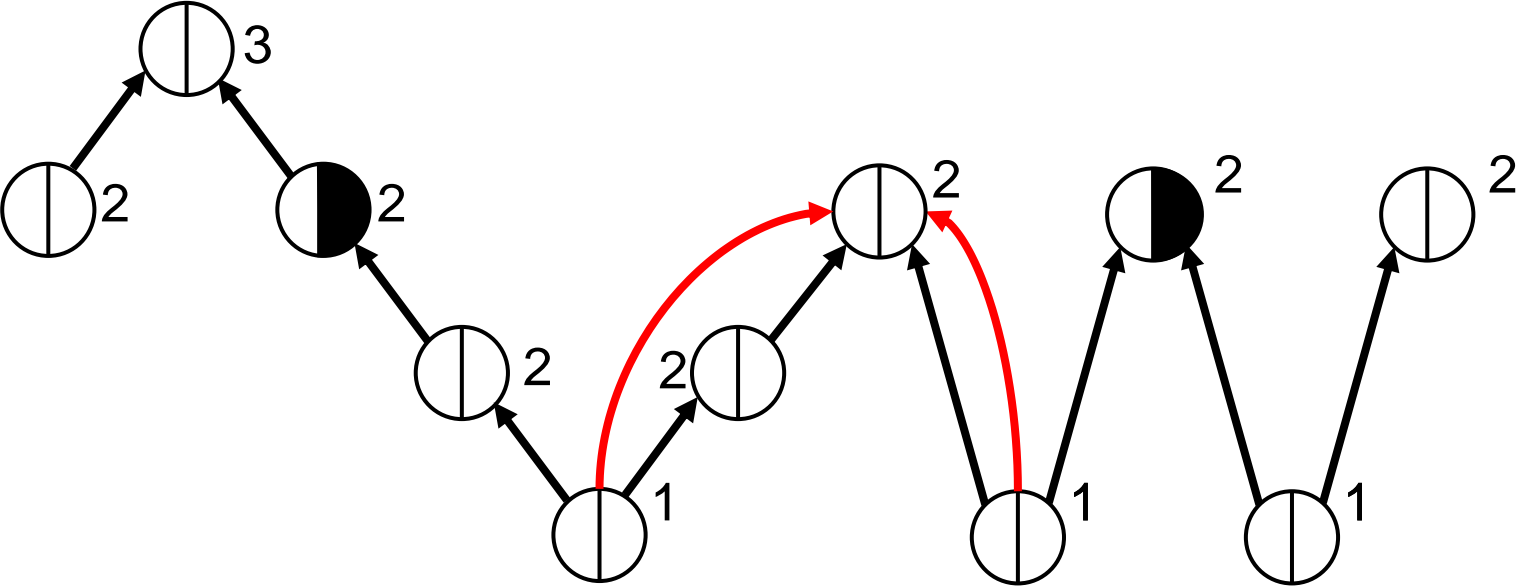
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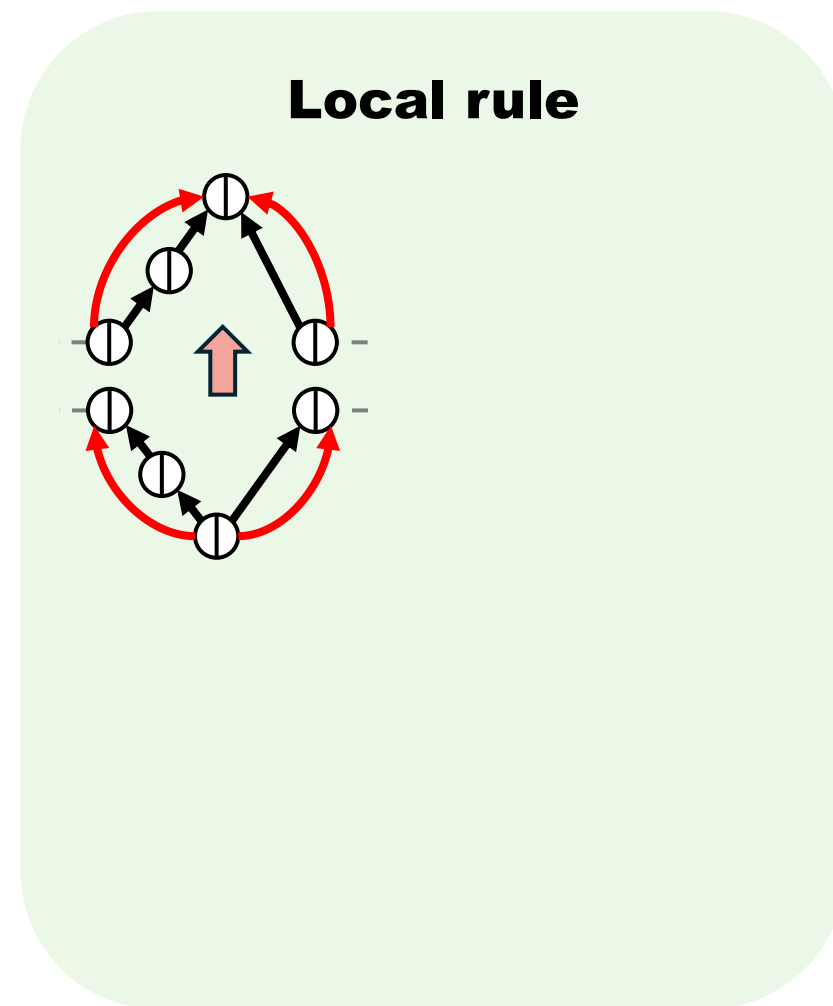
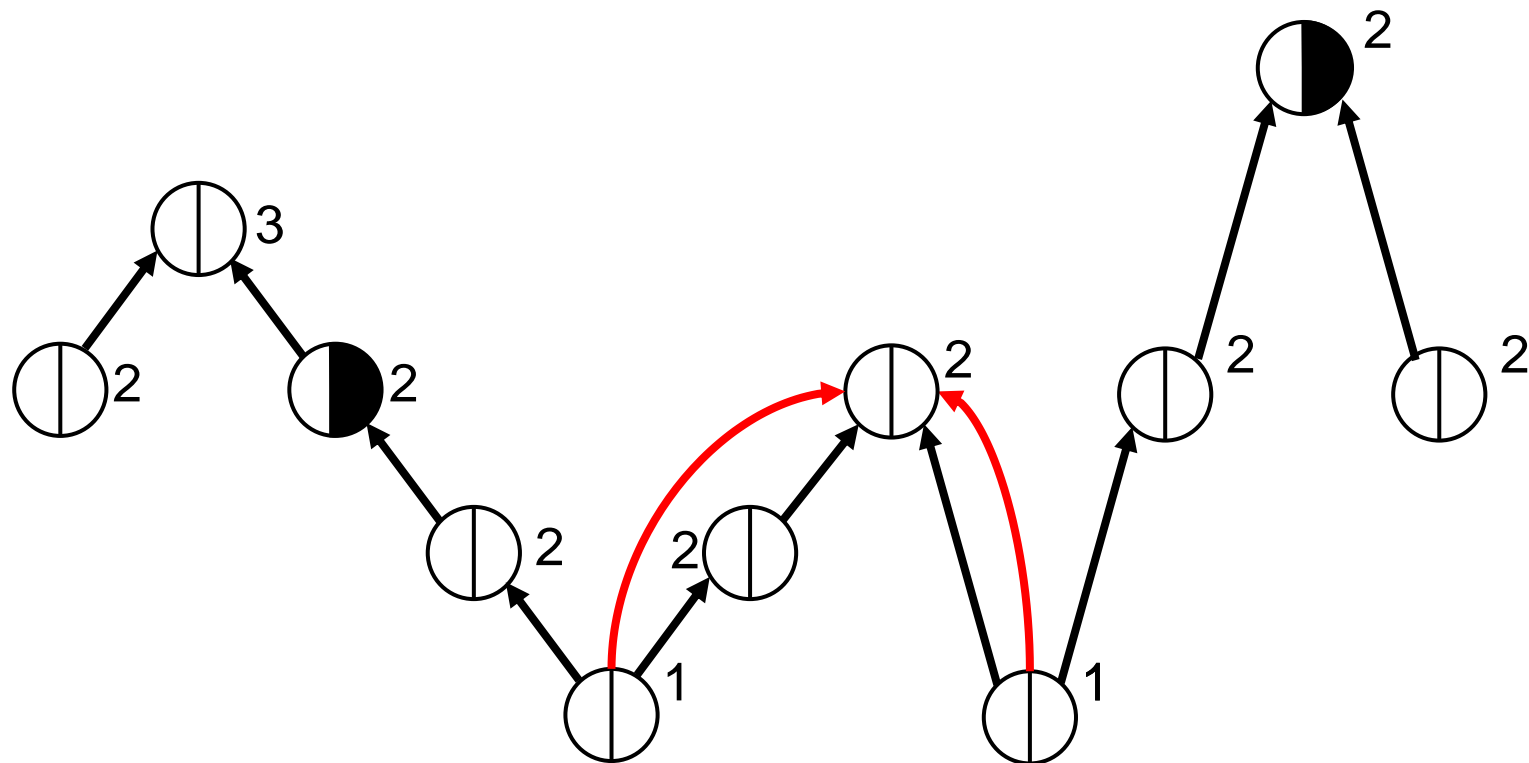
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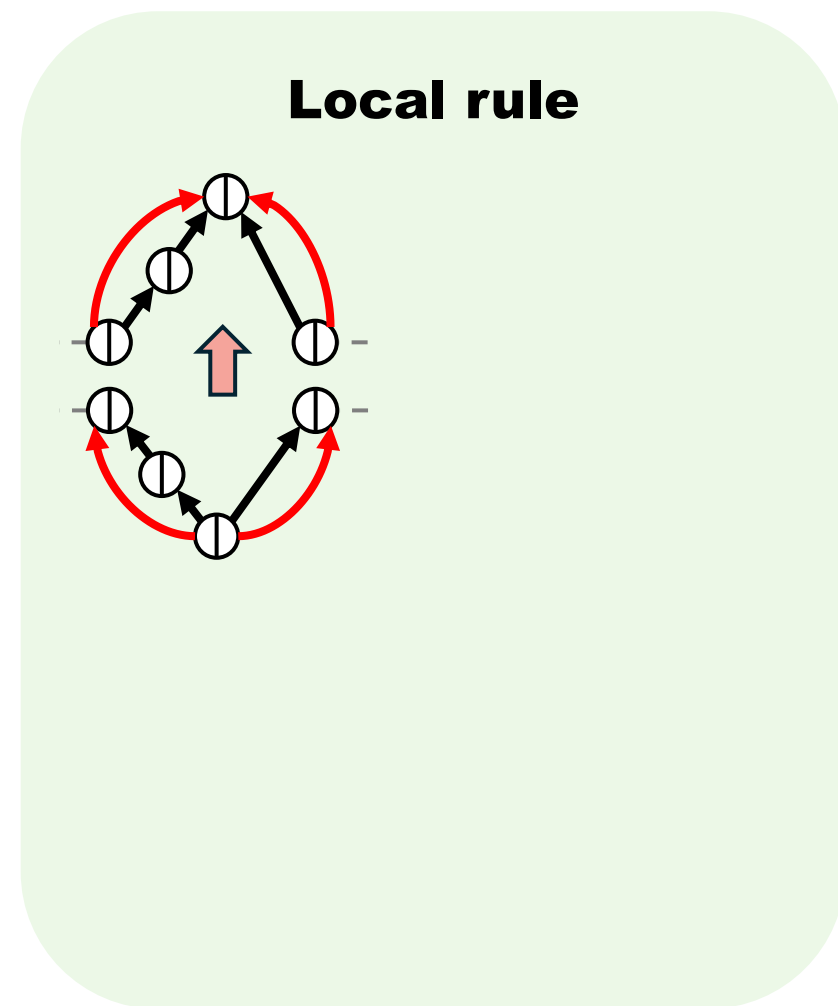
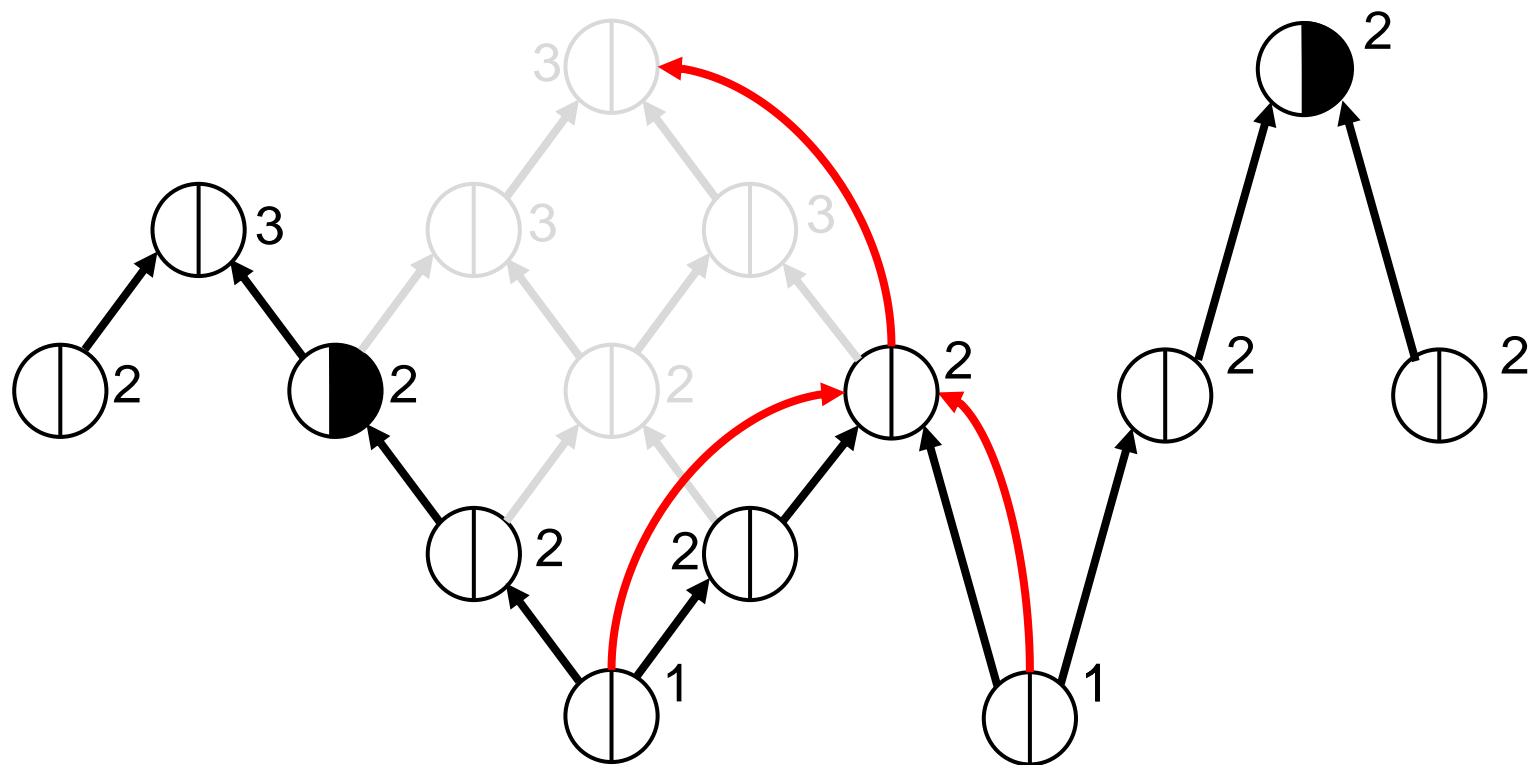


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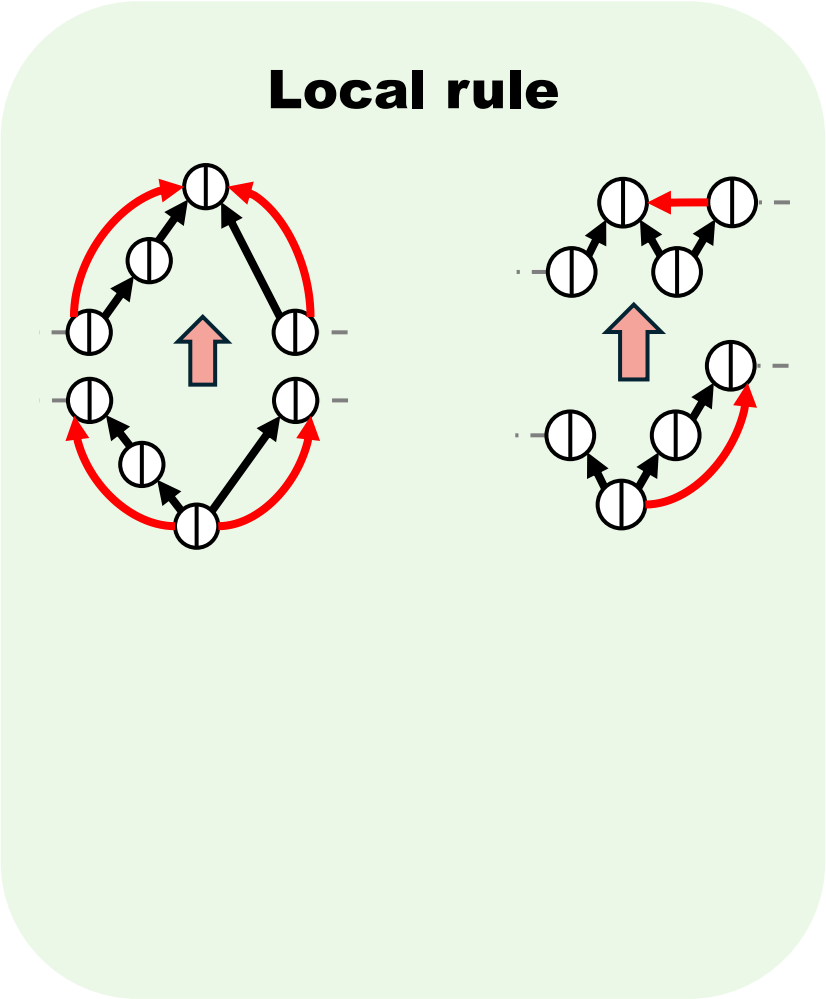
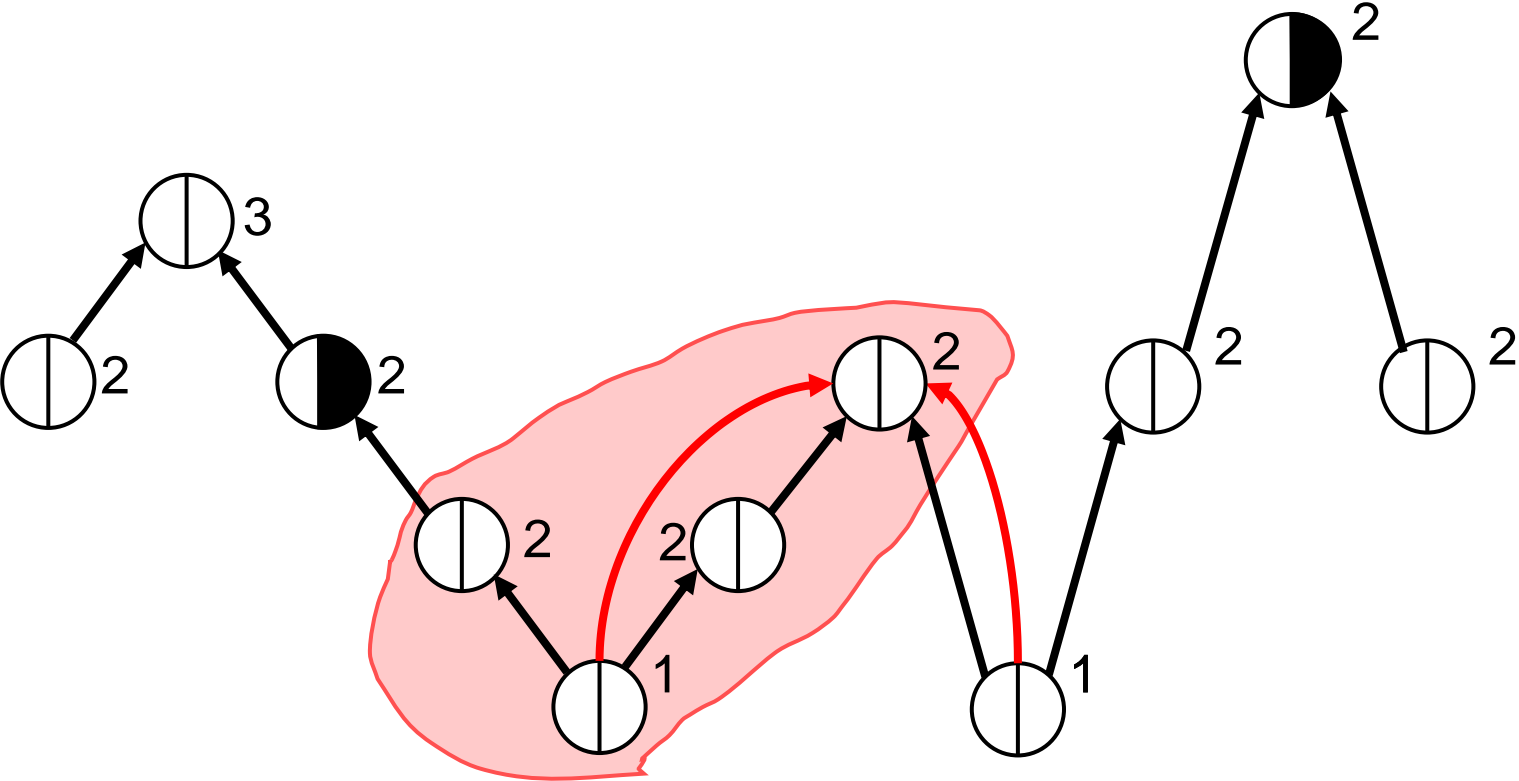




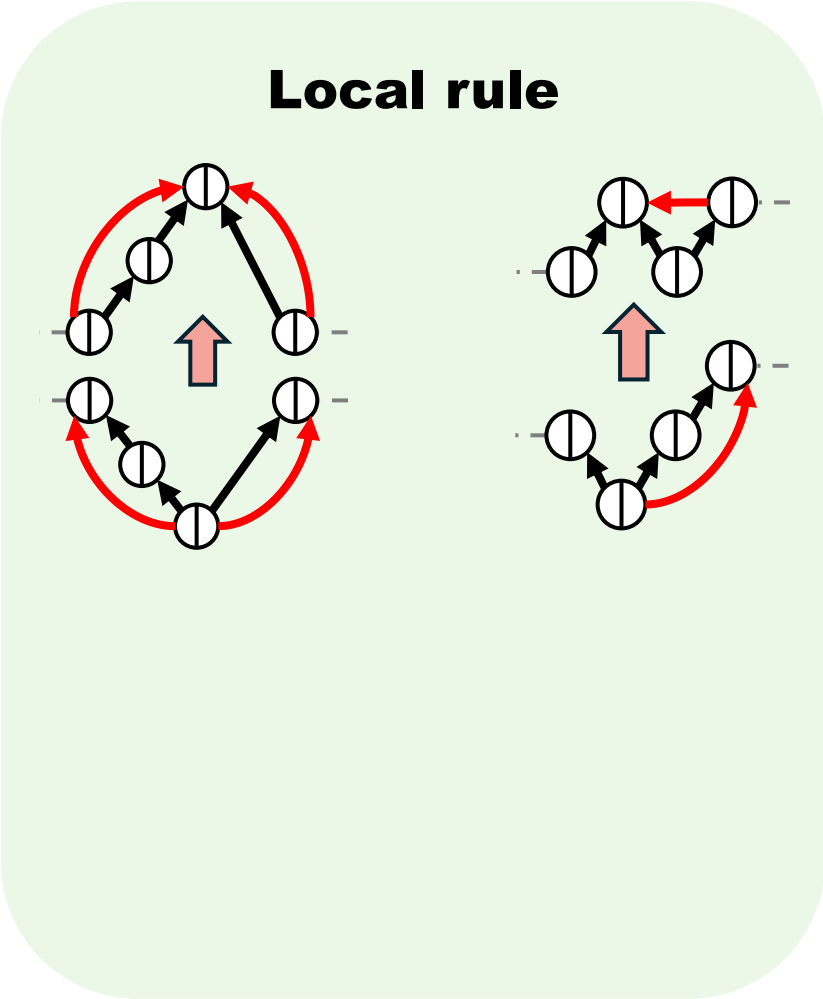
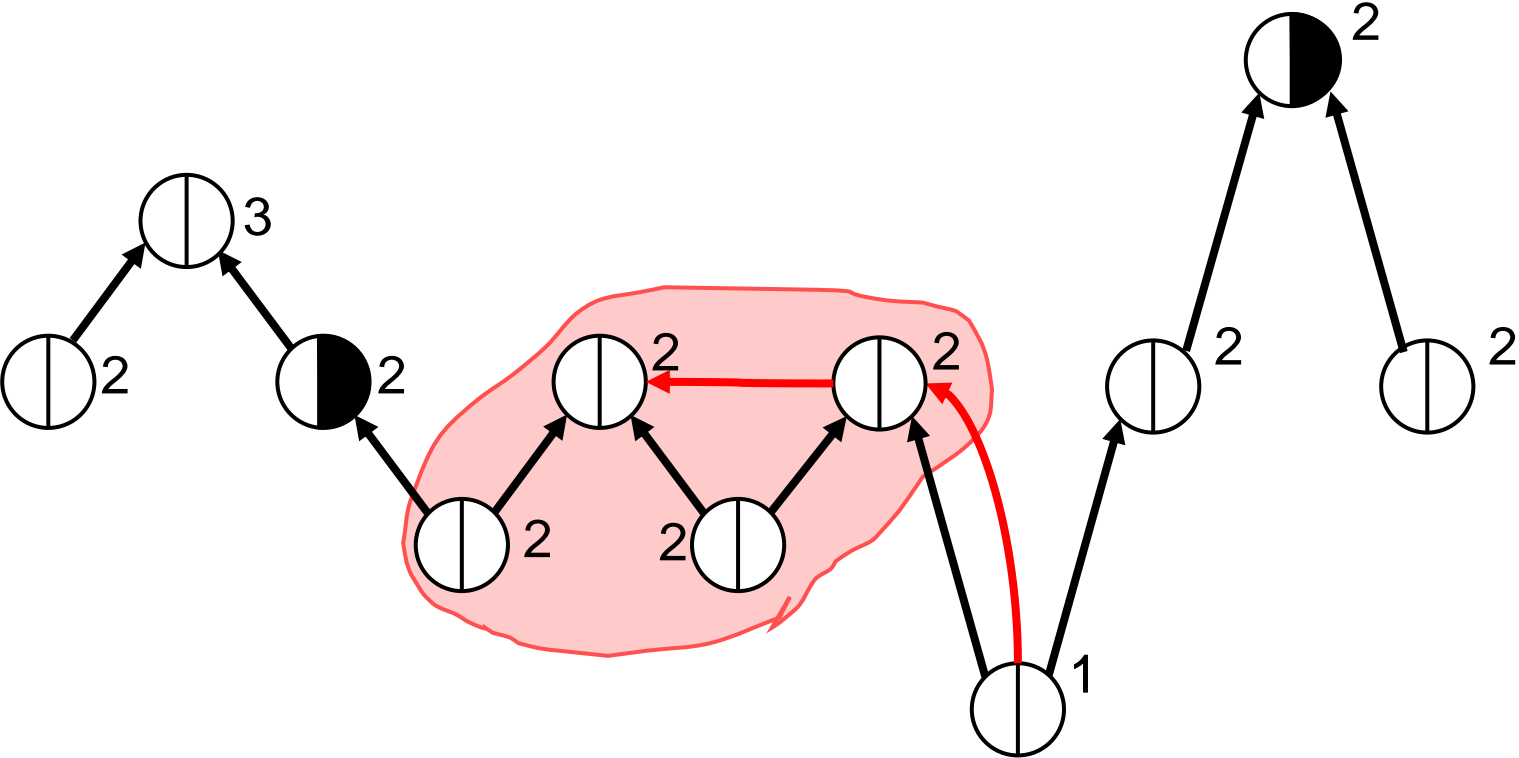
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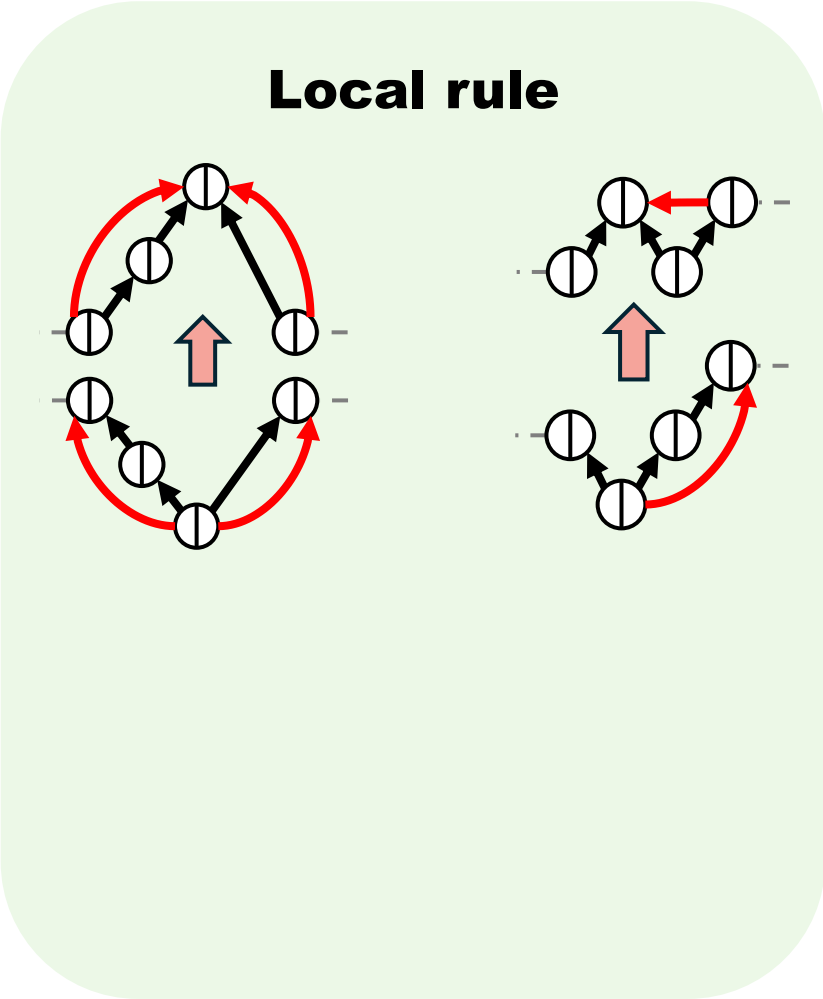
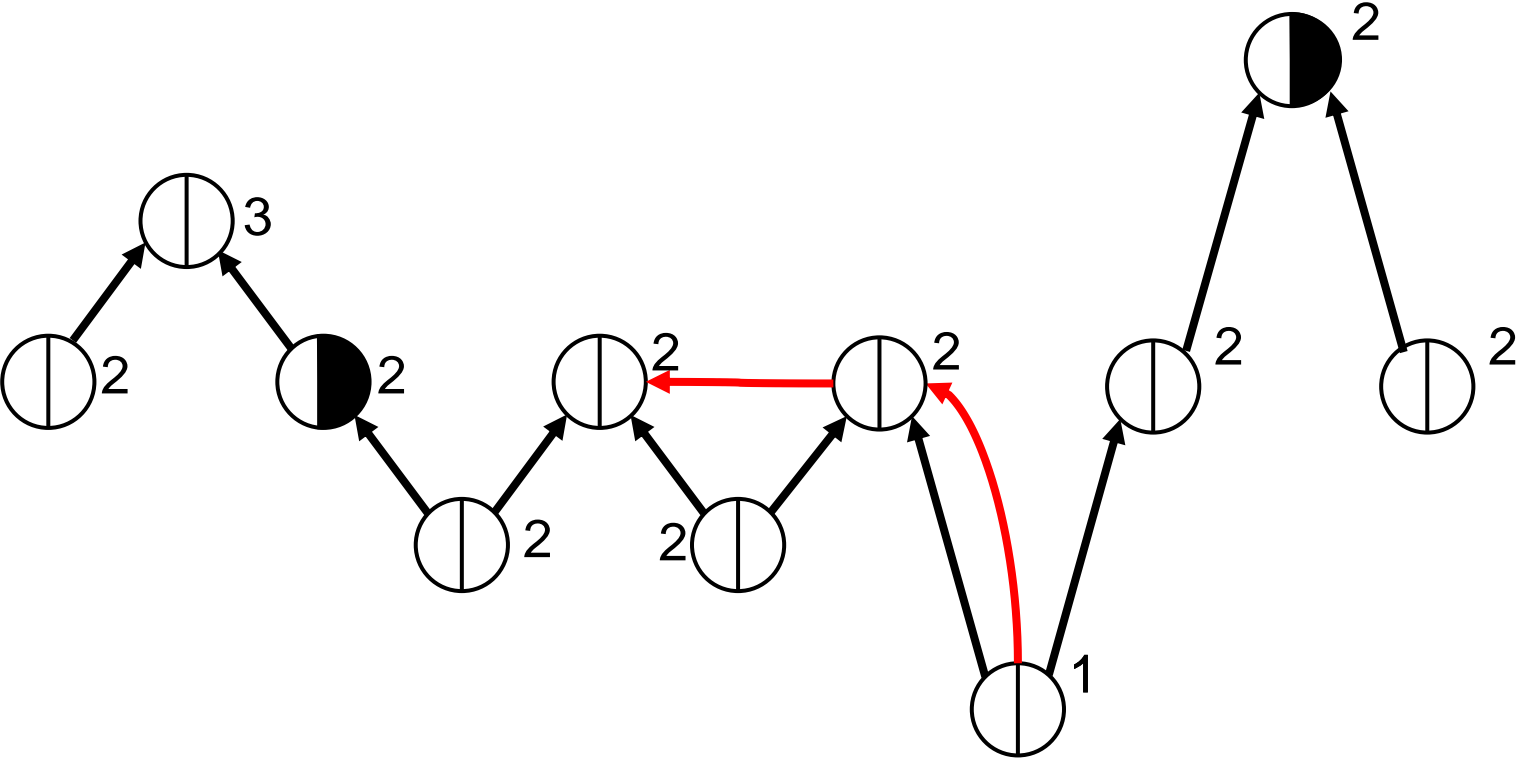
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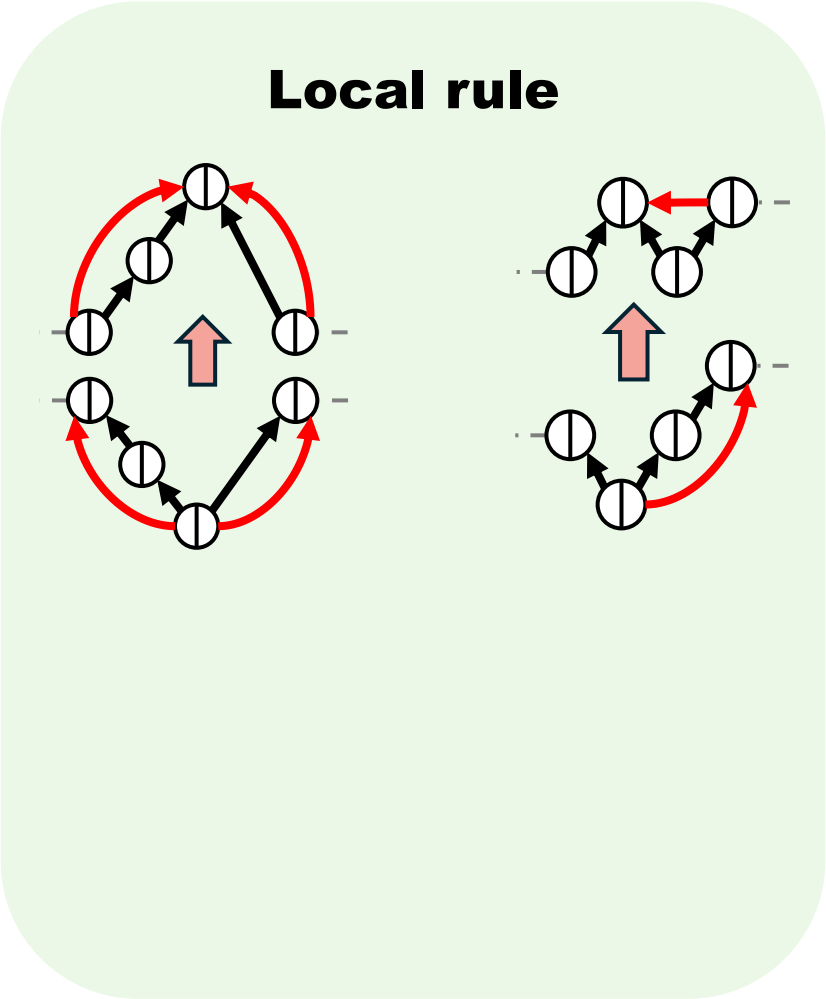
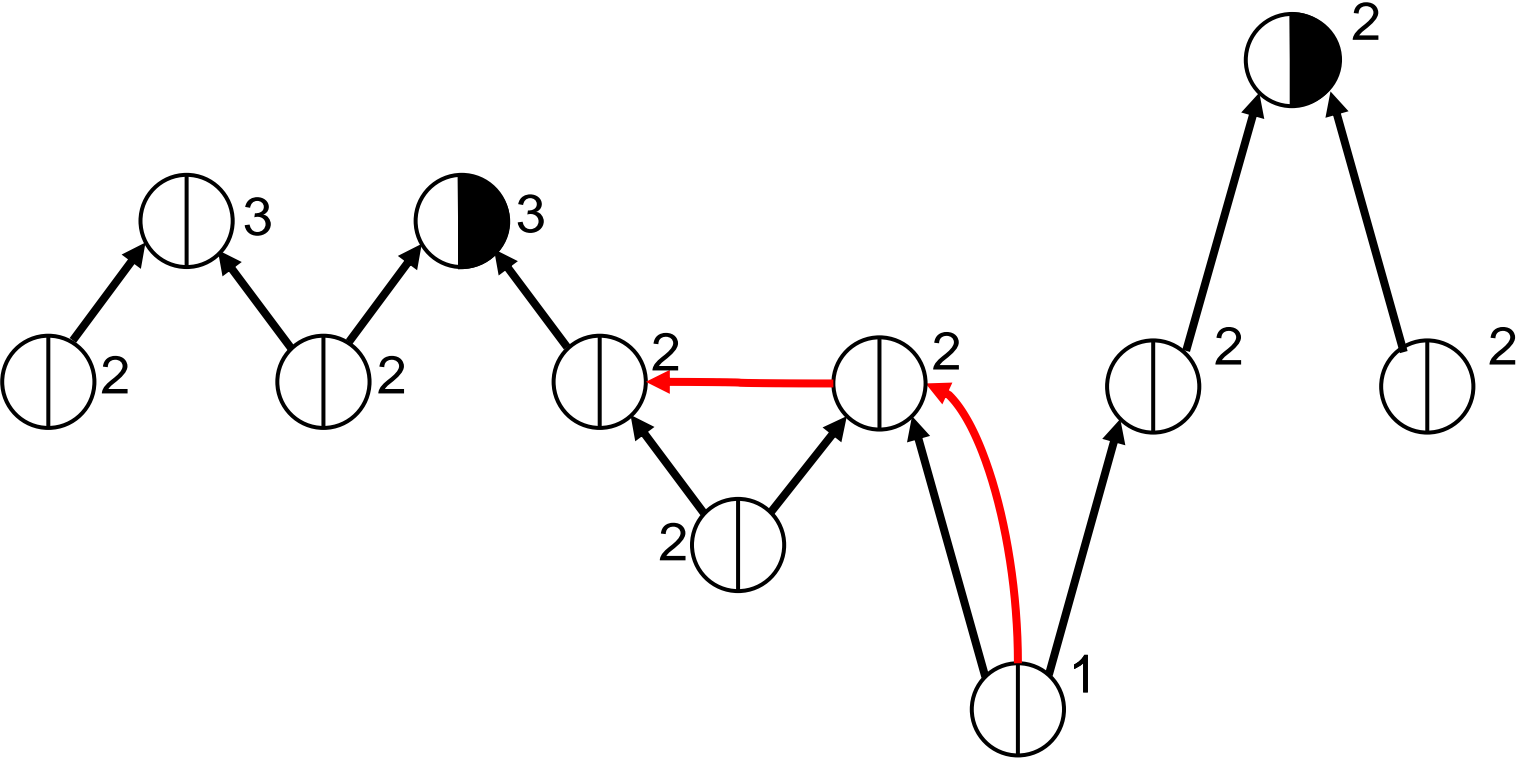
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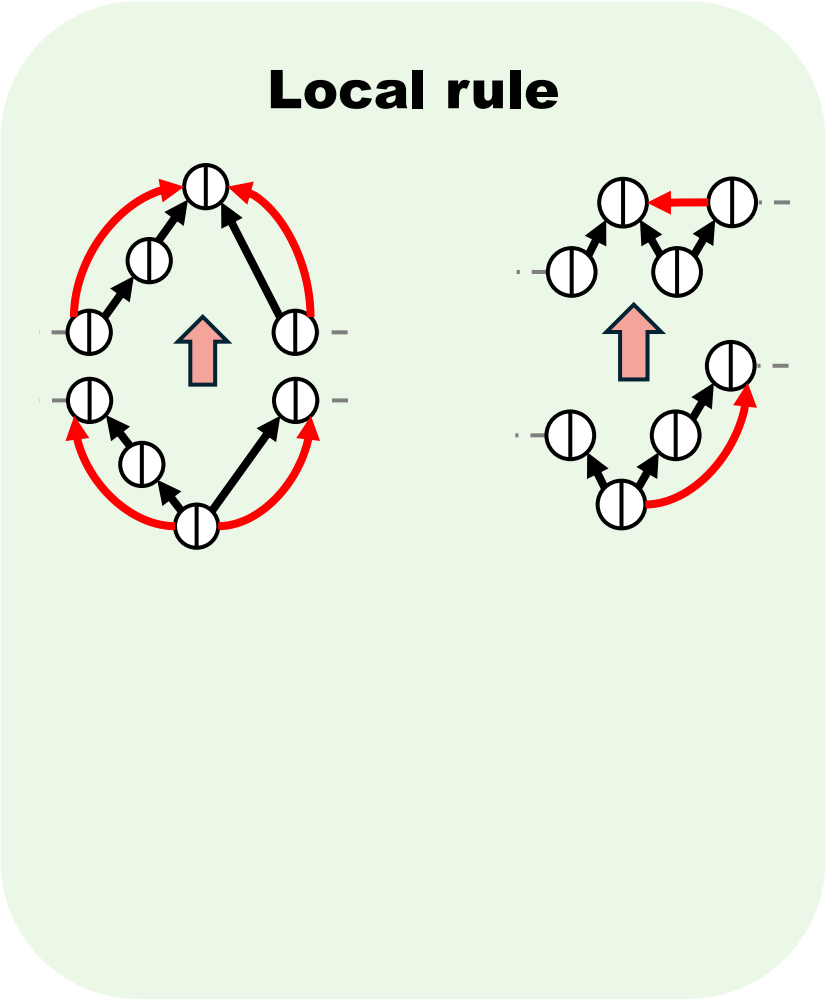
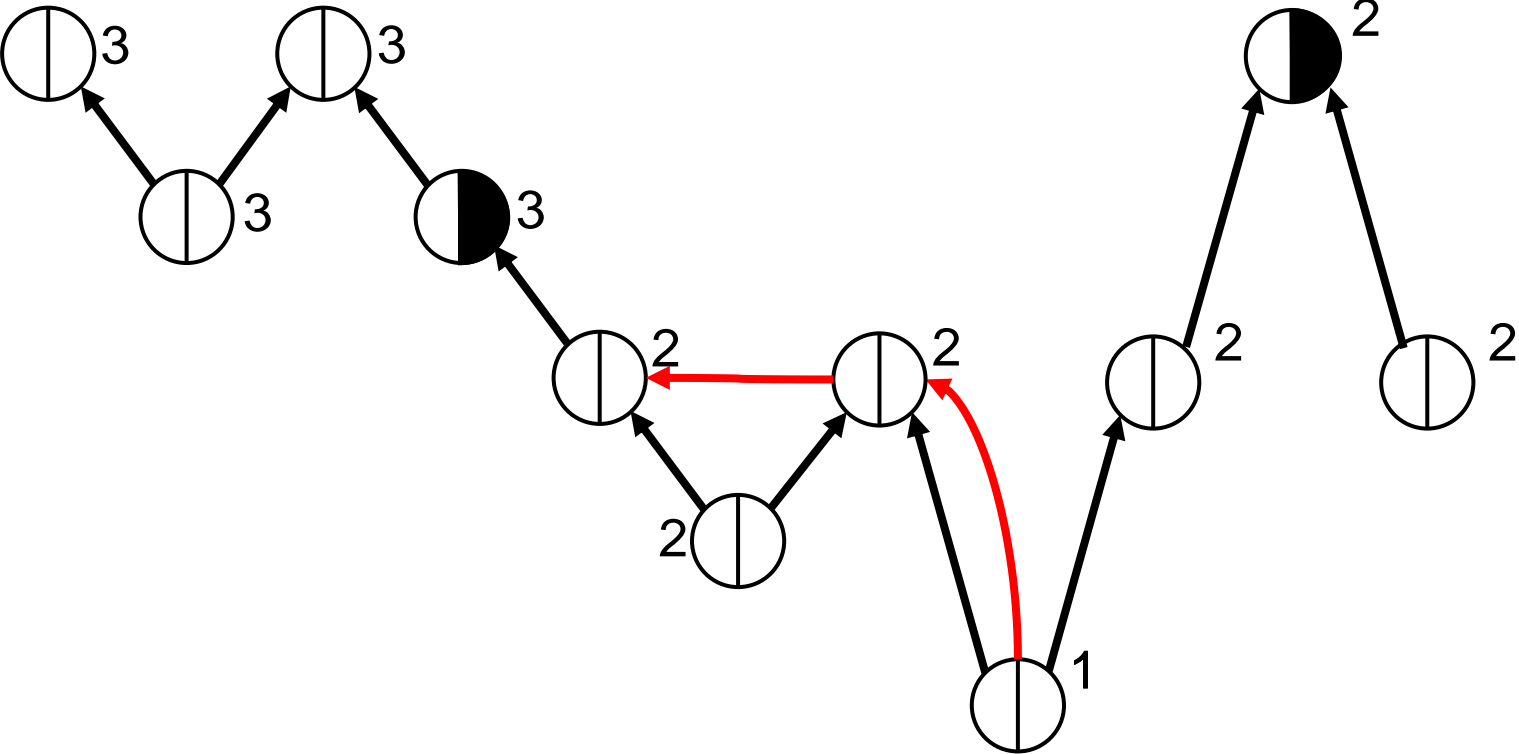
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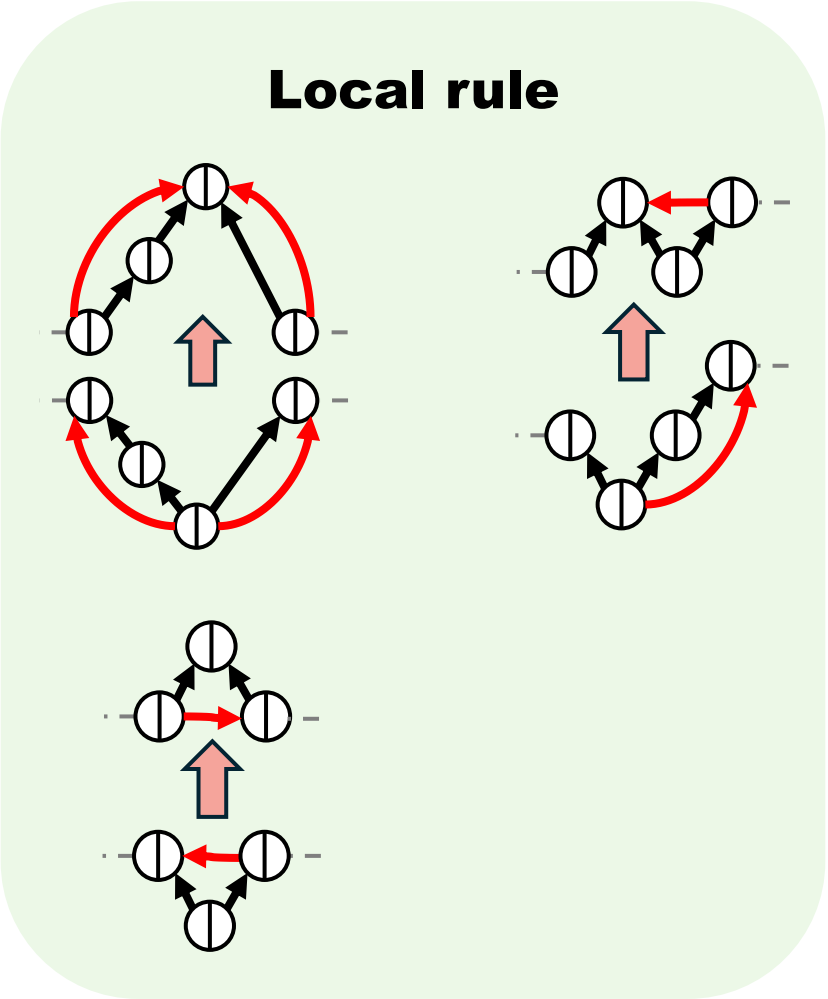
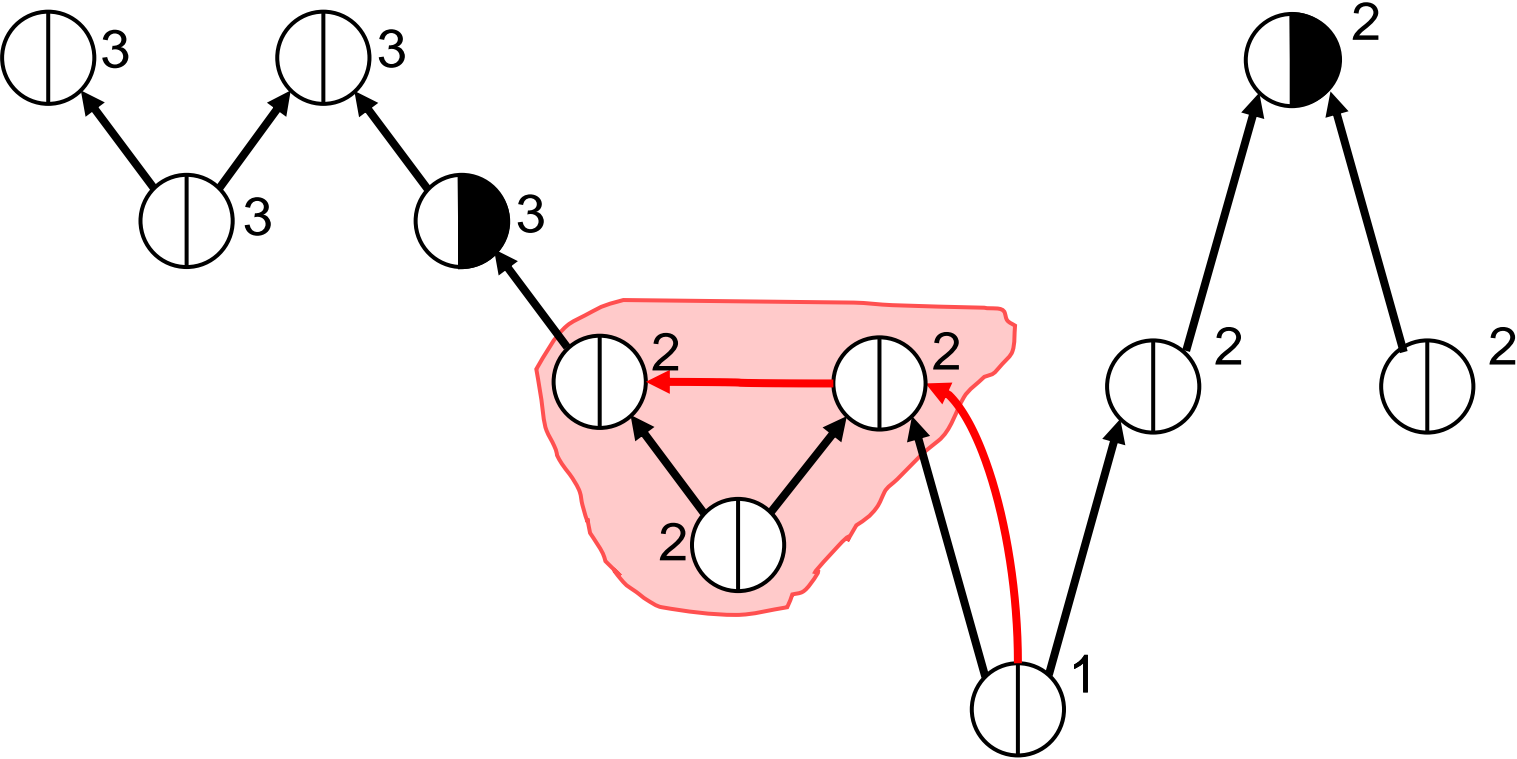
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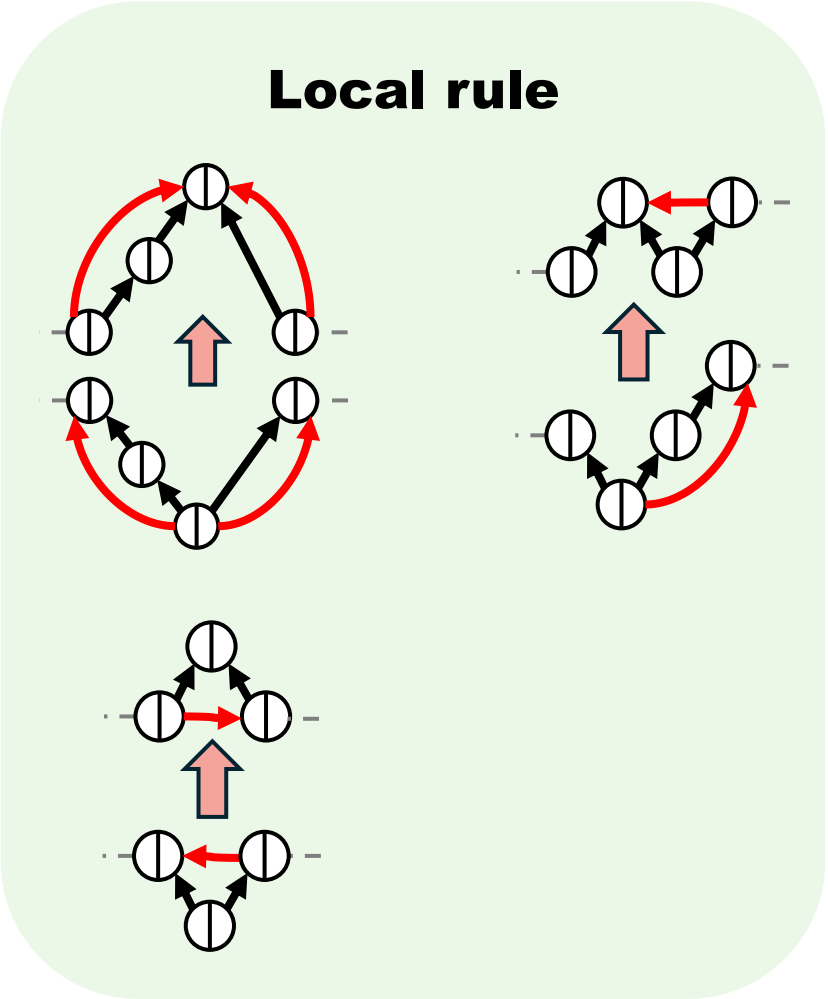
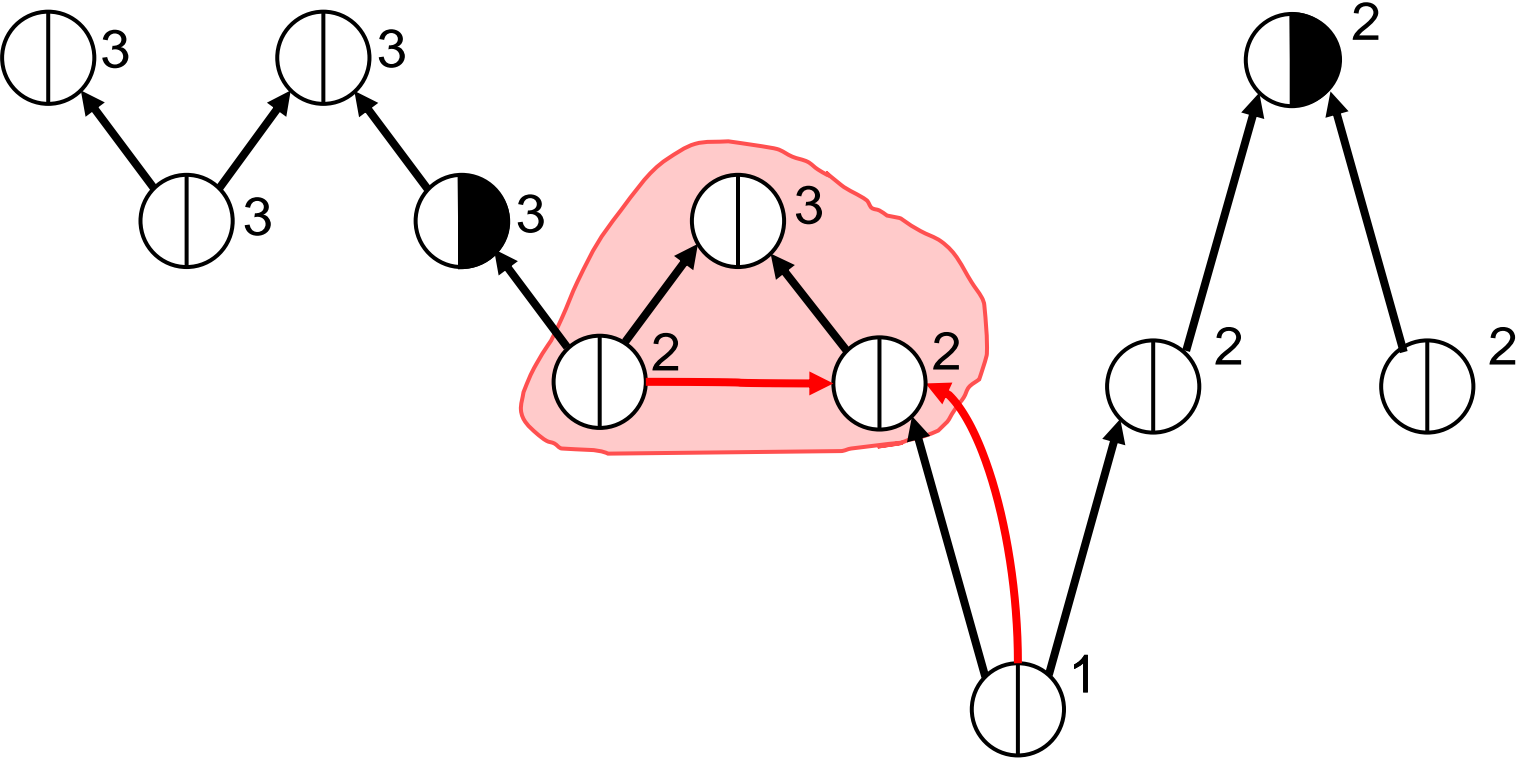
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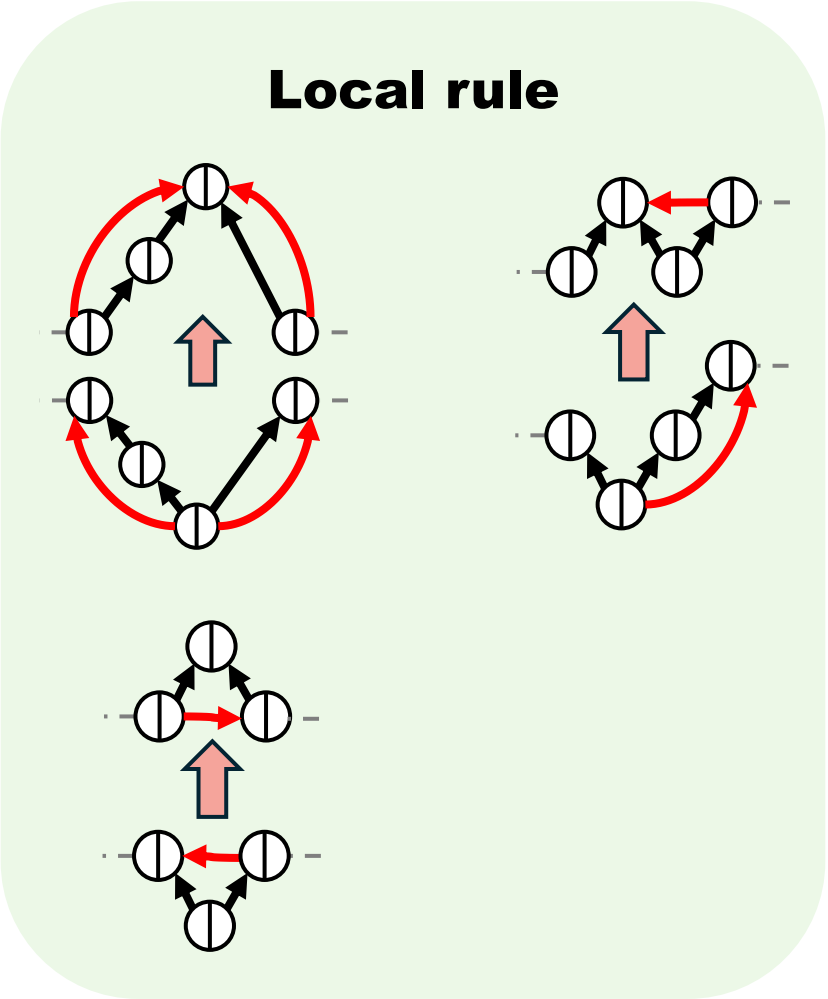
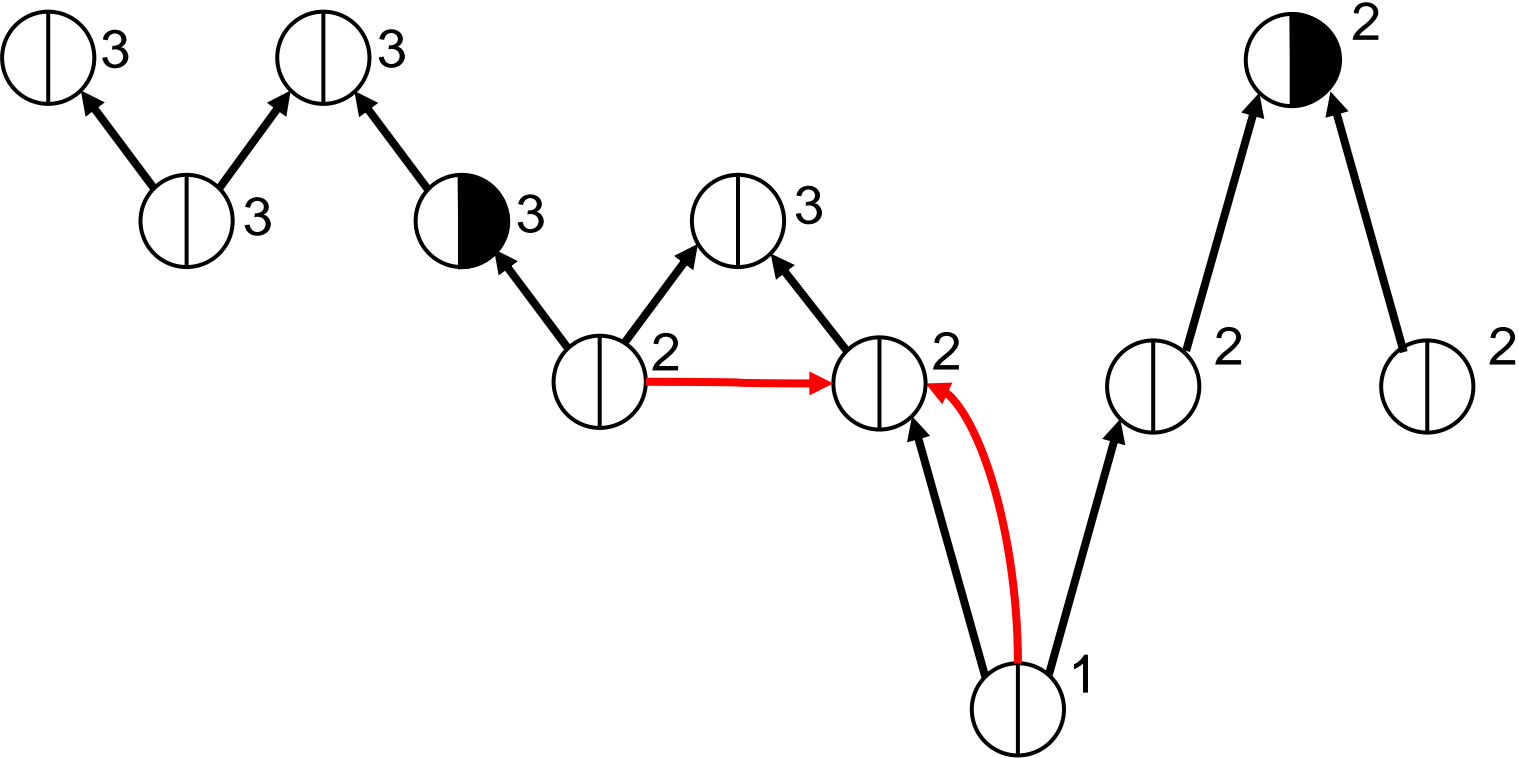


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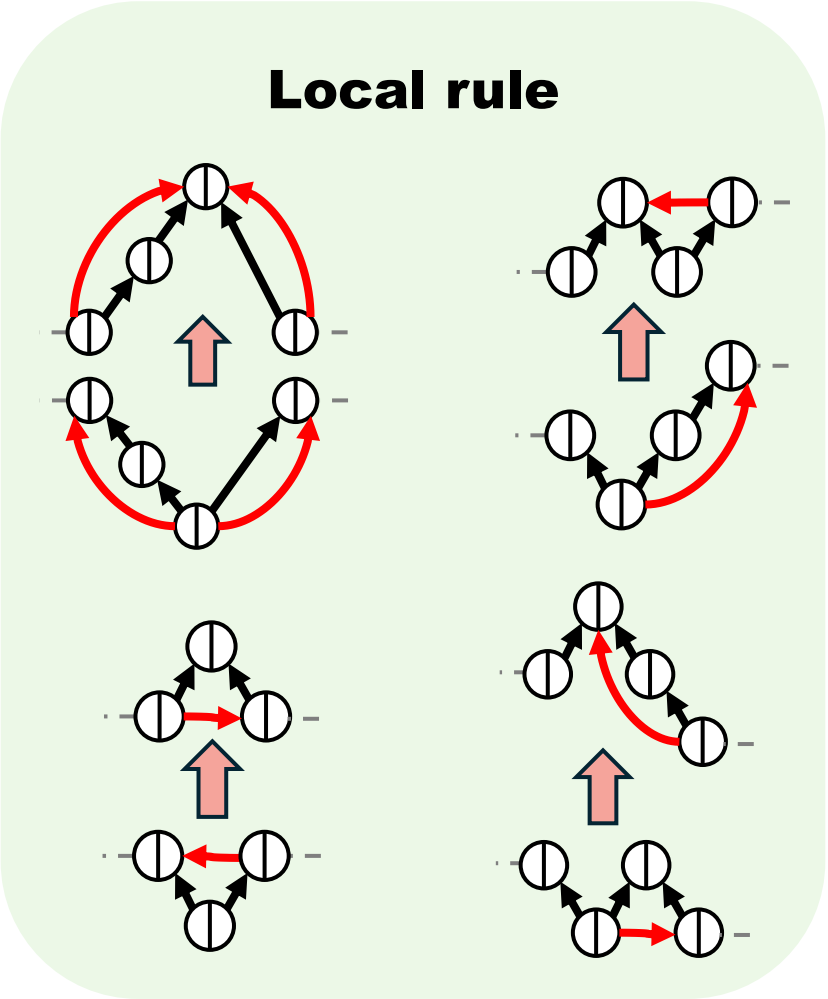
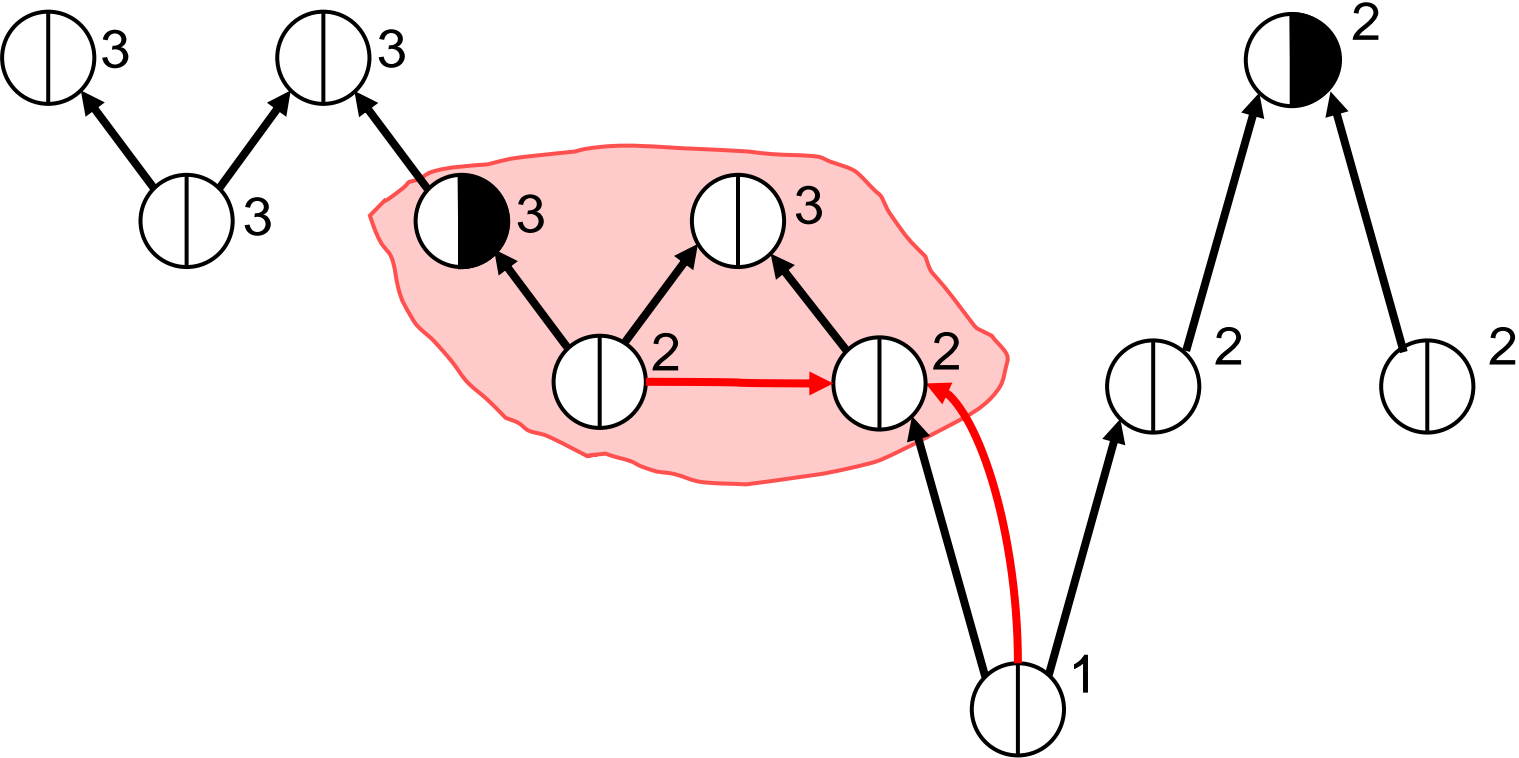




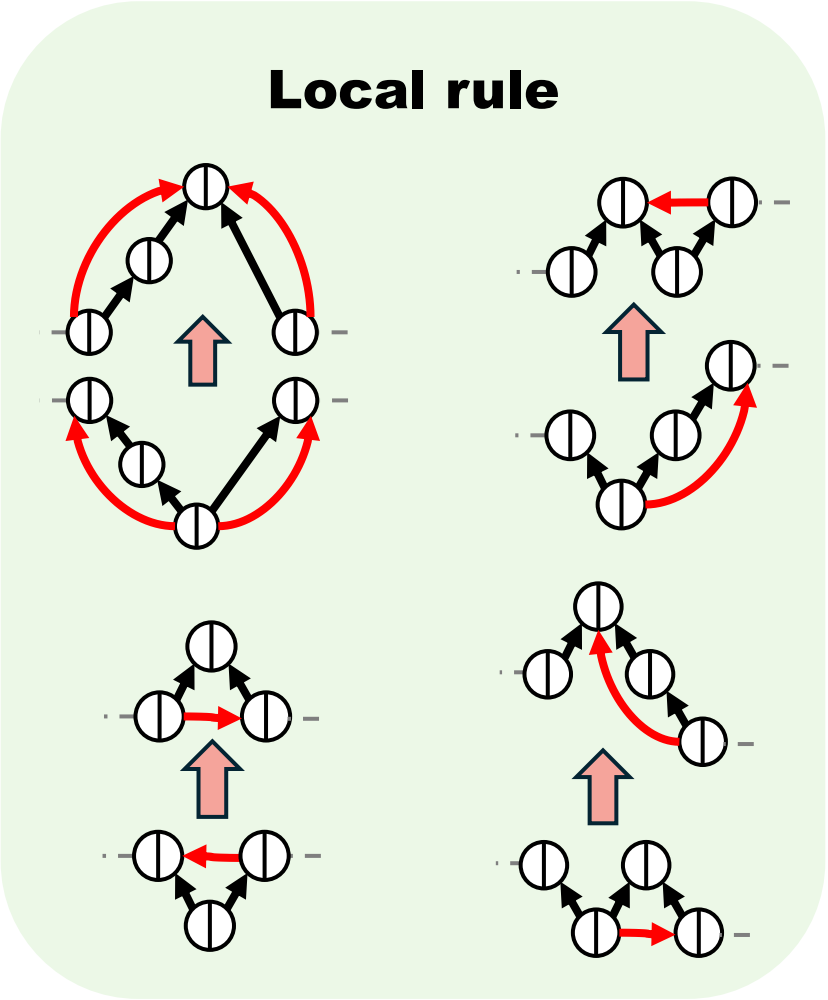
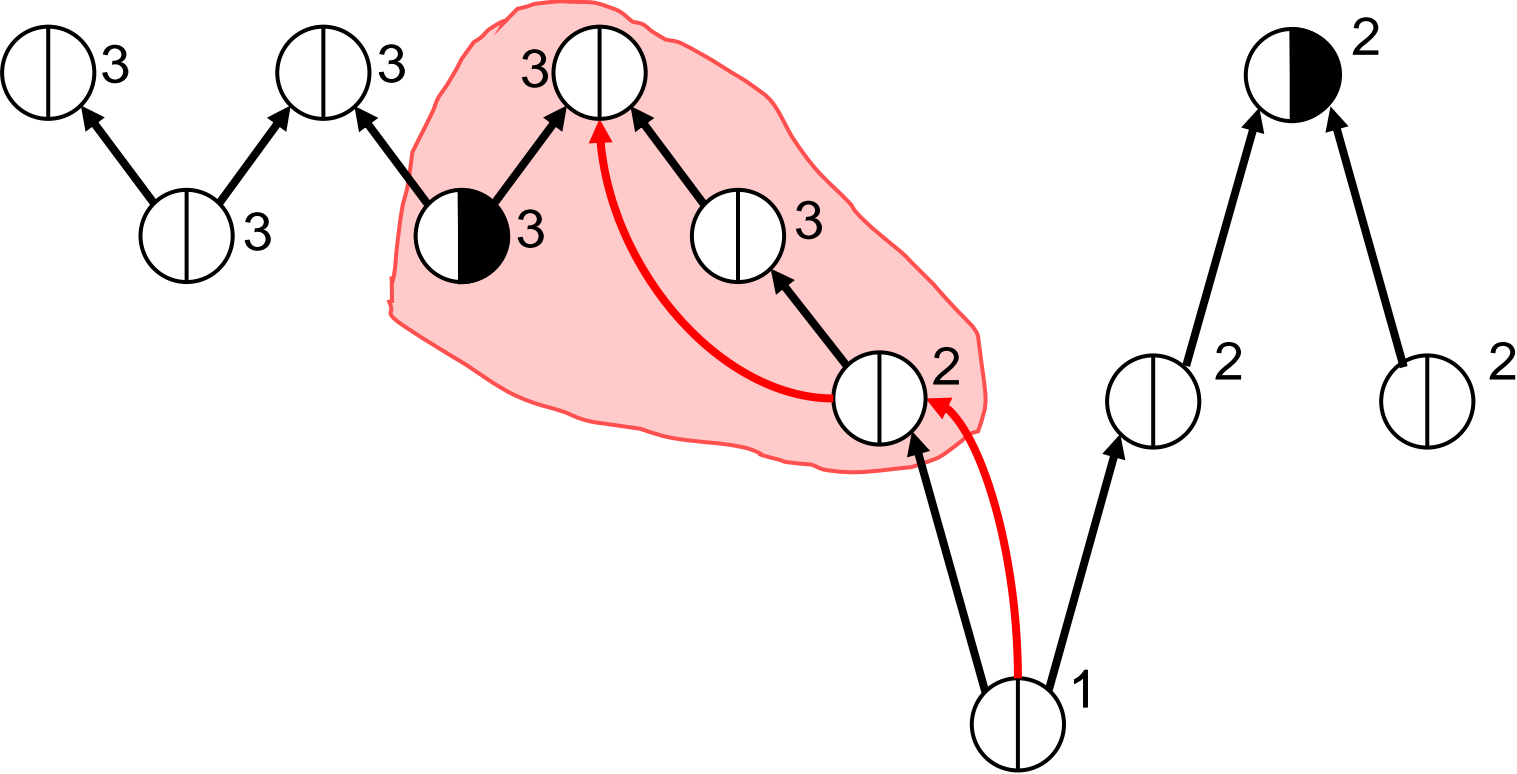
# Reversible time dilation



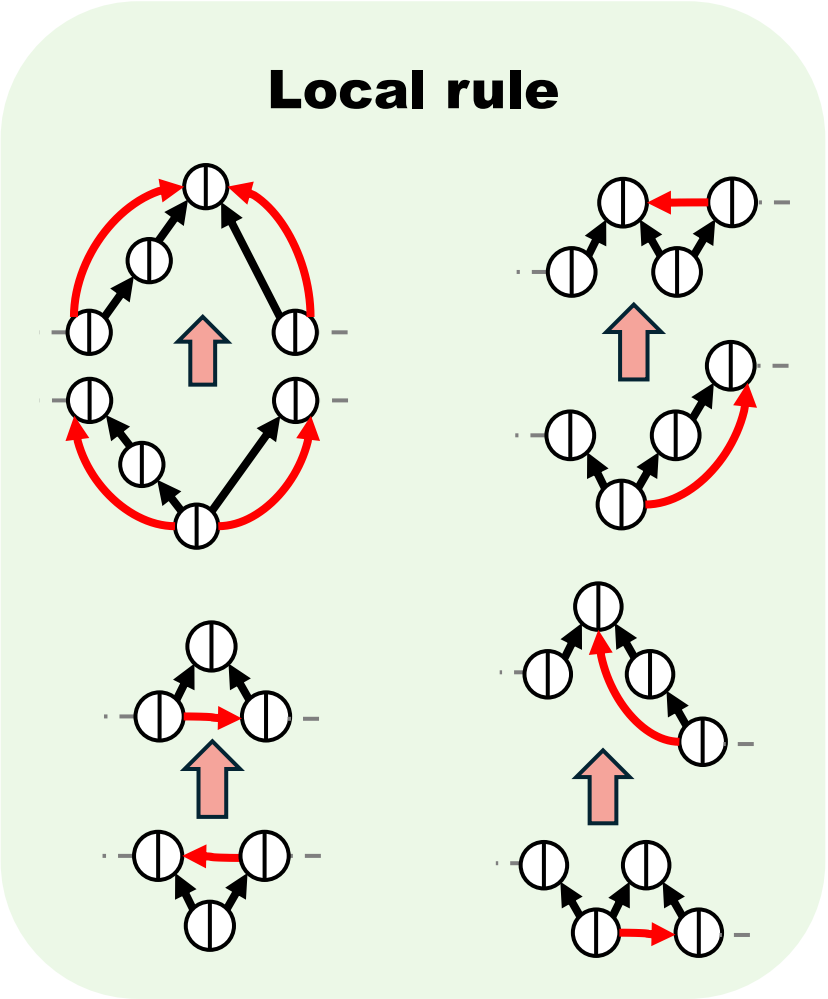
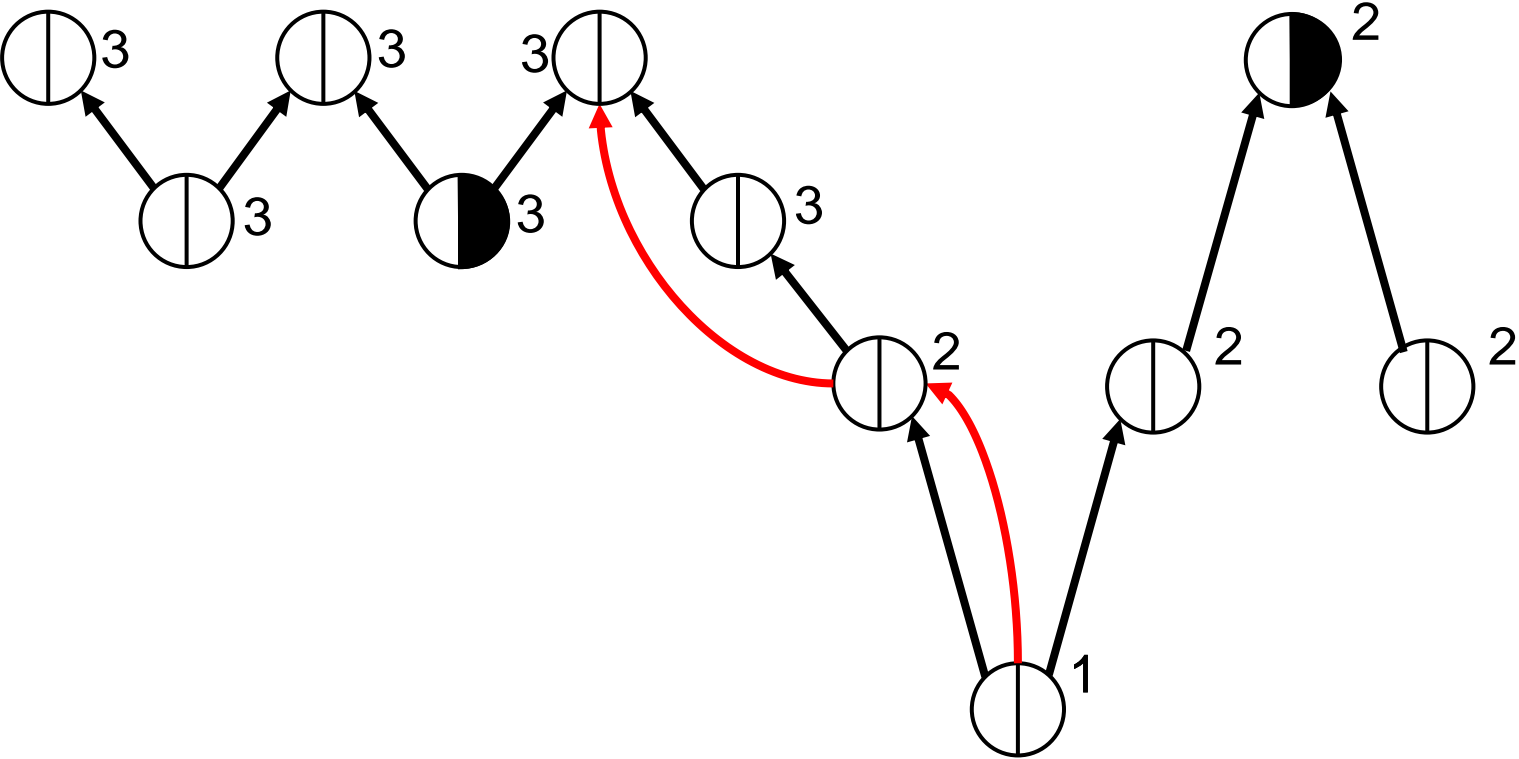
# Reversible time dilation



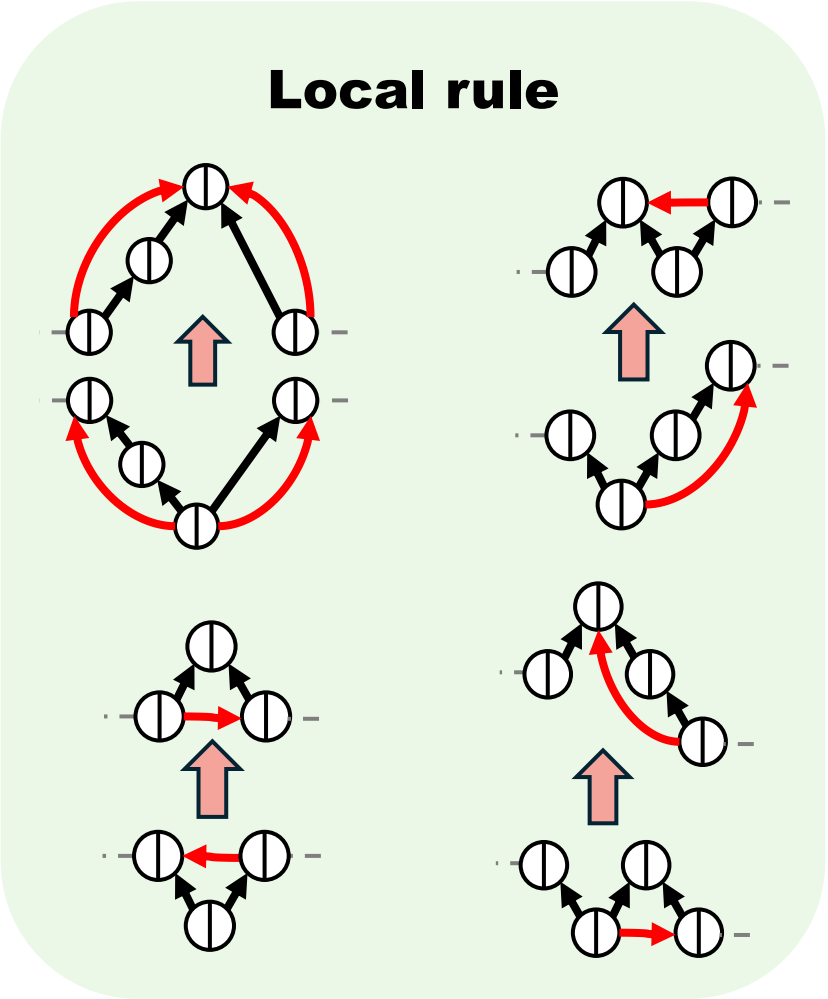
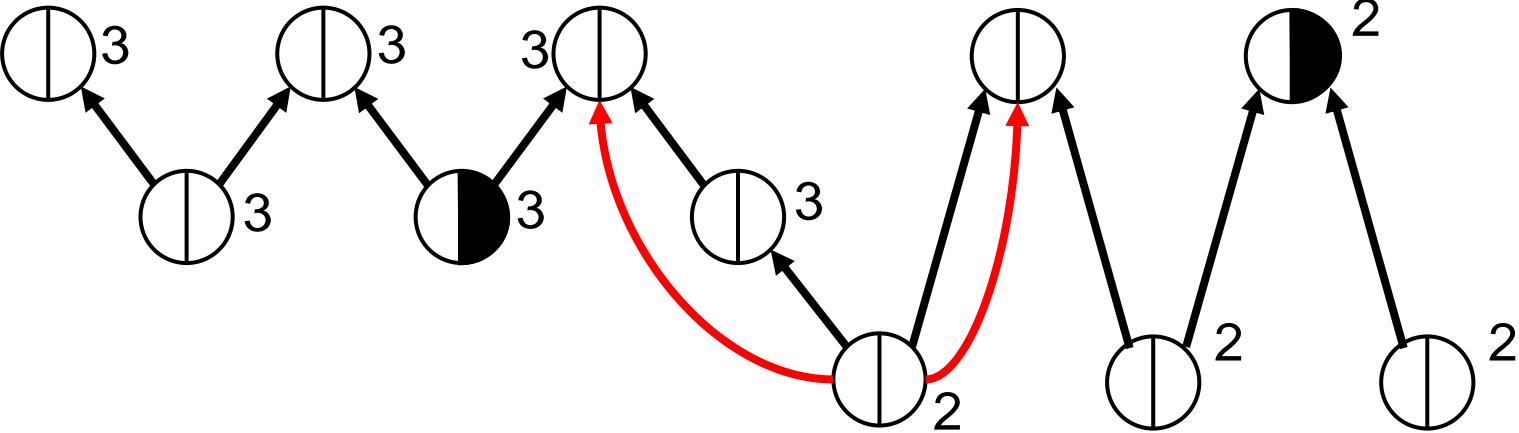
# Reversible time dilation



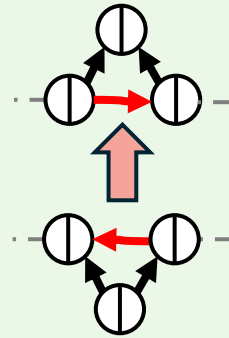
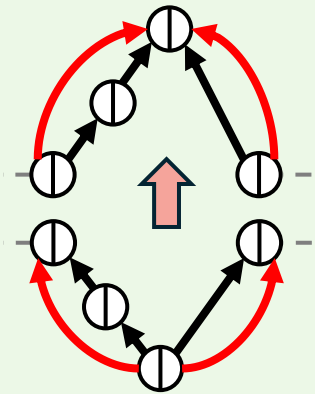
# Reversible time dilation



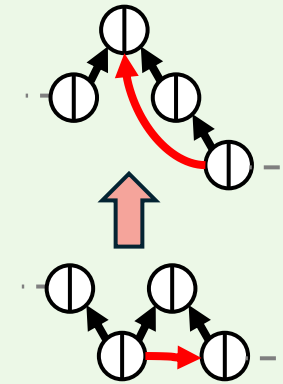
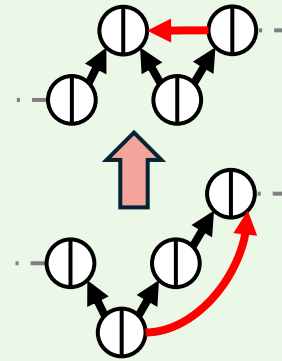
# Reversible time dilation



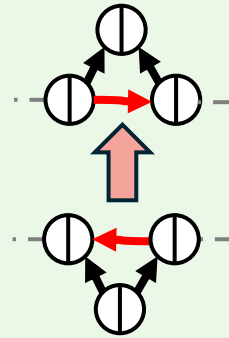
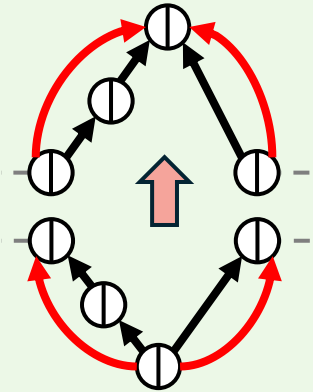
# Is this really reversible ?



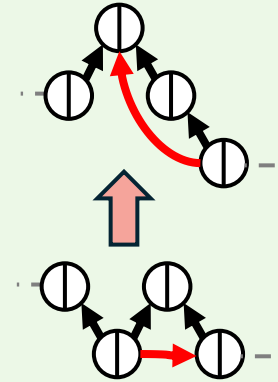
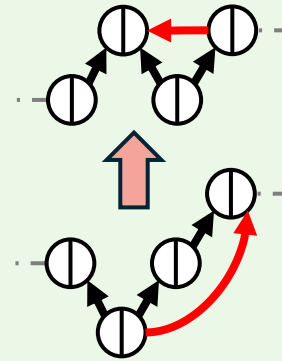
**Local rule**



# Is this really reversible ?



**Local rule**

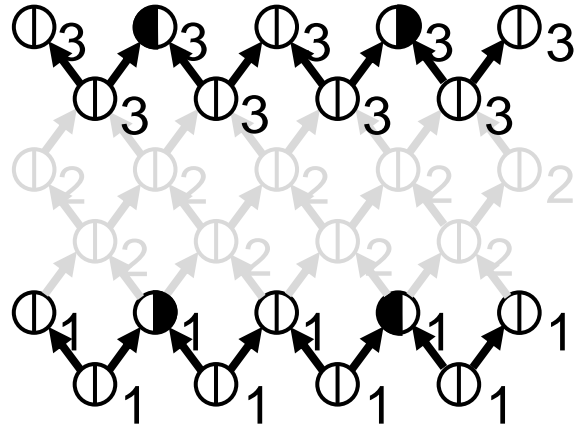


## **Theorem 2**

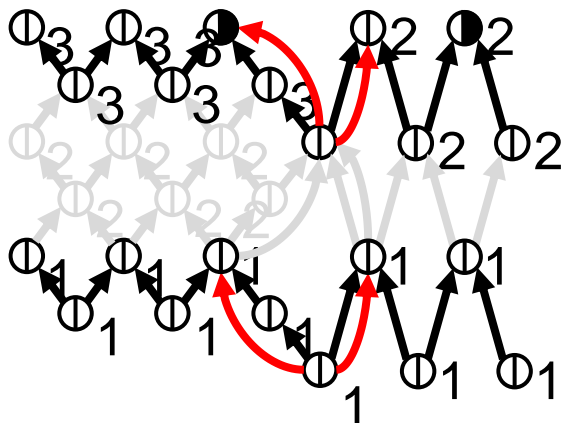
Any disk symmetric local rule is reversible.

# Conclusion

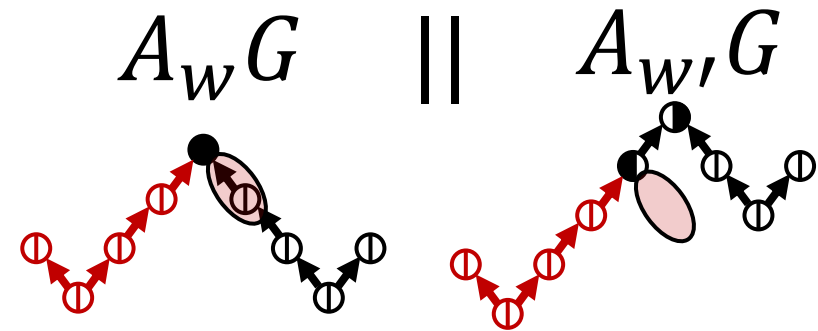
Using graph rewriting we **can simulate synchronous** dynamical system ...



... but also represent some **intrinsically asynchronous** evolution.



While preserving important physical properties such as **determinism**...



... and **reversibility**.

